

GPU TECHNOLOGY
CONFERENCE

NVPRO-PIPELINE

A RESEARCH RENDERING PIPELINE

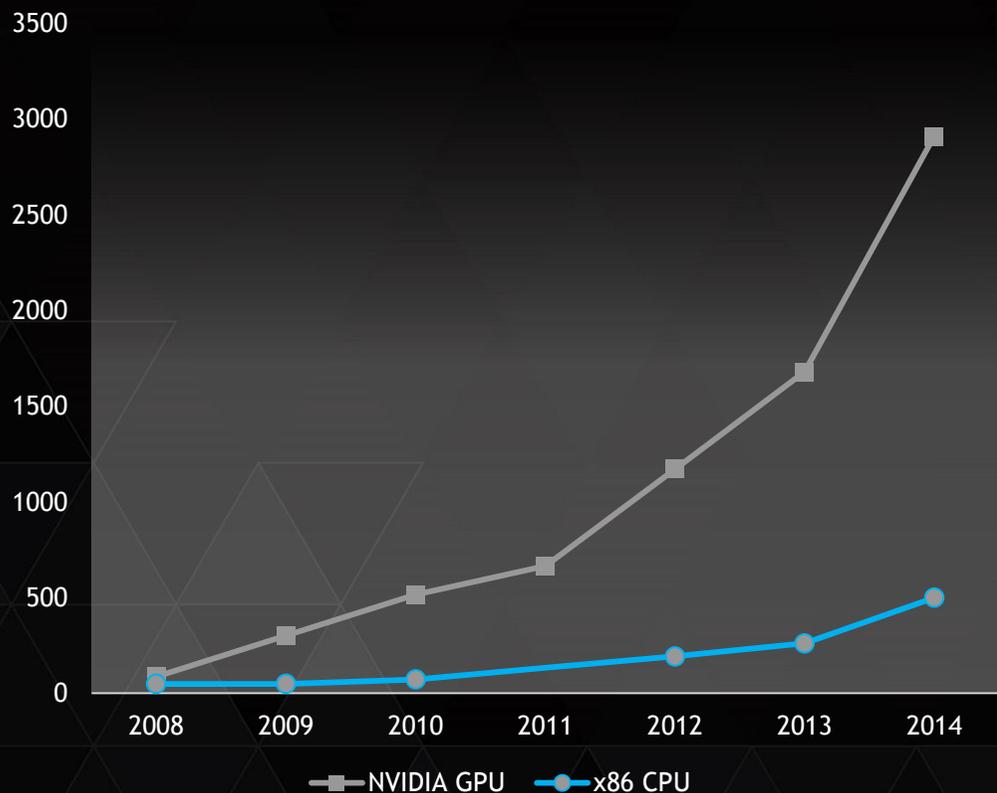
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NVPRO-PIPELINE

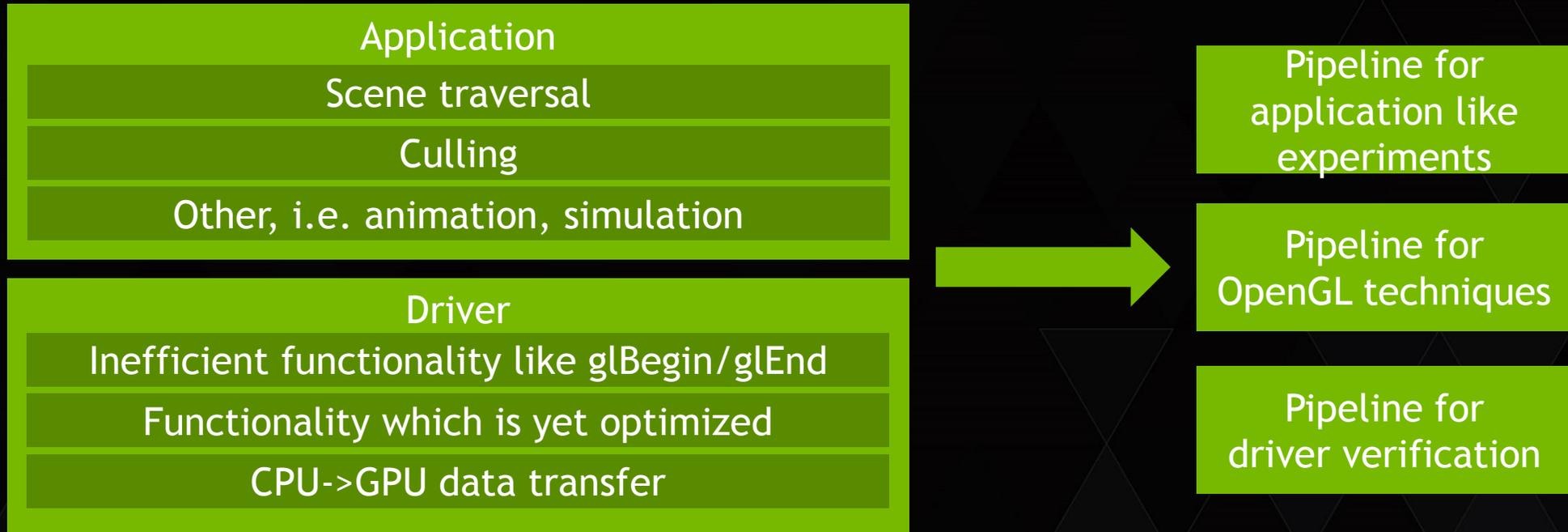
Peak Double Precision FLOPS

GFLOPS



- ▶ GPU perf improved better than CPU perf
- ▶ In the past apps were GPU bound
- ▶ Today apps tend to become CPU bound
- ▶ nvpro-pipeline started as research platform to address this issue
- ▶ <http://github.com/nvpro-pipeline>

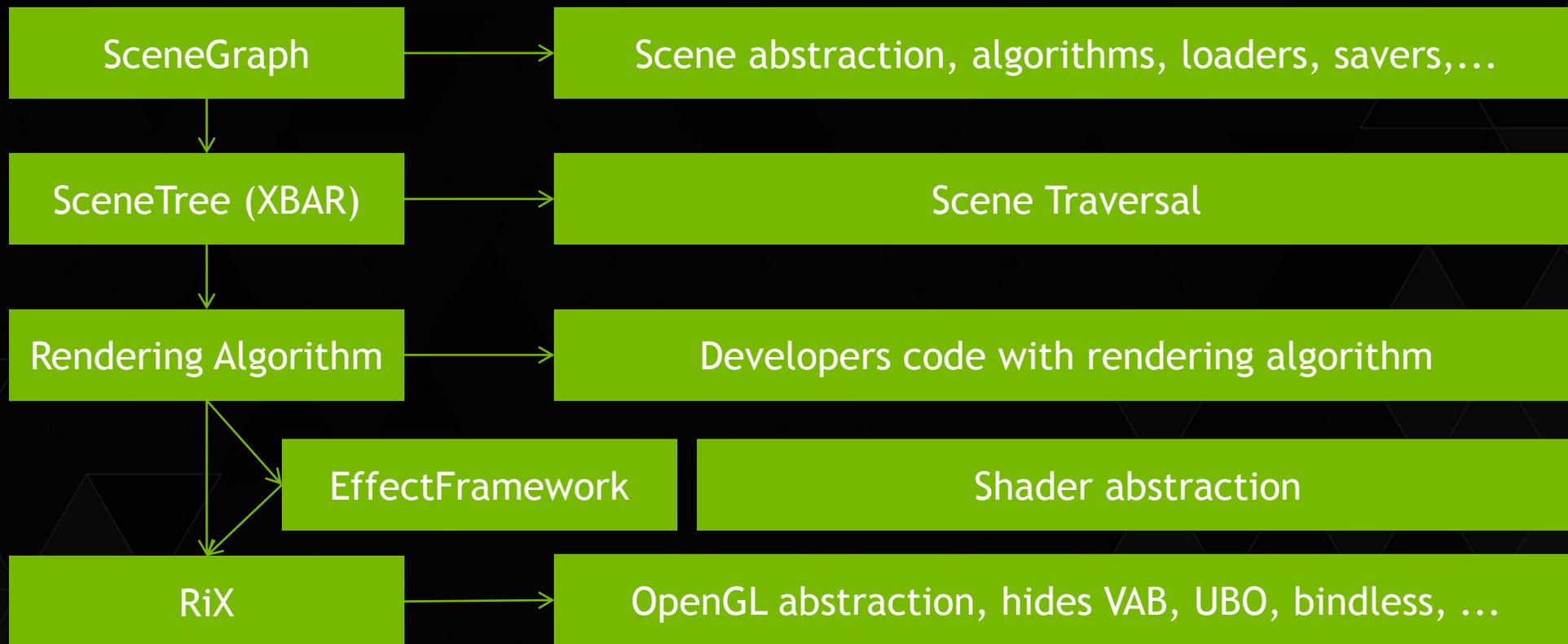
CPU BOUNDEDNESS REASONS



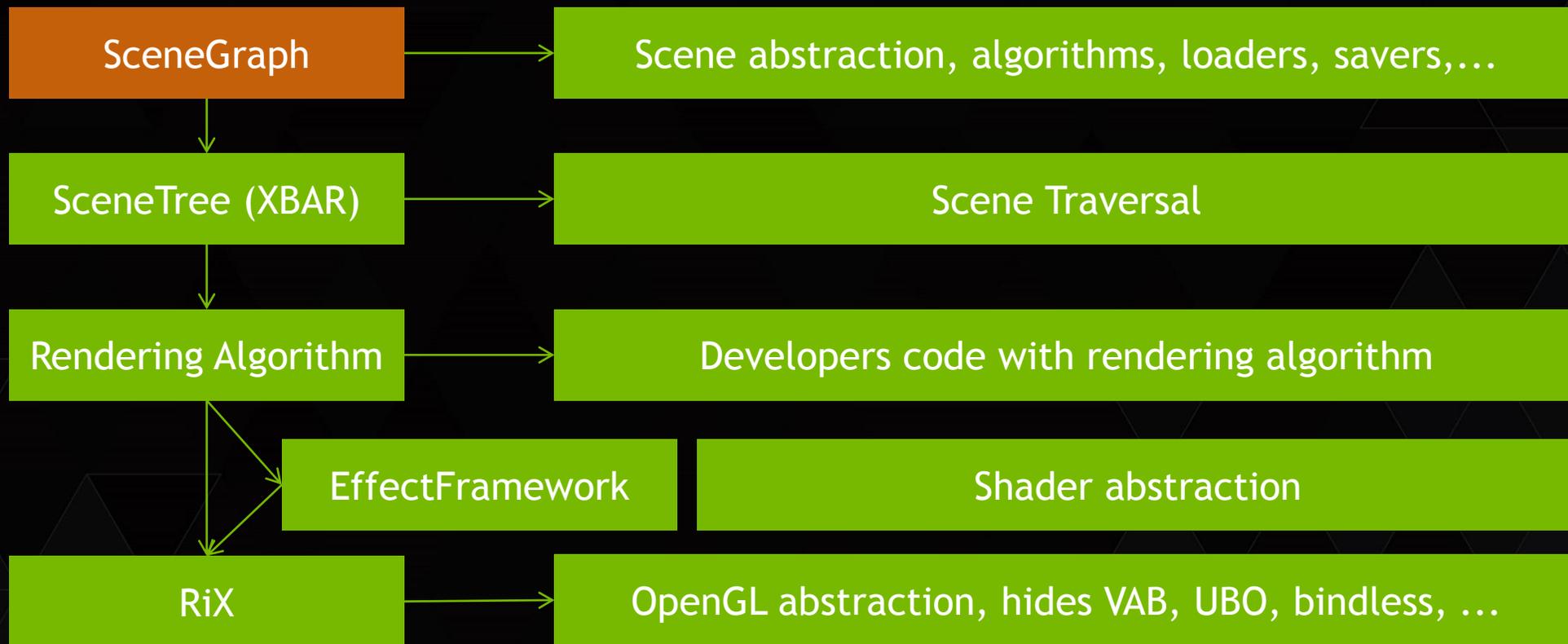
NVPRO-PIPELINE MODULES

SceneGraph [dp::sg]	RiX (Renderer) [dp::rix]	Effect System [dp::fx]	Utilities [dp::util]
Algorithms	GL Backend [dp::rix::gl]	XML Based for GLSL [dp::fx::xml]	Math library [dp::math]
SceneTree (XBAR)	Vulkan backend planned		Culling [dp::culling]
Loaders/Savers			Windowing [dp::ui]
Renderer for RiX::GL			Manipulators [dp::ui::manipulator]

RENDERING PIPELINE

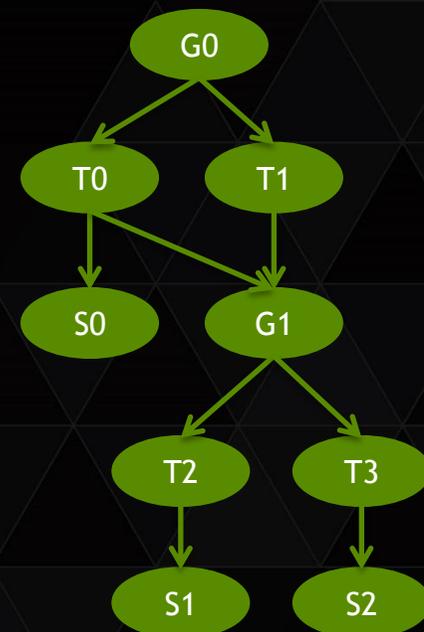


RENDERING PIPELINE



SCENEGRAPH

- ▶ Simplified version of SceniX SceneGraph
 - ▶ GeoNodes, Groups, Transforms, Billboards, Switches still available
 - ▶ Animated* objects have been removed to make development easier
 - ▶ New property based animation system prepared, but not yet active (LinkManager)



SCENEGRAPH TRAVERSAL COST

▶ Memory cost

- ▶ Objects scattered in RAM
 - ▶ Latency when accessing an object
- ▶ Objects are big
 - ▶ Traversing one object might touch multiple cache-lines

▶ Instruction calling cost

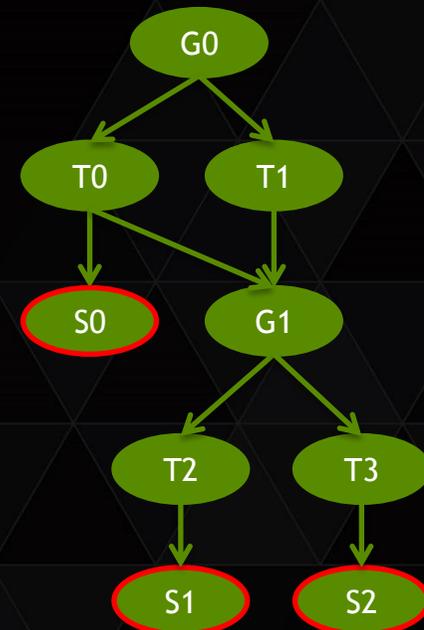
```
▶ void processNode(Node *node) { // function call
    switch (node->getType()) { // branch misprediction
        case Group:
            handleGroup((Group*) node); // virtual function call
            break;
        case Transform:
            handleTransform((Transform*) node);
            break;
        case GeoNode:
            handleGeoNode((GeoNode*) node);
            break;
    }
}
```

▶ Transformation Cost

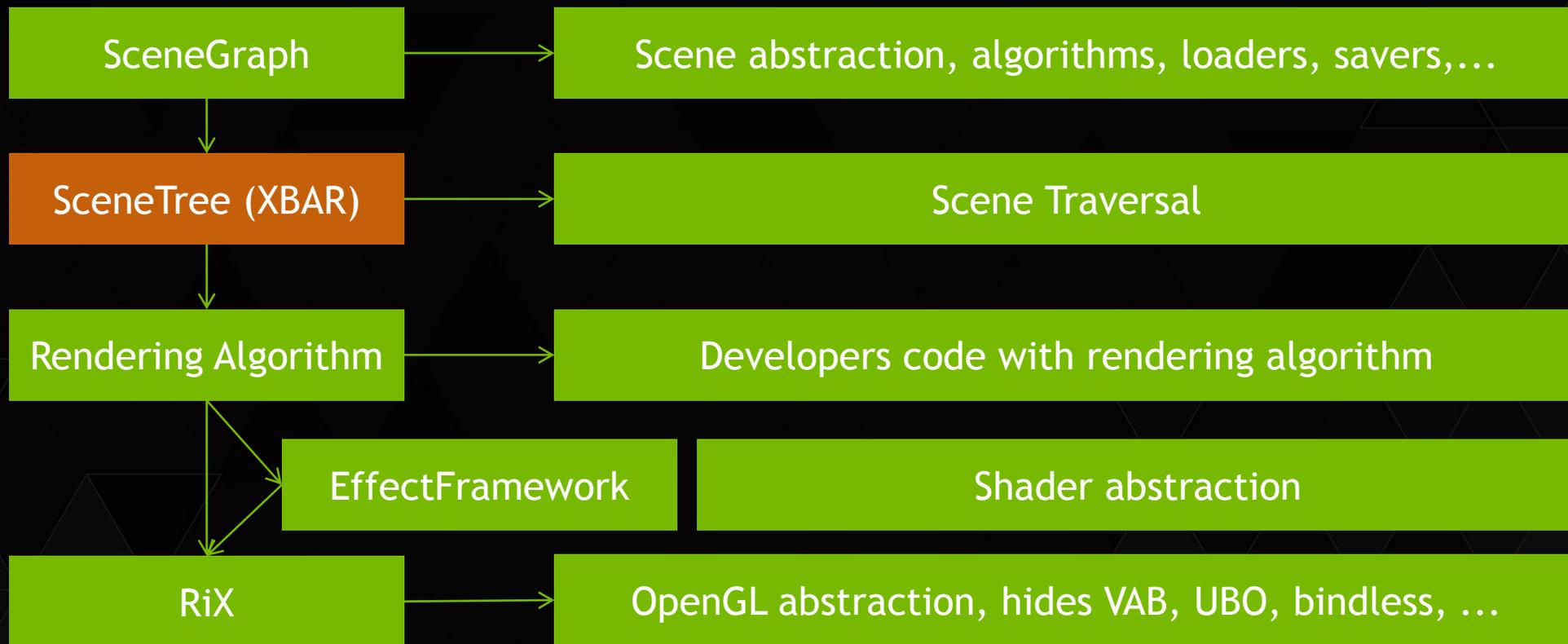
- ▶ Compute accumulated transformations during traversal

▶ Hierarchy Cost

- ▶ Deep hierarchy adds 'needless' traversal cost (5/14 nodes in example of interest)

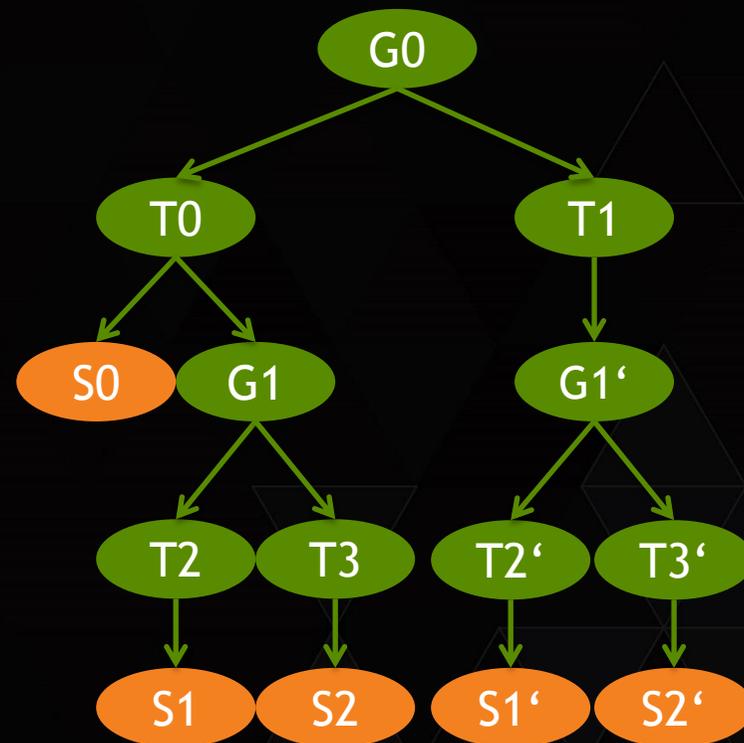


RENDERING PIPELINE



SCENETREE REQUIREMENTS

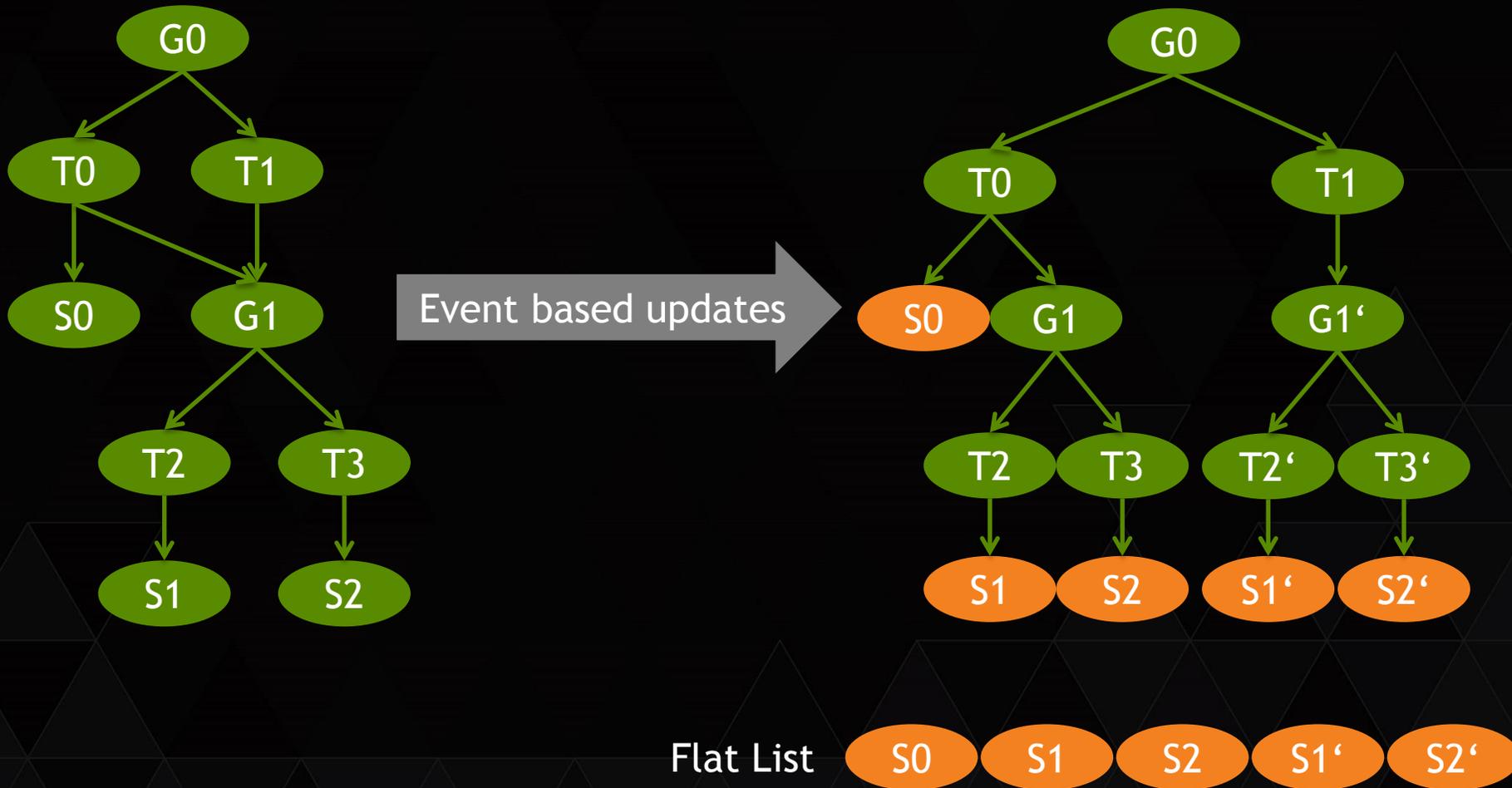
- ▶ Generate on the fly from SceneGraph
- ▶ Incremental updates
 - ▶ Minimal amount of work on changes
- ▶ Caching mechanism per path
 - ▶ No recomputation of ,unchanged‘ values
- ▶ Flat list of GeoNodes
 - ▶ Get rid of traversal
- ▶ Memory efficient
 - ▶ Don't copy data, keep references



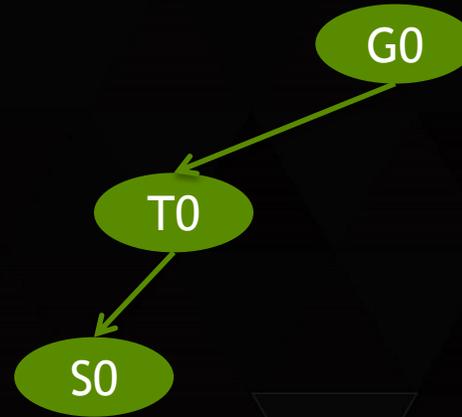
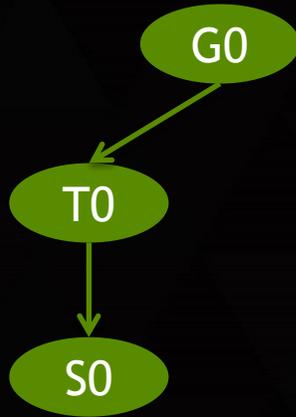
Flat List



SCENETREE CONSTRUCTION



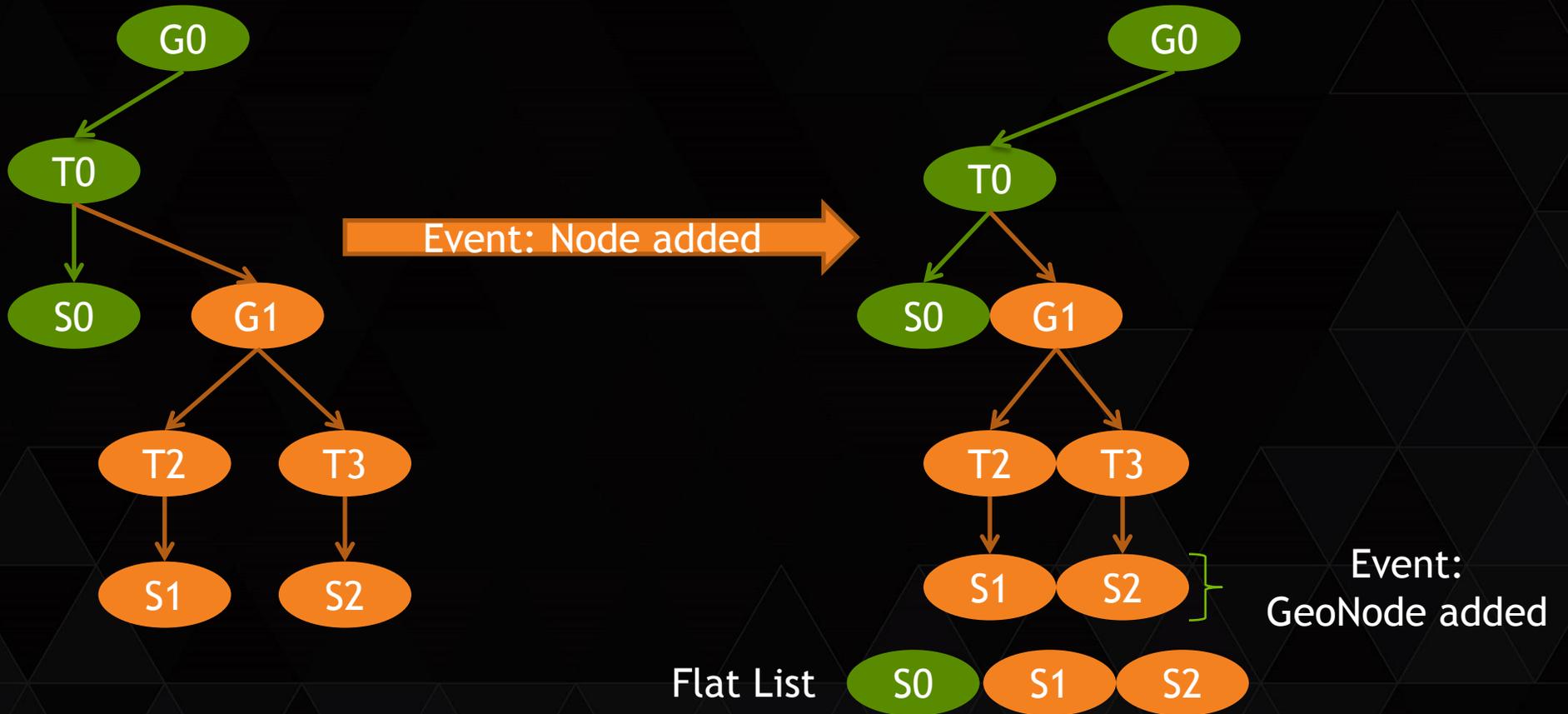
SCENETREE CONSTRUCTION



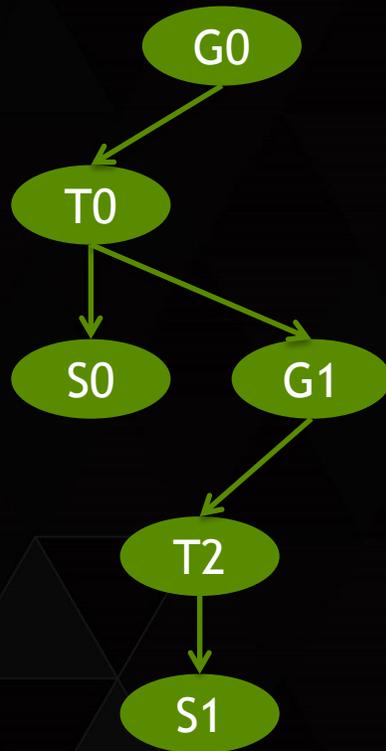
Flat List

S0

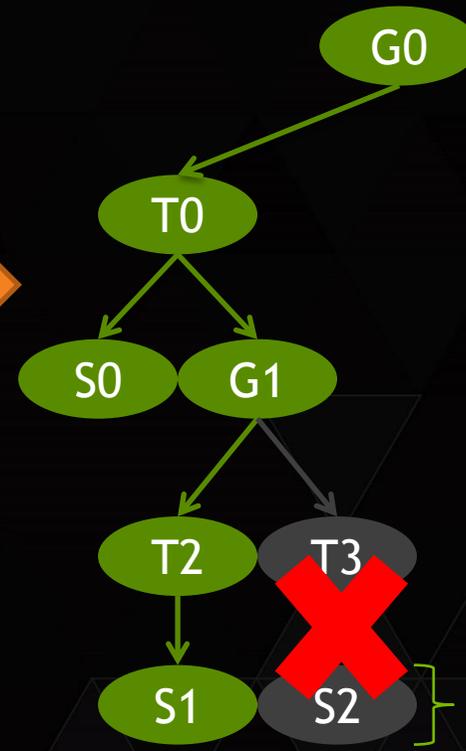
SCENETREE CONSTRUCTION



SCENETREE CONSTRUCTION



Event: Node Removed

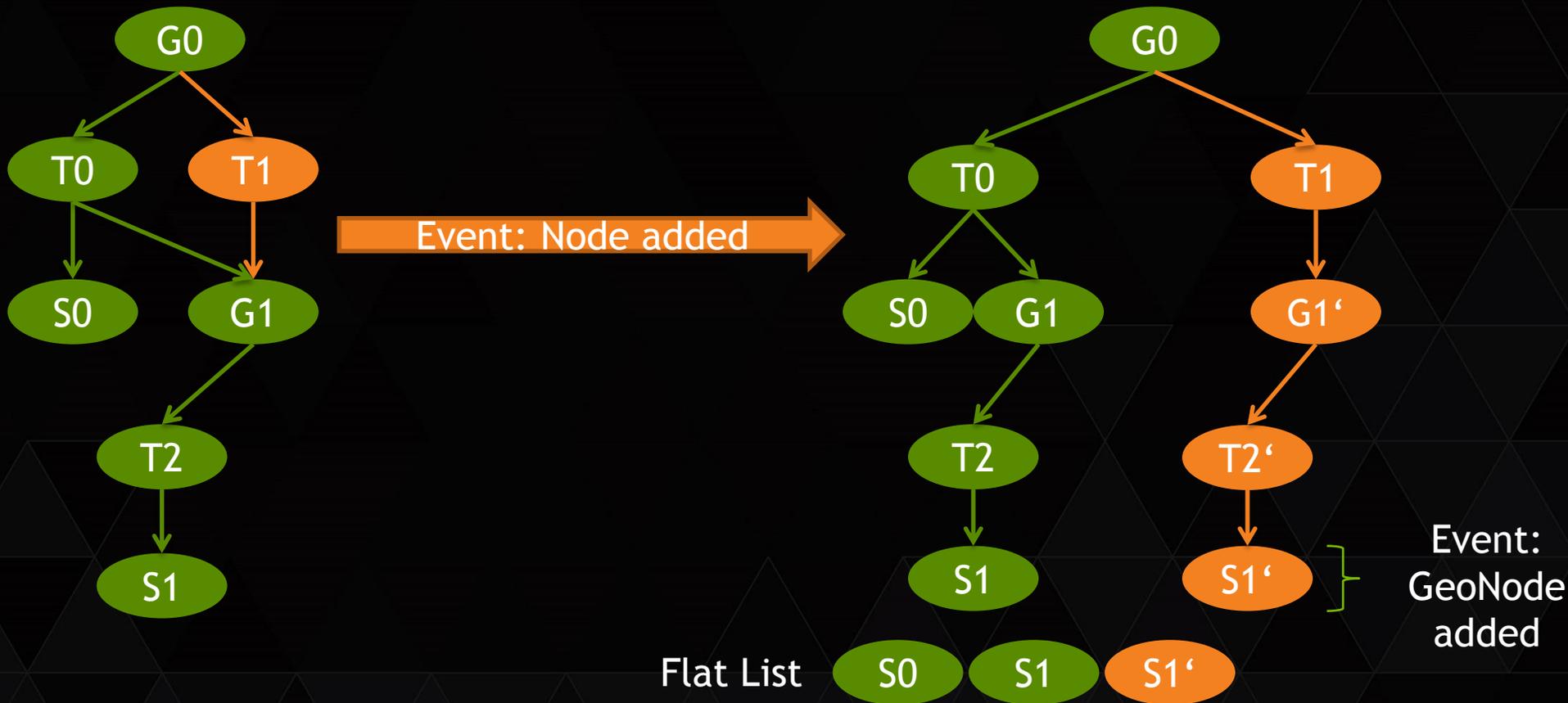


Flat List

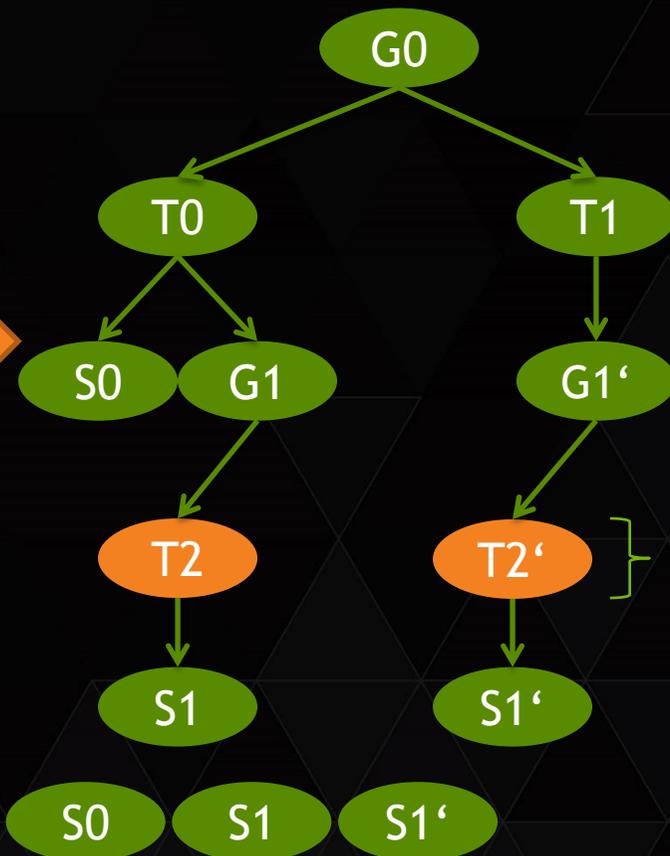
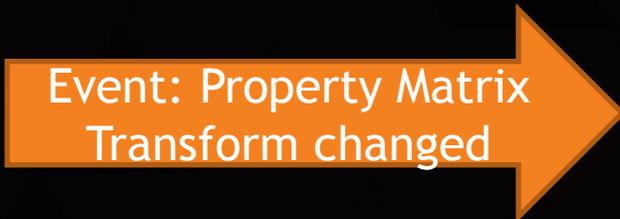
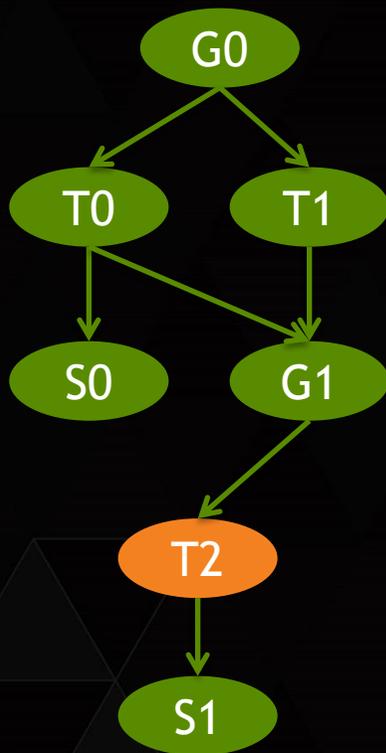


Event: GeoNode Removed

SCENETREE CONSTRUCTION



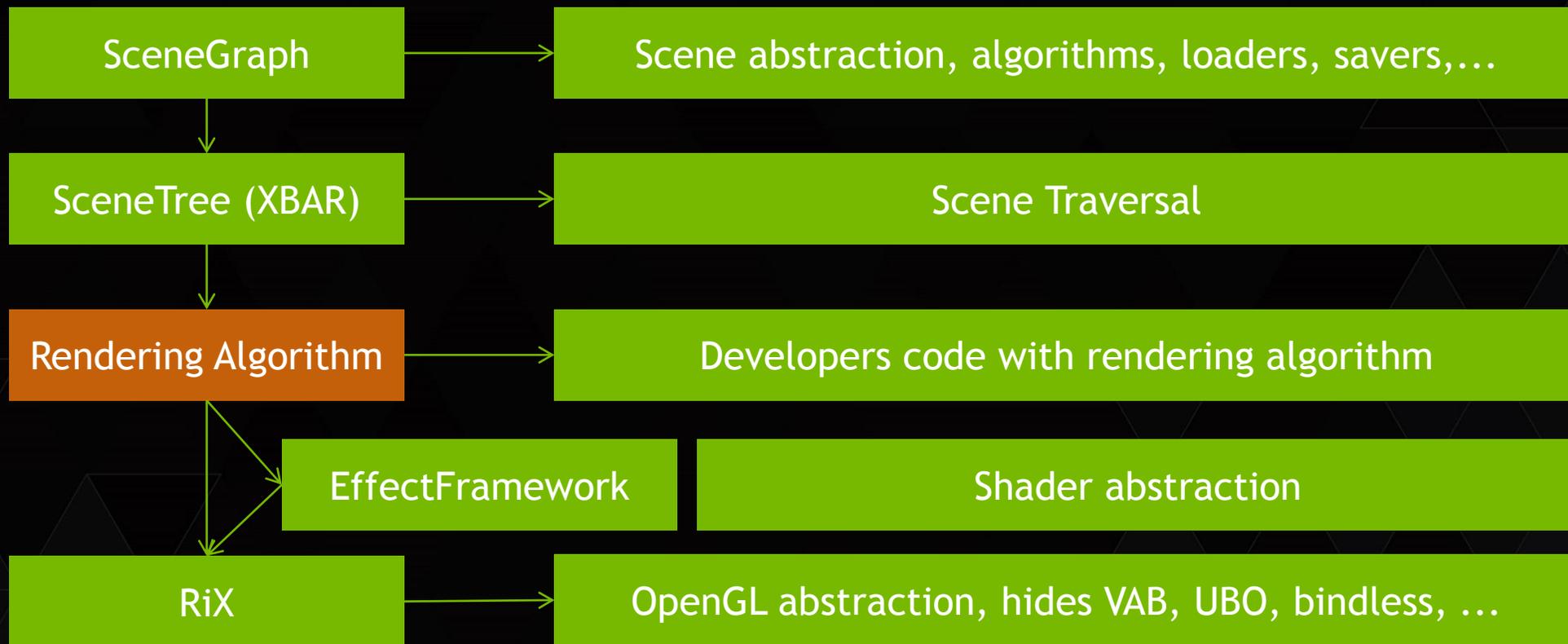
SCENETREE CONSTRUCTION



Event:
Transform
Changed
(2x)



RENDERING PIPELINE



SCENERENDERER

- ▶ Observe SceneTree to track GeoNodes in arrays
- ▶ `dp::sg::renderer::rix::gl` is ,example' renderer

Render Scene

Update resources

Compute near/far plane

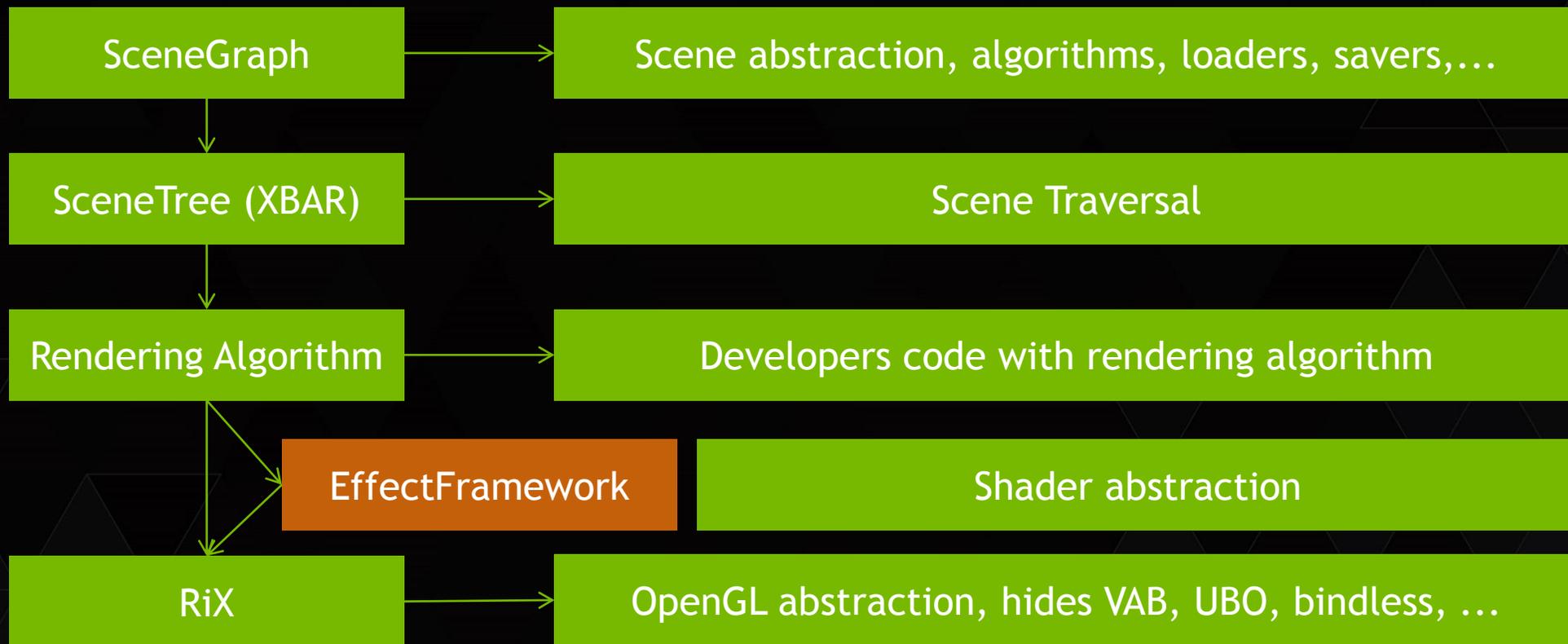
Frustum culling

Depth pass

Opaque pass

Transparent pass

RENDERING PIPELINE



ANATOMY OF A SHADER

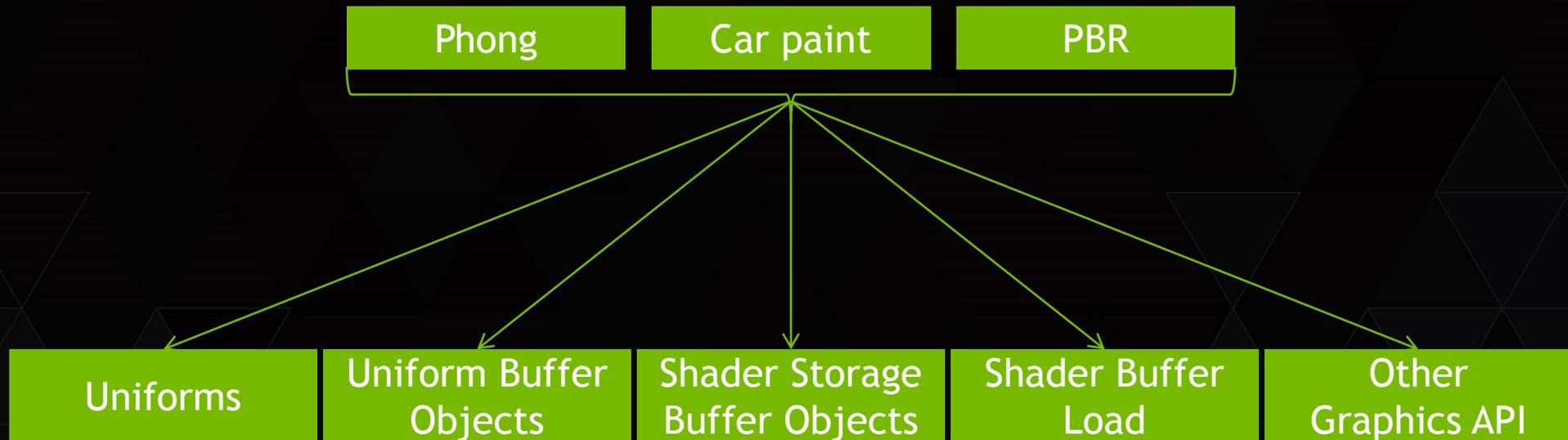
Shader Part	Source Code Example	Pipeline Module
Version Header	<pre>// version header & extensions #version 330 #extension GL_NV_shader_buffer_load : enable</pre>	Renderer
Uniforms	<pre>// Uniforms uniform struct Parameters{ float parameter; };</pre>	Material description
Attributes	<pre>// vertex attributes (vertex shader) layout(location = 0) in vec4 attrPosition;</pre>	(Material description)
Shader Stage variables	<pre>in/out vec3 varPosition;</pre>	Hardcoded or generated
Library functions	<pre>Bsdf*(params); determineMaterialColor(); determineNormal();</pre>	User provided to generator
User Implementation	<pre>void main() { // some code }</pre>	Material description or rendering system

PARAMETER GROUPING

	ParameterGroupSpecs	Binding Frequency
EffectSpec	Shader independent globals, i.e. camera	constant
	Shader dependent globals, i.e. environment map	
	Light, i.e. light sources and shadow maps	rare
	Material parameters without objects, i.e. float, int and bool	frequent
	Material parameters with objects, i.e. textures and buffers	
	Object parameters, i.e. position/rotation/scaling	always

EFFECT FRAMEWORK GOALS

- ▶ Unique shader interface with support of multiple rendering APIs
- ▶ Code generation for different kind of parameter techniques, i.e.



PARAMETER SHADER CODE GENERATION

ParameterGroup phong_fs

vec3	ambient
vec3	diffuse
vec3	specular
float	specularExp

Uniforms

```
uniform vec3 ambient;  
uniform vec3 diffuse;  
uniform vec3 specular;  
uniform float specularExp;
```

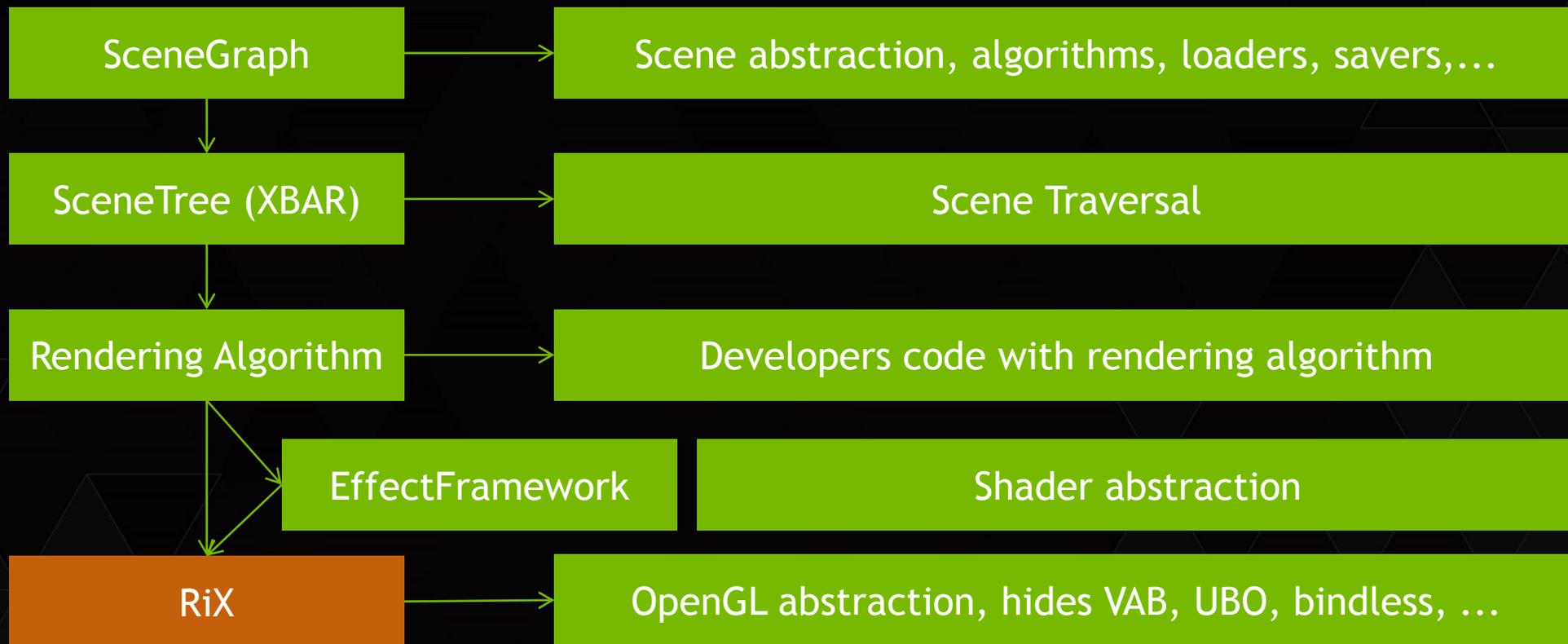
UBO

```
layout(std140)  
uniform ubo_phong_fs {  
    uniform vec3 ambient;  
    uniform vec3 diffuse;  
    uniform vec3 specular;  
    uniform float specularExp;  
}
```

shaderbufferload

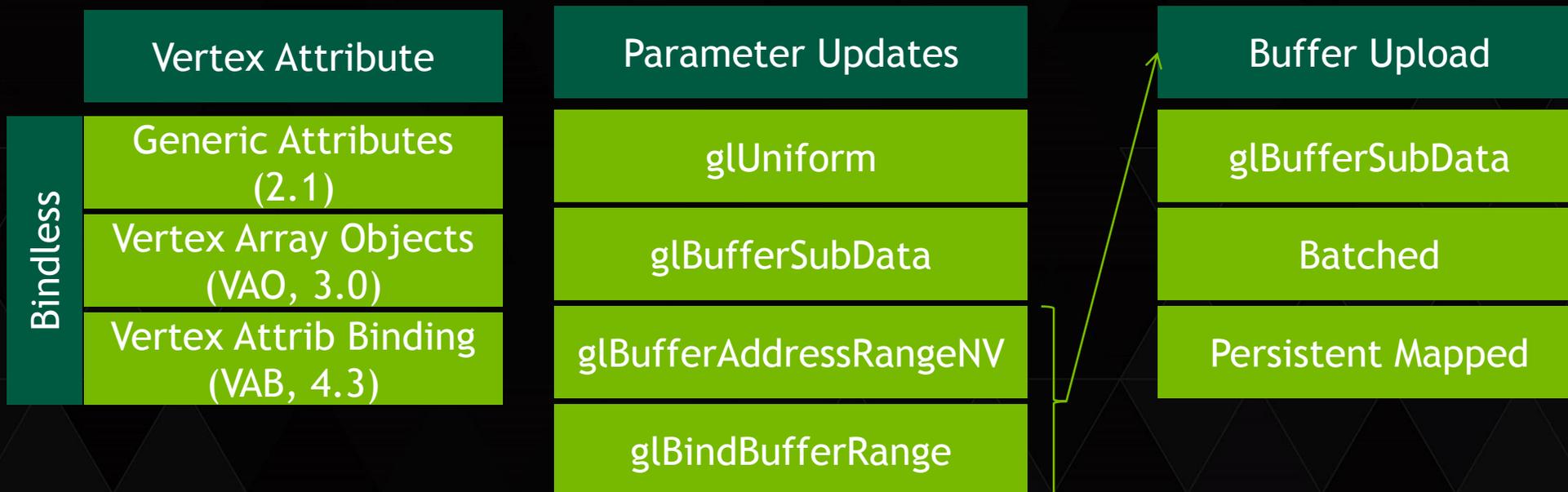
```
struct sbl_phong_fs {  
    uniform vec3 ambient;  
    uniform vec3 diffuse;  
    uniform vec3 specular;  
    uniform float specularExp;  
}  
  
uniform sbl_phong_fs *sys_phong_fs;  
  
#define ambient      sys_phong_fs->ambient  
#define diffuse      sys_phong_fs->diffuse  
#define specular     sys_phong_fs->specular  
#define specularExp  sys_phong_fs->specularExp
```

RENDERING PIPELINE

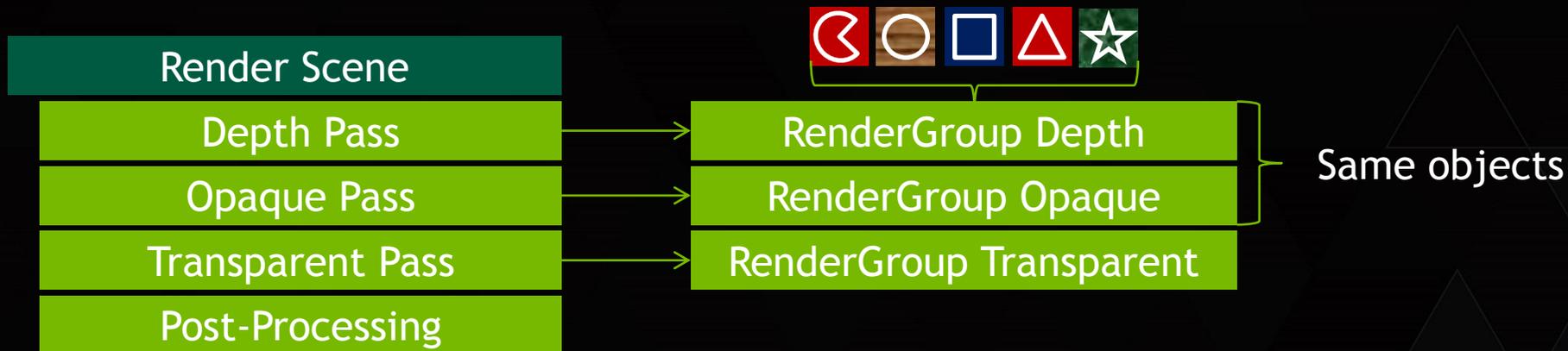


RIX

- ▶ Rendering API abstraction with OpenGL backend in place
- ▶ Hide implementation details which generate all kind of (OpenGL) streams

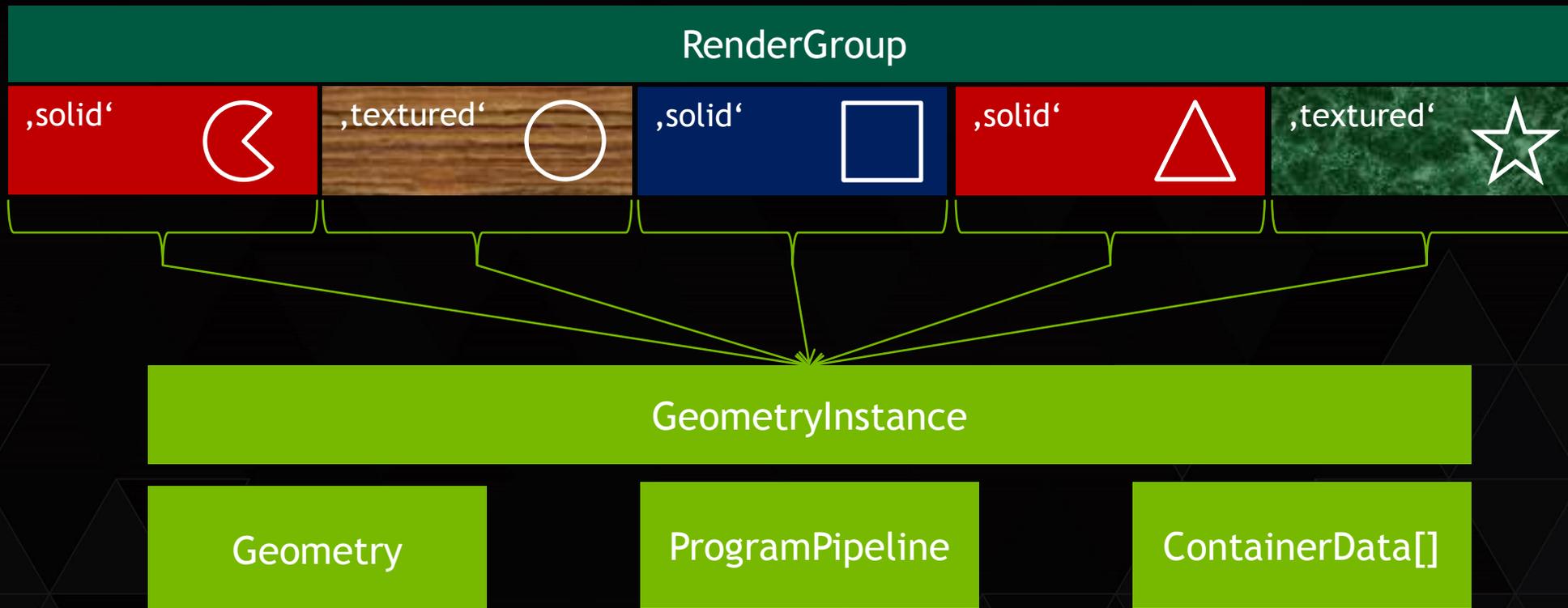


RENDER PIPELINE USING RIX



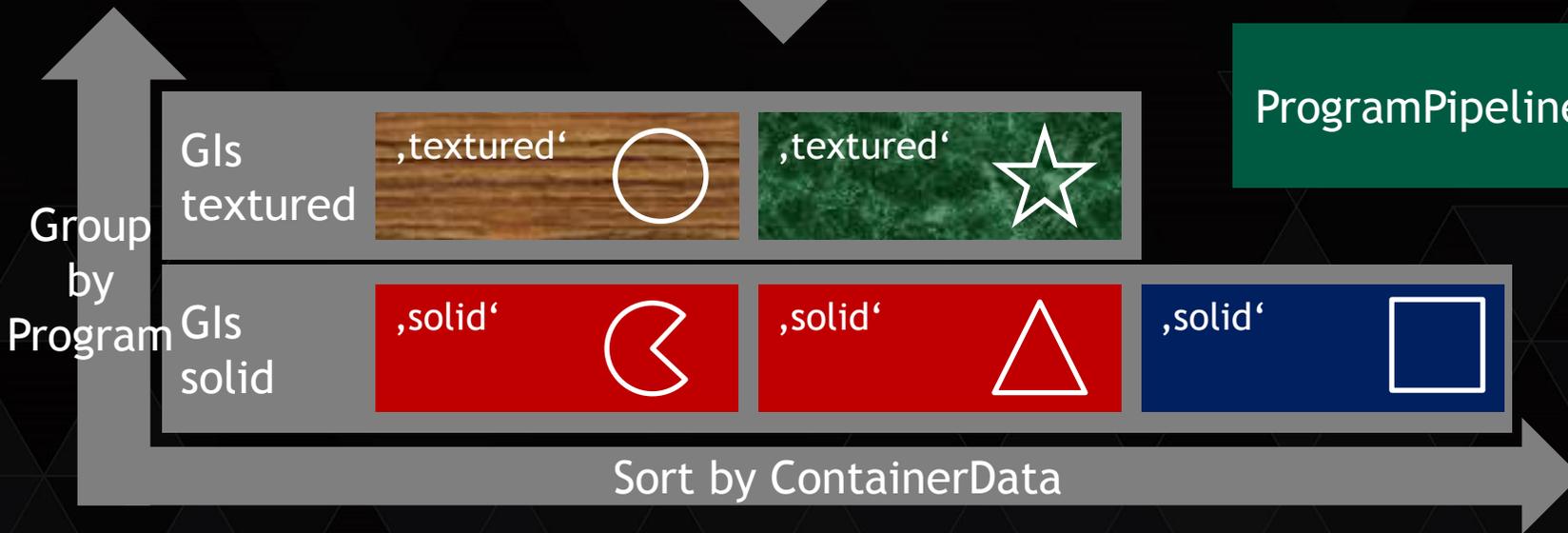
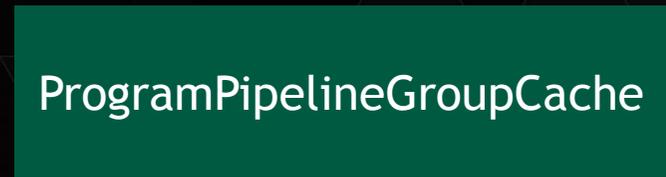
- ▶ RenderGroup per render pass
 - ▶ Rendering cache can be optimized for pass
 - ▶ Depth-Pass might require only positions, but not normals and texture coordinates -> smaller cache
 - ▶ Fewer OpenGL calls than opaque pass with optimized cache
 - ▶ Transparent pass might or might not require ordering

RENDER GROUP



GeometryInstance can only be referenced by single RenderGroup

RENDER GROUP



PROGRAM PIPELINE GROUP CACHE

```
ProgramPipelineGroupCache<VertexCache, ParameterCache>
```

AttributeCacheEntry



GeometryInstanceCacheEntry

,solid'



,solid'



,solid'



ContainerCacheEntry

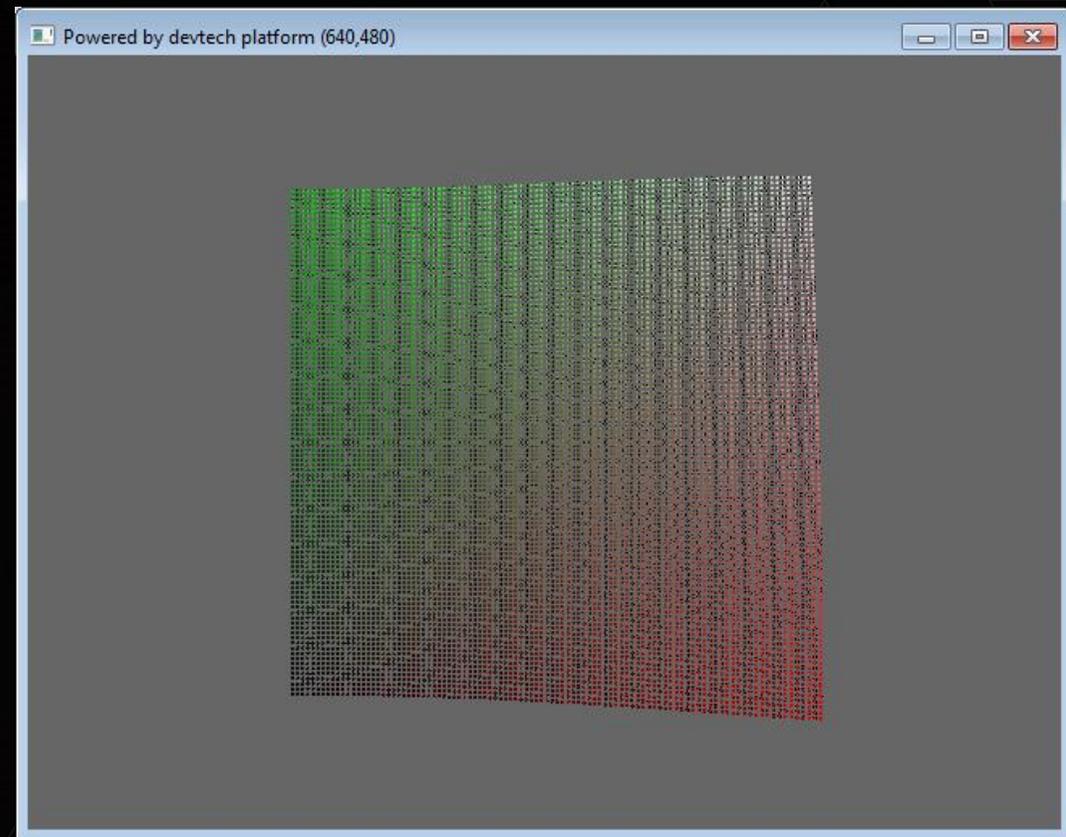


offset

```
std::vector<unsigned char> uniforms;  
dp::gl::Buffer  bufferData; // UBO, SSBO
```

BENCHMARK

- ▶ GLUTAnimation
 - ▶ 100x100 Spheres
 - ▶ Geometry duplication
 - ▶ 5 different materials
 - ▶ Each sphere has own ,color‘



CPU TIME VERTEX TECHNIQUES

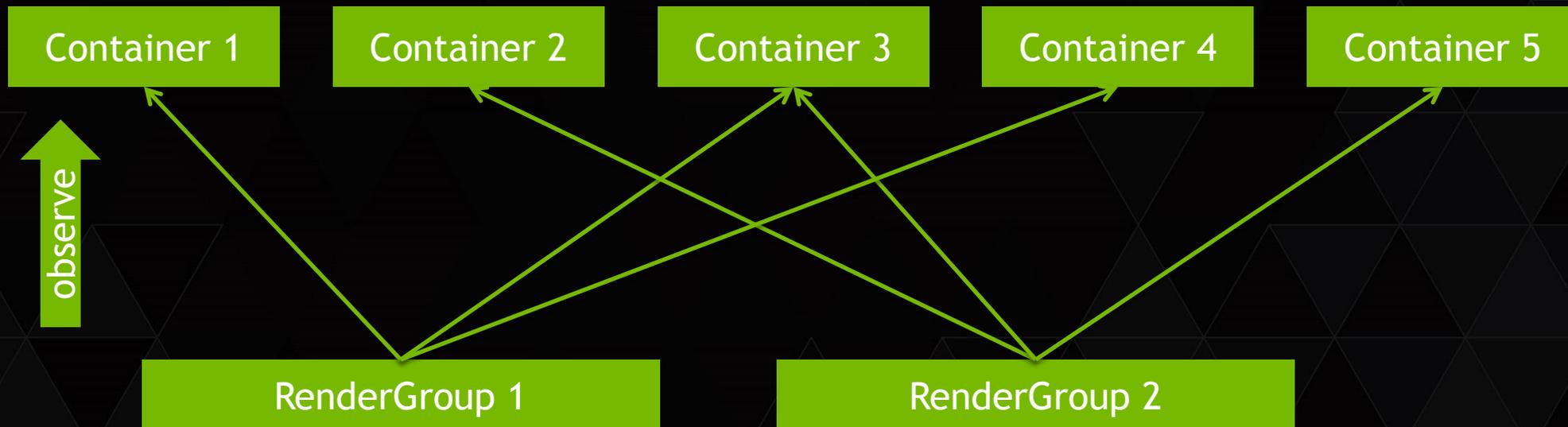
Technique	Bindless		Bindless
	Rendertime (ms)		
VBO	5.7	1.8	2
VAB	4.9	1.6	1.8
VAO	7.5	3.2	3.2
	1 stream		2 stream

CPU TIME PARAMETER TECHNIQUES



PARAMETERS UPDATE HANDLING

- ▶ Each RenderGroup has a set of ContainerDatas
 - ▶ Map of containerData -> cache position (IMAGE)
- ▶ How to manage dirty state per RenderGroup efficient?
 - ▶ Set of ContainerData

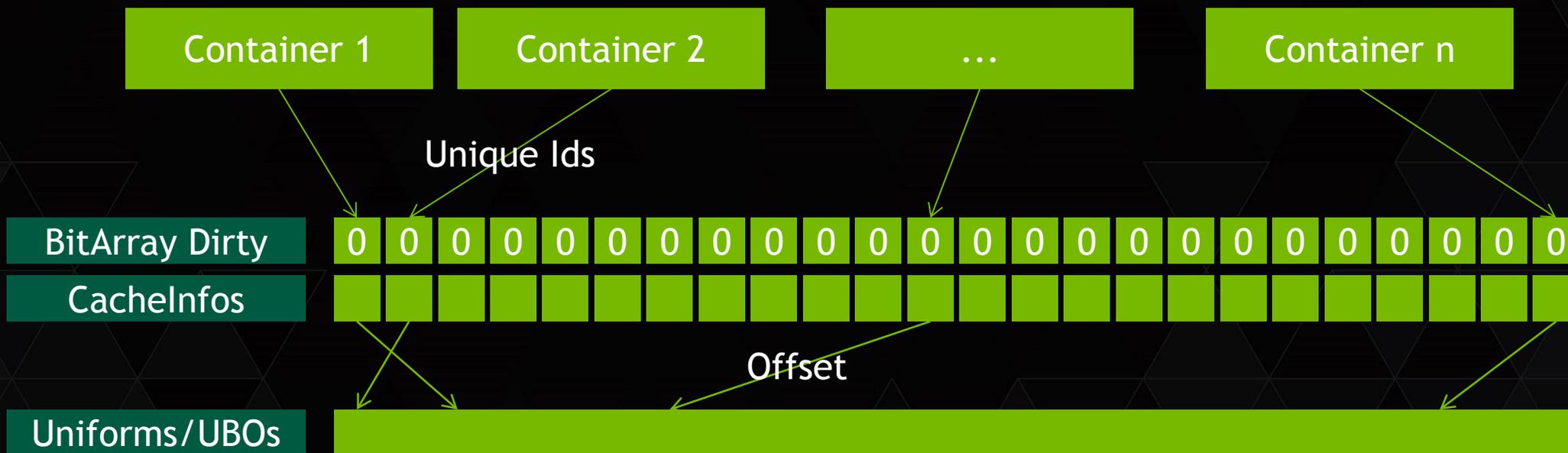


CONTAINERDATA UPDATE HANDLING

- ▶ First approach
 - ▶ RenderGroup holds `std::set<ContainerData>` of dirty objects
 - ▶ `std::map<ContainerData, CacheLocation>` for `ContainerData->CacheLocation` mapping
- ▶ Profiling revealed this was a bad idea
 - ▶ Dirty phase
 - ▶ `std::set::insert`, top hotspot in `GLUTAnimation`
 - ▶ Binary search, allocation, large amount of ‘random memory access’ ops
 - ▶ Update Phase
 - ▶ `std::map<ContainerData*, CacheLocation>::find()`
 - ▶ Binary search, ‘random memory access’

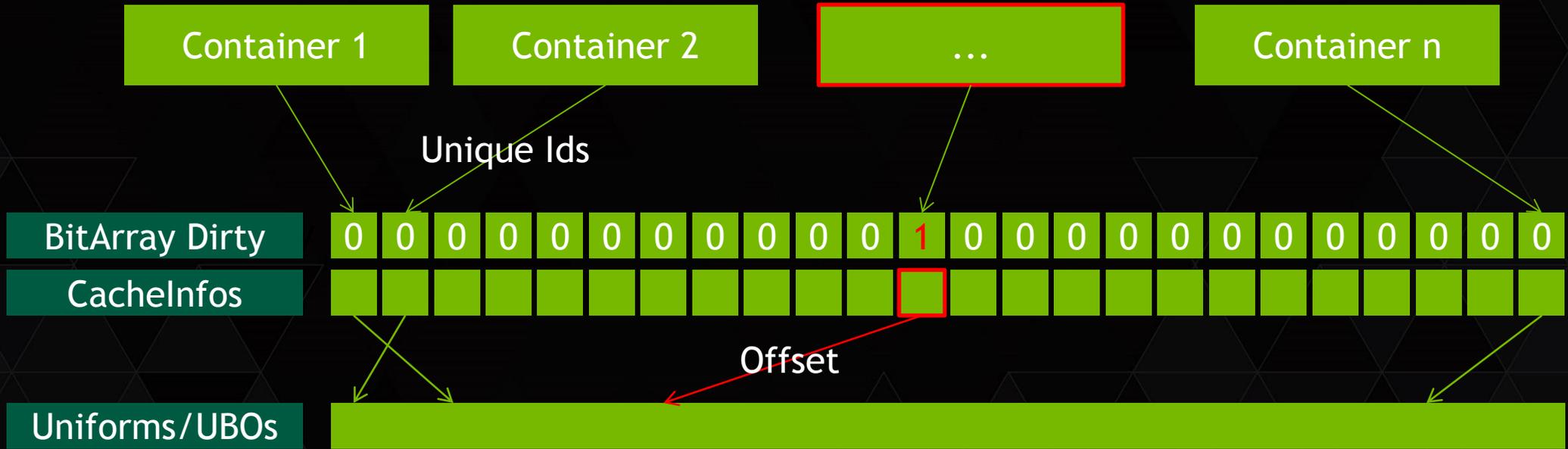
CONTAINERDATA UPDATE HANDLING

- ▶ Second approach
 - ▶ Assign each Container a unique id, keep unique ids as dense as possible



CONTAINERDATA UPDATE HANDLING

- ▶ Update phase: Set bits in dirty array
- ▶ Process update phase: Get offset from CacheInfos Array
- ▶ Constant time operations



RESULTS

	Time STL (ms)	Time BitArray (ms)	Profiler Hotspot
Do Updates	4.8	2.5	Event handling
Process Update	4.0	0.9	Cache update
Total Time	8.8	3.6	

BITARRAY::TRAVERSEBITS

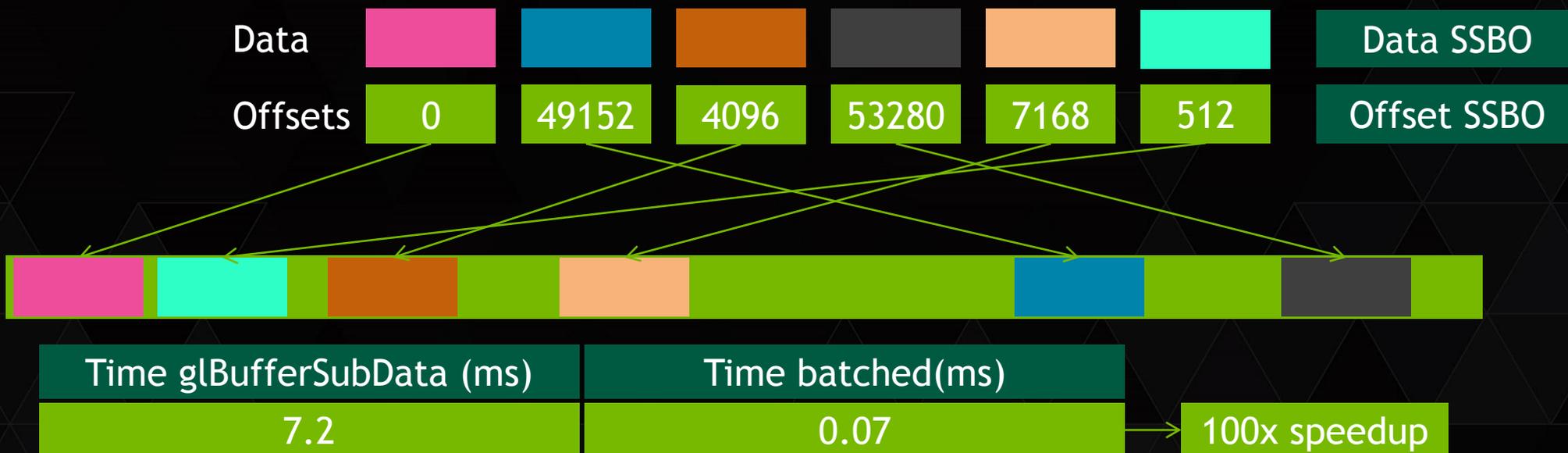
- ▶ Linear memory -> cache efficient
- ▶ Works on size_t type, skips 32/64 bits if no bit is set in a element
- ▶ Uses ctz (count trailing zeroes) intrinsics
 - ▶ No branch mispredicion issues on 01001101 pattern
- ▶ 1M bits need 122kb, ~0.4us traversal time if no bit set
- ▶ As comparison
 - ▶ Red-Black treenode has 3 ptrs and a color, at least
 - ▶ 64-bytes per node + payload
 - ▶ 1953 nodes need more memory than 1m bits
- ▶ BitTree would solve linear problem during traversal

SPARSE UBO/SSBO UPDATES

- ▶ Efficient algorithm to handle changed containers -> done
- ▶ Assuming thousands of Containers referencing UBOs are dirty
 - ▶ How to execute an efficient update?
 - ▶ One map/unmap call for the UBO?
 - ▶ No, too much data transfer between CPU and GPU
 - ▶ One mapRange/unmapRange per update?
 - ▶ No, mapRange/unmapRange create sync points
 - ▶ glBufferSubData?
 - ▶ If glBindBufferRange is being used it'll be slow too!

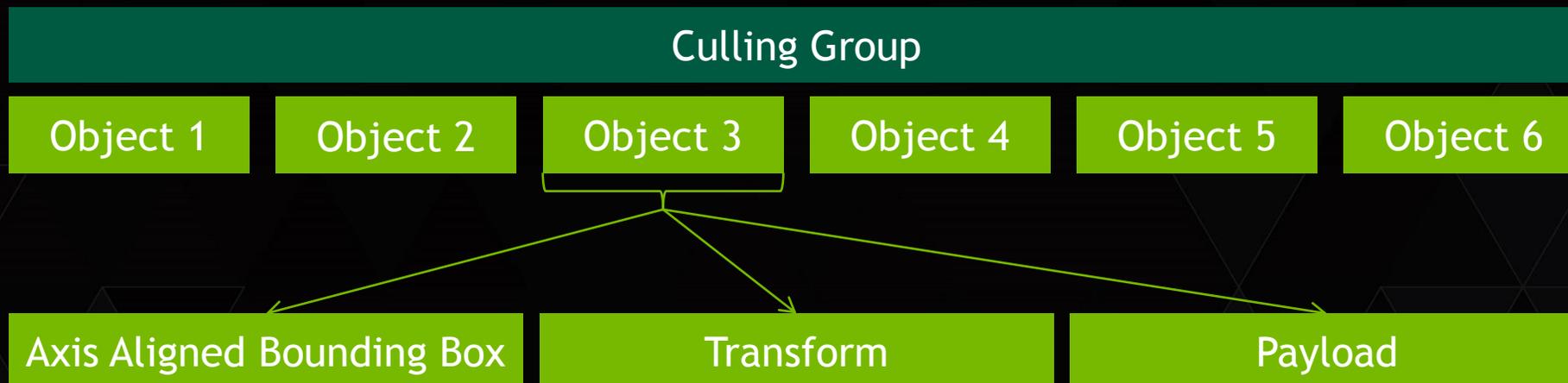
SPARSE UBO/SSBO UPDATES

- ▶ `dp::gl::BufferUpdater`
 - ▶ Supports updates of any block-size which is a multiple of 16
 - ▶ Gathers all updates, uploads them as compact buffer and scatters on the GPU



CULLING

- ▶ `dp::culling` abstract API for frustum culling
 - ▶ CPU & OpenGL compute backend



CULLING

- ▶ `foreach` (object : group) {
 `isVisible = result->isVisible` (object->culling);
 `setVisible` (object->rix, isVisible);
 }
- ▶ expensive ,query‘ and update call for each object
- ▶ Solution: `ResultObject.Cull` (group, result, viewProjection);

Culling Group						
	Object 1	Object 2	Object 3	Object 4	Object 5	Object 6
Old visibility	1	0	0	1	0	1
New visibility	1	0	1	0	0	1
XOR	0	0	1	1	0	0

BitArray::TraverseBits on XOR result

RESULTS

- ▶ Scene traversal can be avoided for static scene parts
- ▶ Rendering time depends a lot on used OpenGL methods
 - ▶ VAB + glBindBufferRange UBO good, in combination with bindless best
- ▶ BitArrays can be a good tool to avoid maps/sets
- ▶ Try to batch small updates to GPU memory

- ▶ Still CPU bound?
 - ▶ S5135 - GPU-Driven Large Scene Rendering in OpenGL (Tue 16:00, LL21B)
- ▶ GPU bound?
 - ▶ S5291 - Slicing the Workload: Multi-GPU Rendering Approaches (Web 10:00, LL21B)

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THANK YOU

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JOIN THE CONVERSATION

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<http://github.com/nvpro-pipeline>