

# sparsersb: Accessing **librsb**'s Shared Memory Parallel Sparse BLAS Implementation from **GNU/Octave**

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OctConf'13  
MOX @ Politecnico di Milano  
Milano, Italy, June 24–26, 2013



# Presentation outline

## Intro

- what ?

- why ?

- again: what ?

## Basic Features

- constructor

- correct usage

- further usage

## Performance

- setup

- results

- summary

## Advanced features

- introspection

- hand tuning

- auto tuning

## Outro

- summing up

- extra slides



# This presentation is about sparsersb

sparsersb is a command provided to GNU/Octave via an OCT-file, giving easy access to the librsb library

- ▶ defines the "rsb sparse matrix" type in the GNU/Octave language
- ▶ bits about the internals:
  - ▶ ≈2 KLoC of C++
  - ▶ class octave\_sparsersb\_mtx:

```
public octave_sparse_matrix
```
  - ▶ DEFUNOP (transpose, sparse\_rsb\_mtx)
  - ▶ DEFBINOP(op\_mul, sparse\_rsb\_mtx, matrix)
  - ▶ DEFBINOP(op\_trans\_mul, sparse\_rsb\_mtx, matrix)
  - ▶ DEFBINOP(...) # ... x 20
  - ▶ DEFUNOP(...) # ... x 6
  - ▶ DEFASSIGNOP(...) # ... x 4
  - ▶ ...
- ▶ GPLv3 licensed
- ▶ on Octave-Forge
- ▶ not aiming to replace sparse !

## sparsersb is based on librsb

librsb is a library implementing multithreaded algorithms for the "RSB" sparse matrix format

- ▶ written with *iterative methods* in mind
- ▶  $\approx 80$  KLoC of hand written C 99, GNU Octave, M4
- ▶ numerical kernels generated by M4
- ▶ correctness tests largely generated by Octave
- ▶ performant as/more than Intel MKL's CSR implementation
- ▶ GPLv3 licensed

# Motivations behind sparsersb

- ▶ experimenting/testing iterative methods
- ▶ testing librsb ideas
- ▶ contributing to GNU/Octave!

# Motivations behind librsb

- ▶ my PhD research
- ▶ high performance for single node, shared memory (OpenMP)
- ▶ for iterative methods
- ▶ standalone or component of distributed memory (e.g.: MPI) applications
- ▶ optimized for large matrices ( $\gg / >$  outermost cache size)

# Sparse Matrix Computations

- ▶ numerical matrices which are *large* and populated mostly by zeros
- ▶ ubiquitous in scientific/engineering computations (e.g.:PDE)
- ▶ the *performance* of sparse matrix codes computation on modern CPUs can be problematic (a fraction of peak)!
- ▶ there is no “*silver bullet*” for performance
- ▶ jargon: *performance*=*time efficiency*<sup>1</sup>

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<sup>1</sup>Which so far turns out to be energy efficiency as well.

# Which sparse matrix computations matter the most to us ?

The numerical solution of **linear systems** of the form  $Ax = b$  (with  $A$  a sparse matrix,  $x, y$  dense vectors) using **iterative methods** requires repeated (and thus, **fast**) computation of (variants of) *Sparse Matrix-Vector Multiplication* and *Sparse Matrix-Vector Triangular Solve*:

- ▶  $SpMV$ : “ $y \leftarrow \beta y + \alpha A x$ ”
- ▶  $SpMV-T$ : “ $y \leftarrow \beta y + \alpha A^T x$ ”
- ▶  $SymSpMV$ : “ $y \leftarrow \beta y + \alpha A^T x, A = A^T$ ”
- ▶  $SpSV$ : “ $x \leftarrow \alpha L^{-1} x$ ”
- ▶  $SpSV-T$ : “ $x \leftarrow \alpha L^{-T} x$ ”

# Shared memory parallel, cache based computers

high performance programming **cache based, shared memory parallel** computers requires:

- ▶ *locality of memory references* — for the memory hierarchy exposes:
  - ▶ limited bandwidth
  - ▶ significant memory access latency
- ▶ programming multiple cores for coarse-grained *workload partitioning*
  - ▶ high synchronization and cache-coherence costs

## The *Recursive Sparse Blocks* (RSB) matrix layout

- ▶ a *quad-tree* of sparse *leaf* submatrices
- ▶ outcome of recursive *partitioning* in *quadrants*
- ▶ submatrices are stored by either *row oriented Compressed Sparse Rows* (CSR) or *Coordinates* (COO)
- ▶ an *unified* format supporting many common operations and format variations (e.g.: diagonal implicit, one or zero based, transposition, complex types, ...)
- ▶ partitioning with regards to both the underlying cache size **and** available threads

## sparsersb: warmup

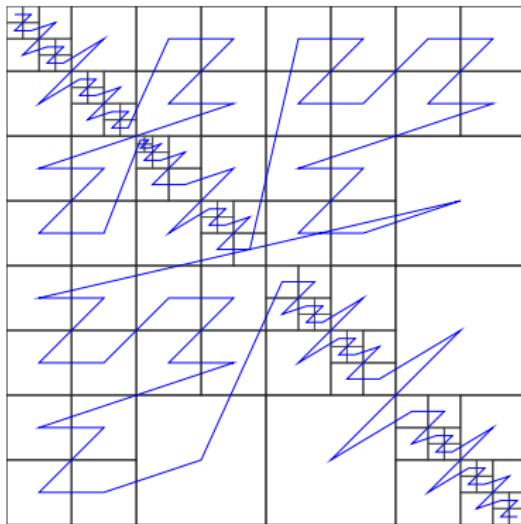
```
# Get matrix ASIC_320k from
# http://www.cise.ufl.edu/research/sparse/matrices/Sandia/ASIC_320k
#
octave:1> A=sparsersb("ASIC_320k.mtx.gz"); # load gzipped Matrix Market file
octave:2> typeinfo(A)
ans = rsb sparse matrix
octave:3> A
A =

Recursive Sparse Blocks  (rows = 321821, cols = 321821, nnz = 2635364 [0.0025%]

(1, 1) -> 0.019
(1, 12060) -> -1.5e-15
(1, 12061) -> -5.8e-16
(1, 23338) -> -0.0023
(1, 23339) -> -1e-18
(1, 23340) -> 0
(1, 81086) -> -0.016
(2, 2) -> 0.0074
...
...
```

Instance of *ASIC\_320k* matrix ( $3.2 \cdot 10^5$  rows,  $3.2 \cdot 10^5$  columns,  $2.6 \cdot 10^6$  nonzeros):

```
octave:4> sparsersb(A,"renderb","ASIC_320k.eps");
```



## Adaptivity to threads count

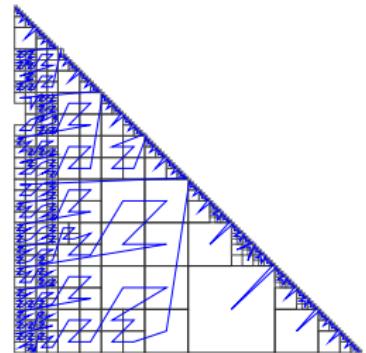
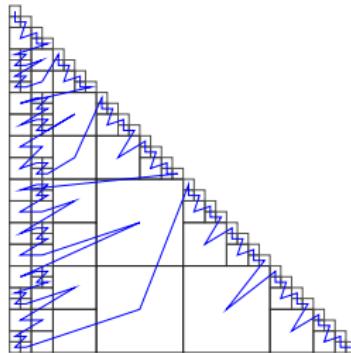
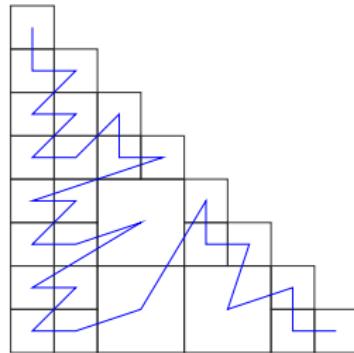


Figure: Matrix *audikw\_1* (symmetric, 943695 rows,  $3.9 \cdot 10^7$  nonzeros) for 1, 4 and 16 threads on a Sandy Bridge.

Matrix layout described in (Martone et al., 2010).

## Pros/Cons of our RSB implementation, w.r.t. performance

- ▶ + scalable parallel  $SpMV / SpMV-T$
- ▶ + partially parallel  $SpSV / SpSV-T$
- ▶ + many other common operations (e.g.: parallel matrix build algorithm)
- ▶ + native support for parallel symmetric multiply ( $SymSpMV$ )
- ▶ - a number of known cases (unbalanced matrices) where parallelism is poor
- ▶ - some algorithms easy to express/implement for CSR/CSC are more complex for RSB

## sparsersb: matrix assembly

```
IA=[1,1,3]; # row      coordinates of non zero matrix coefficients
JA=[1,1,3]; # column coordinates of non zero matrix coefficients
VA=[1,10,33]; # non zero matrix coefficients

# Octave sparse matrix creation syntax:
OM=sparse( IA,JA,VA,"summation"); # Octave's CSC
# Same for sparsersb:
RM=sparsersb( IA,JA,VA,"summation") # librsb's RSB

ans =
Recursive Sparse Blocks (rows = 3, cols = 3, nnz = 2 [22%])
(1, 1) -> 11
(3, 3) -> 33
```

## sparsersb: where to use it

sparsersb's performance lies in matrix-vector multiply:

```
alpha=1.0;
beta=-1.0;
X=[-1,-2,-3];
Y=[ 0, 0, 0];

# Octave matrix:
Y=alpha*OM*X+beta*Y;
# Same usage of the "*" operator:
Y=alpha*RM*X+beta*Y;
```

## no tertiary operators for in place *SpMV*

Octave does at most provide binary operators for *SpMV*.

```
Y=...:  
# The following:  
Y+=RM.*X; # matrix-vector multiply  
Y+=RM.'*X; # transposed matrix-vector multiply  
# work like:  
Y=Y+RM.*X; # matrix-vector multiply  
Y=Y+RM.'*X; # transposed matrix-vector multiply
```

The result of the multiplication goes first to a temporary location, only then it is added to Y.

## sparsersb matrix usage: some further operators

```
RM=sparsersb([1]) # conversion from dense
RM=sparsersb(OM)  # conversion from Octave sparse matrices
RM=transpose(RM) # built-in: transpose, normest, trace, ...
RM * RM           # matrix-matrix multiplication
RM \ X            # triangular solve
RM *= alpha       # scaling
RM = -RM          # negation
```

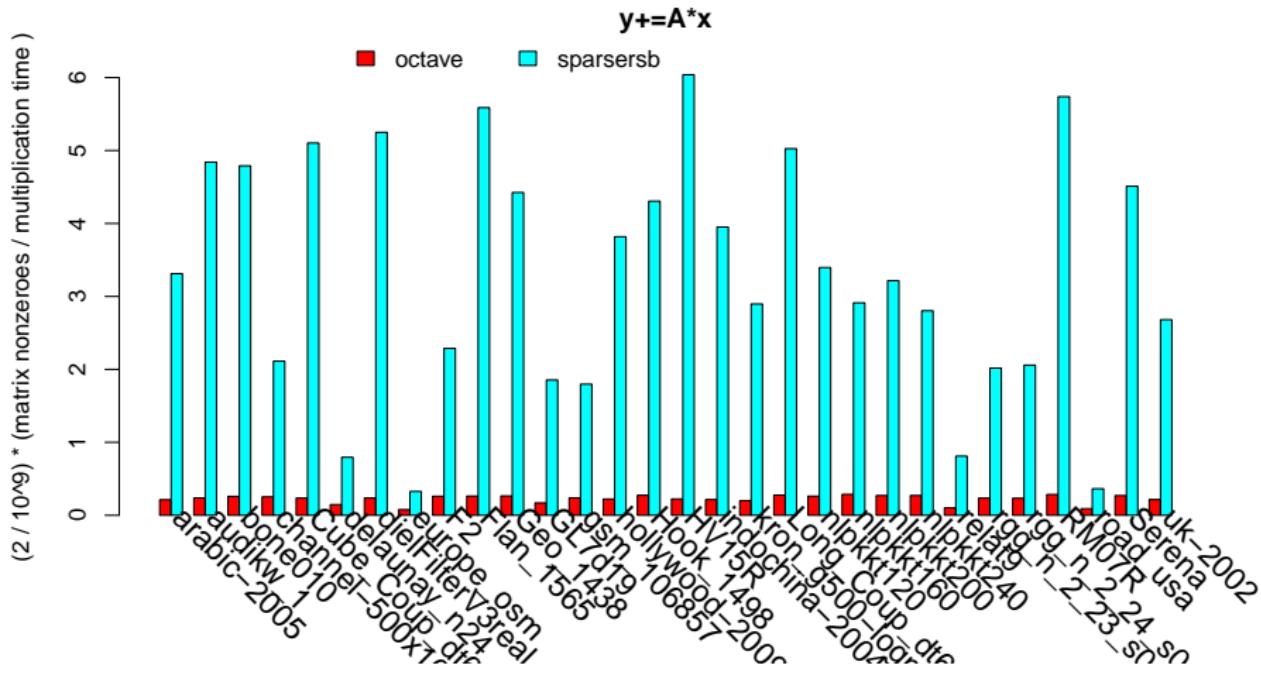
## Performance Comparison to Octave

- ▶ running `octavebench.m` on a  $2 \times 8$  core Intel Sandy Bridge "Romely-EP"
- ▶ Octave-3.6.4 with `CXXFLAGS=-O3 -pipe -march=native -mtune=native -mavx -pthread`
- ▶ `librsb/sparsersb` with `CFLAGS=-O3 -pipe -march=native -mtune=native -mavx -fPIC`
- ▶ compiled with GCC 4.7.2
- ▶ publicly available matrices from the Florida Sparse Matrix Collection

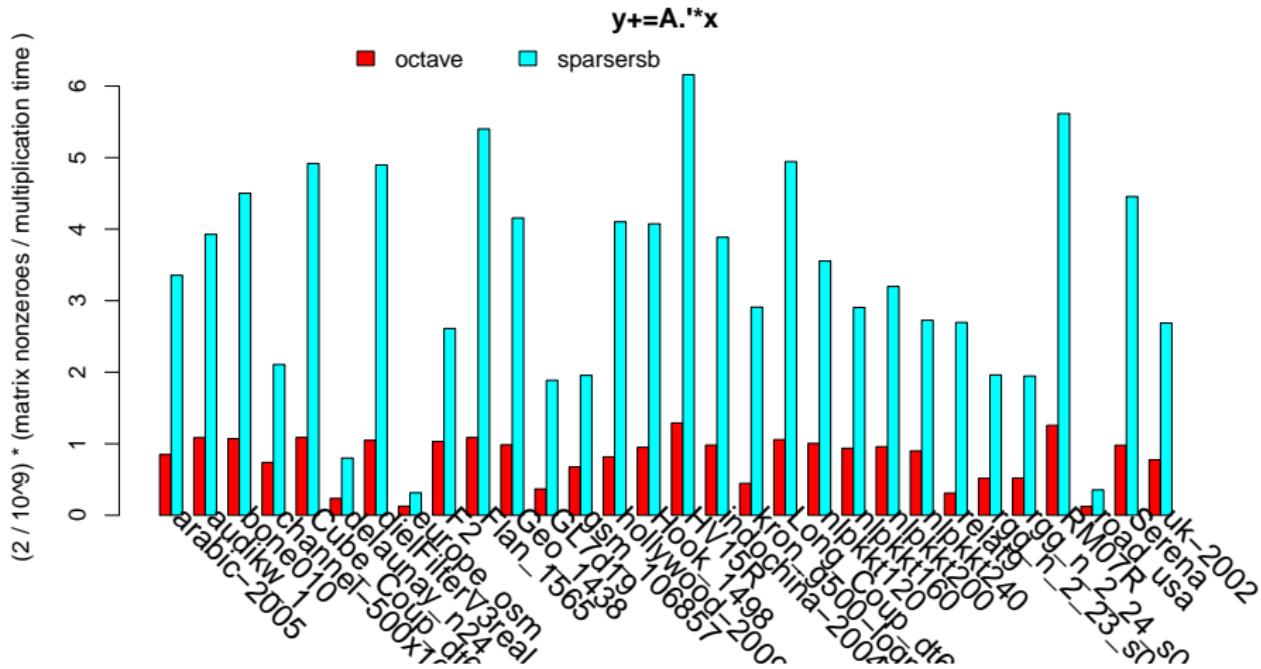
matrix	symm	nr	nc	nnz	nnz/nr
arabic-2005	G	22744080	22744080	639999458	28.14
audikw_1	S	943695	943695	39297771	41.64
bone010	S	986703	986703	36326514	36.82
channel-500x100x100-b050	S	4802000	4802000	42681372	8.89
Cube_Coup_dt6	S	2164760	2164760	64685452	29.88
delaunay_n24	S	16777216	16777216	50331601	3.00
dielFilterV3real	S	1102824	1102824	45204422	40.99
europe_osm	S	50912018	50912018	54054660	1.06
Flan_1565	S	1564794	1564794	59485419	38.01
Geo_1438	S	1437960	1437960	32297325	22.46
GL7d19	G	1911130	1955309	37322725	19.53
gsm_106857	S	589446	589446	11174185	18.96
hollywood-2009	S	1139905	1139905	57515616	50.46
Hook_1498	S	1498023	1498023	31207734	20.83
HV15R	G	2017169	2017169	283073458	140.33
indochina-2004	G	7414866	7414866	194109311	26.18
kron_g500-logn20	S	1048576	1048576	44620272	42.55
Long_Coup_dt6	S	1470152	1470152	44279572	30.12
nlpkkt120	S	3542400	3542400	50194096	14.17
nlpkkt160	S	8345600	8345600	118931856	14.25
nlpkkt200	S	16240000	16240000	232232816	14.30
nlpkkt240	S	27993600	27993600	401232976	14.33
relat9	G	12360060	549336	38955420	3.15
rgg_n_2_23_s0	S	8388608	8388608	63501393	7.57
rgg_n_2_24_s0	S	16777216	16777216	132557200	7.90
RM07R	G	381689	381689	37464962	98.16
road_usa	S	23947347	23947347	28854312	1.20
Serena	S	1391349	1391349	32961525	23.69
uk-2002	G	18520486	18520486	298113762	16.10

**Table:** Matrices used for our experiments. Symmetric are marked by S, general unsymmetric by G.

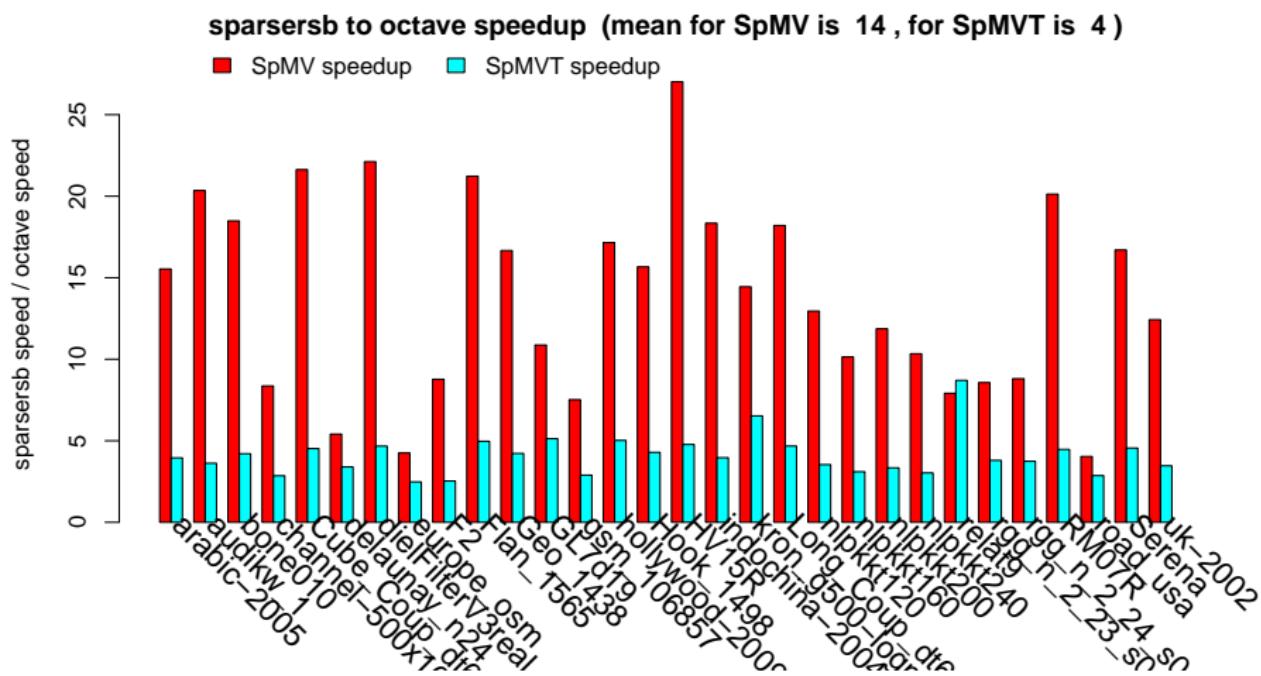
# *SpMV ("Y+=A\*B") speed*



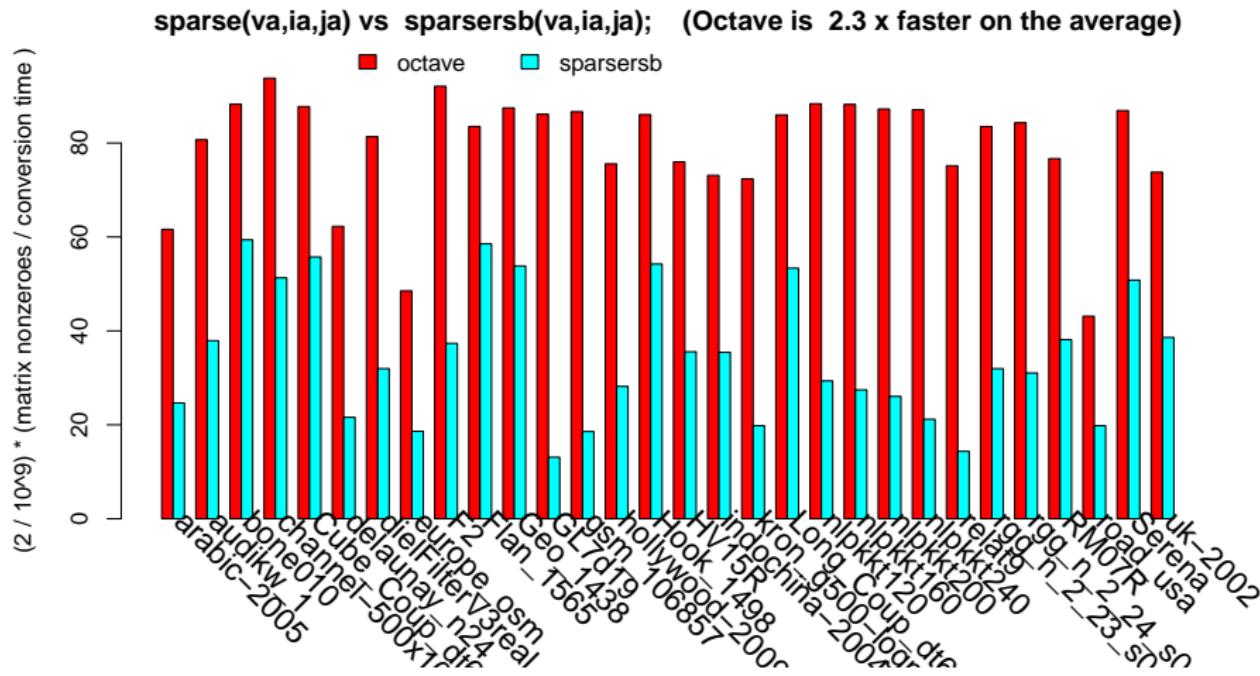
# *SpMV-T ("Y+=A.'\*B") speed*



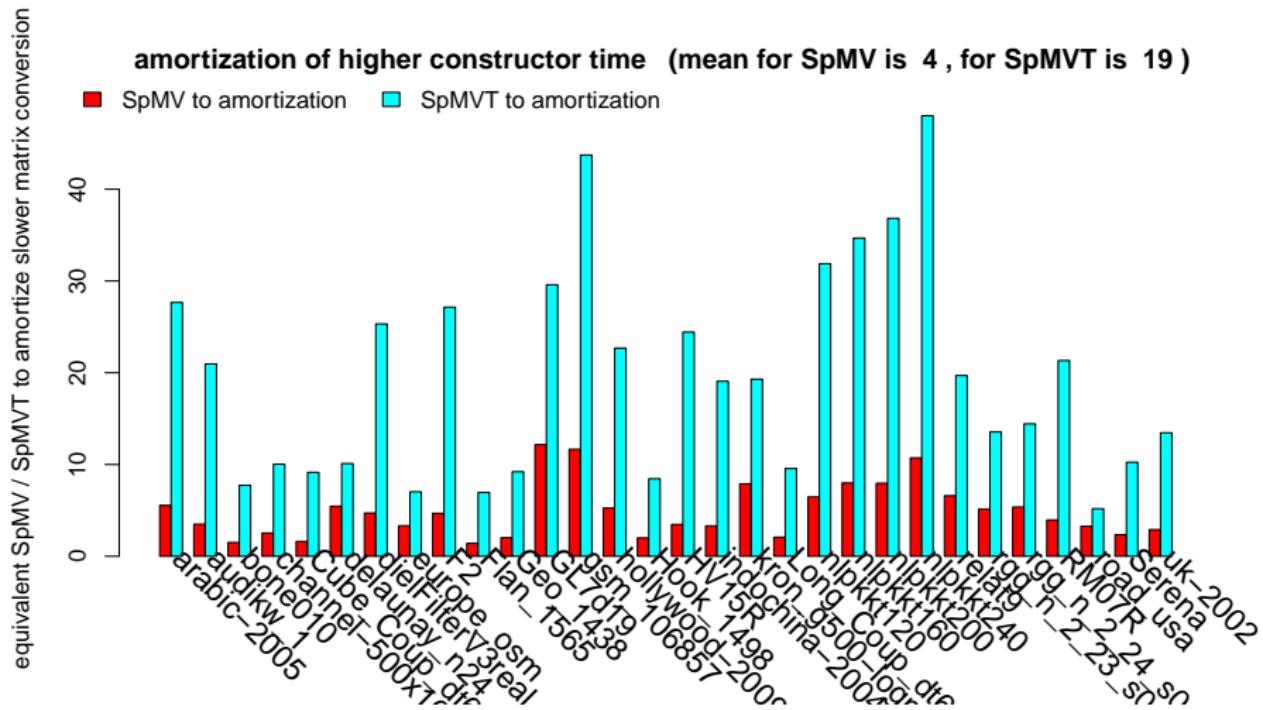
# sparsersb speedup to Octave



# Constructor ("sparsersb(ia,ja,va,nr,nj)") speed vs Octave's



## Amortization of constructor in equivalent *SpMV* / *SpMV-T*



## Performance observations

- ▶  $\approx 14\times$  faster than Octave's serial CSC in *SpMV*
- ▶  $\approx 4\times$  faster than Octave's serial CSC in *SpMV-T*
- ▶  $\approx 3\times$  slowdown w.r.t. Octave when assembling (from coordinate arrays)
- ▶ amortizes conversion overhead within a few dozen of multiplications

## Low level introspection

```
A=sparsersb(sprand(3,3,0.5))
# A =
# Recursive Sparse Blocks  (rows = 3, cols = 3, nnz = 5 [56%])
#
# (1, 2) -> 0.29
# (2, 2) -> 0.21
# (2, 3) -> 0.69
# (3, 1) -> 0.63
# (3, 2) -> 0.39
#
sparsersb(A,"get","RSB_MIF_MATRIX_INFO__TO__CHAR_P")
# ans = (3 x 3)[0x8586790] @ (0(0..0),0(0..0)) (5 nnz, 1.7 nnz/r)
# flags 0x2046186 (coo:1, csr:1), hw:1, storage: 40, subm: 3, symflags:
sparsersb(A,"get","RSB_MIF_LEAVE_COUNT__TO__RSB_BLK_INDEX_T")
# ans = 3
sparsersb(A,"get","RSB_MIF_INDEX_STORAGE_IN_BYTES_PER_NNZ__TO__RSB_REAL")
# ans = 4.8
sparsersb(A,"get","RSB_MIF_TOTAL_SIZE__TO__SIZE_T")
# ans = 928
```

# Setting librsb Options

Concept similar to that of Octave's spparms's.

```
sparsersb("set","RSB_IO_WANT_EXECUTING_THREADS","-1") # default
sparsersb("set","RSB_IO_WANT_EXECUTING_THREADS","1") # default m
sparsersb("set","RSB_IO_WANT_EXECUTING_THREADS","2")
sparsersb("set","RSB_IO_WANT_VERBOSE_ERRORS","7")
sparsersb("set","RSB_IO_WANT_MEMORY_HIERARCHY_INFO_STRING","")

# "get" will be available in version 1.1:
errlevel=sparsersb("get","RSB_IO_WANT_VERBOSE_ERRORS")
nthreads=sparsersb("get","RSB_IO_WANT_EXECUTING_THREADS")
```

# Hand tuning the Subdivision Policy

```
A=sparsersb(ones(3000));
sparsersb(A,"get","RSB_MIF_LEAVE_COUNT__TO__RSB_BLK_INDEX_T")
# ans= 82

# A_20 will have less subdivisions
sparsersb("set","RSB_IO_WANT_SUBDIVISION_MULTIPLIER","2.0")
A_20=sparsersb(sparse(A));
sparsersb(A_20,"get","RSB_MIF_LEAVE_COUNT__TO__RSB_BLK_INDEX_T")
# ans= 1024

# A_05 will have more subdivisions
sparsersb("set","RSB_IO_WANT_SUBDIVISION_MULTIPLIER","0.5")
A_05=sparsersb(sparse(A));
sparsersb(A_05,"get","RSB_MIF_LEAVE_COUNT__TO__RSB_BLK_INDEX_T")
# ans= 256
```

These structures may expose different performance in usage.

# Cache blocking policy

The exact RSB structure for a matrix depends on two parameters:

- ▶ thread count
- ▶ cache block size

These determine:

- ▶ parallelism
- ▶ memory bandwidth

# Cache blocking trade-offs

Parallelism vs memory bandwidth:

- ▶ the finer the subdivision, the less contention among threads
- ▶ memory bandwidth the coarser the subdivision, less memory can be used to represent the matrix

# Autotuning

Finds *best* performing matrix and threads count

- ▶ with respect to the specific *SpMV* variant:  
`sparsersb(A, "autotune", TRANSA, NRHS)`
- ▶ with respect to other parameters:  
`sparsersb(A, "autotune", TRANSA, NRHS, ITMAX, TMAX, TN, SF)`
- ▶ with defaults: `sparsersb(A, "autotune")`

## Autotuning results

- ▶ Found to squeeze additional 10...60% performance
- ▶ ( ...at a cost of some thousands of *SpMV* ... )

## sparsersb+librsb: In a nutshell

- ▶ bridge to librsb functionality for GNU/Octave
- ▶ on large matrices, librsb found to be faster than Intel's highly optimized, proprietary CSR implementation (see PMAA'12 results)
- ▶ portable, tunable code
- ▶ LGPLv3 licensed

# Open questions and missing features

mainly

- ▶ non-standard operators e.g.: for row scaling:  $A .+=v$
- ▶ missing operators
  - ▶ permutations; e.g.:  $PA=A(IREN,JREN)$ ;
  - ▶ linear access; e.g.:  $A(1:nnz(A))$
- ▶ multi-operation benchmark/test suite (e.g.: shared with Octave)
- ▶ operators with more operands (e.g.:  $Y=\text{alpha}*OM*X+\text{beta}*Y$ )
- ▶ avoid *bitrot*

## Future work

- ▶ stabilize usage interface and release
- ▶ implement missing operators
- ▶ make sure it works well with Octave's iterative solvers implemented in m-files (`gmres.m`, `pcg.m`, ...)
- ▶ compatibility with preconditioner functions (e.g.: ITSOL's, soon to come in Octave)
- ▶ operations for preconditioners; e.g.:  $SpSV$ ,  $SpSV-T$

## References

- ▶ Code and papers:  
<http://sourceforge.net/projects/librsb>
- ▶ <http://svn.code.sf.net/p/octave/code/trunk/octave-forge/main/sparsersb/src/sparsersb.cc>
- ▶ *Sparse Matrix Implementation in Octave*, 2006, by D. Bateman, A. Adler:  
<http://arxiv.org/abs/cs.MS/0604006>

# Questions / discussion welcome!

Thanks for your attention.

Please consider testing sparsersb/librsb!

Spotting bugs/inefficiencies is essential for free software!

## Extra: Autotuning functionality sample output (1/2)

```
Starting autotuning (10 x 3.000000 s stages, transa=T), -1 suggested starting threads.
* 1 threads: 1.106897 s.
  2 threads: 0.584075 s.
  3 threads: 0.397878 s.
Best threads choice is 3 (starting threads were 1).
Starting autotuner stage, with subdivision of 1.000000 (current threads=1, max threads = 1).
* 1 threads: 1.269518 s.
  2 threads: 0.605315 s.
  3 threads: 0.423535 s.
  4 threads: 0.327688 s.
  5 threads: 0.277200 s.
Best threads choice is 5 (starting threads were 3).
...
```

## Extra: Autotuning functionality sample output (2/2)

```
...
Best threads choice is 12 (starting threads were 10).
For subdivision 4.000000 (2427 leaves, 2.6 bytes/nz, 12 threads), challenging 0.179623 s with 0.163669 s
Best performance obtained through subdivision multiplier of 4.000000 and 12 threads.
Gained a total speedup of 2.430991
In 1/10 tuner iterations, gained a total speedup of 2.430991
  10 threads: 0.172950 s.
  11 threads: 0.174151 s.
  12 threads: 0.166623 s.
...
Best threads choice is 12 (starting threads were 14).
For subdivision 16.000000 (9088 leaves, 2.6 bytes/nz, 12 threads), challenging 0.147328 s with 0.191135 s
Best performance obtained through subdivision multiplier of 4.000000 and 12 threads.
Gained a total speedup of 1.000000
In 7/10 tuner iterations, gained a total speedup of 2.719551
Auto tuning step 7 did not find a better configuration.
Skipping further auto tuning.
Estimated autotuner speedup: 2.719551 x
Setting autotuner-suggested thread count of 12 (will skip further thread number configurations!)
```

## sparsersb.oct build

- ▶ Have a recent Octave installation; e.g.: version 3.6.3 <sup>2</sup>
- ▶ Checkout from Octave-Forge<sup>3</sup>
- ▶ Should compile librsb with -fPIC (any compiler)
- ▶ Should compile Octave with gfortran
- ▶ Build example: `./configure  
LIBRSB_CONFIG=/usr/local/bin/librsb-config; make;  
make tests;`

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<sup>2</sup><http://ftp.gnu.org/gnu/octave/octave-3.6.3.tar.bz2>

<sup>3</sup><svn://svn.code.sf.net/p/octave/code/trunk/octave-forge/main/sparsersb>