

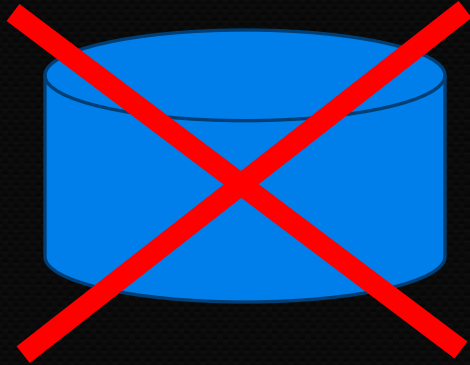
GPU-Based Scene Generation for Flight Simulation

Tim Woodard
Chief Technology Officer
Diamond Visionics
www.dvcsim.com



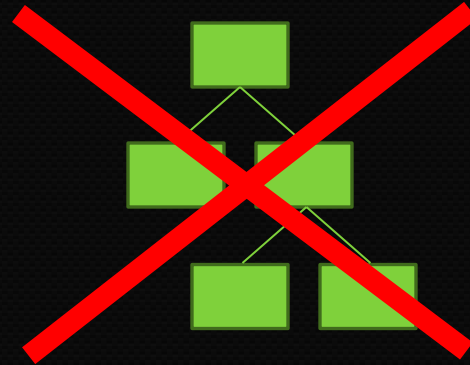
▷ Database Generation

▷ Pre-compile LODs



▷ Image Generation

▷ Hierarchical scene graph



Approach used by most geo-spatial visual systems

How can we optimize these two areas and leverage the GPU?

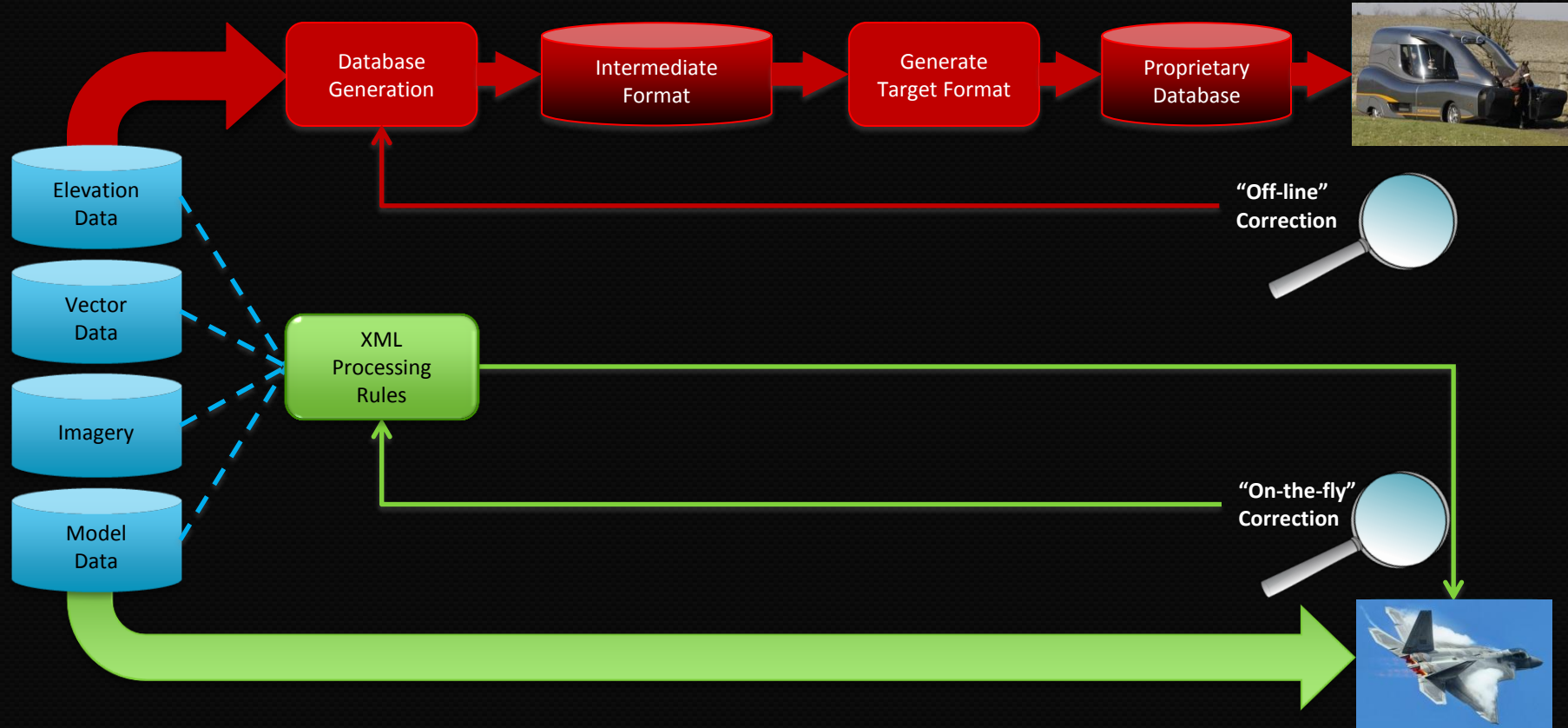
Eliminate both!

Flight Simulation vs. Gaming

- ▶ Instructor-controlled conditions (time, clouds, fog, etc.)
- ▶ 20+ channels
- ▶ No aliasing
- ▶ No Z-fighting
- ▶ No LOD popping
- ▶ Subjective tuning
- ▶ *Never* drop frames
- ▶ **LARGE** “gaming” areas



Process: from Source to Scene



You're doing it wrong



- ▶ Pre-compute LODs for all possible paths into “polygon soup”
- ▶ Very little of the result is typically used
- ▶ Uses tremendous computing resources
- ▶ Uses tremendous amount of storage space

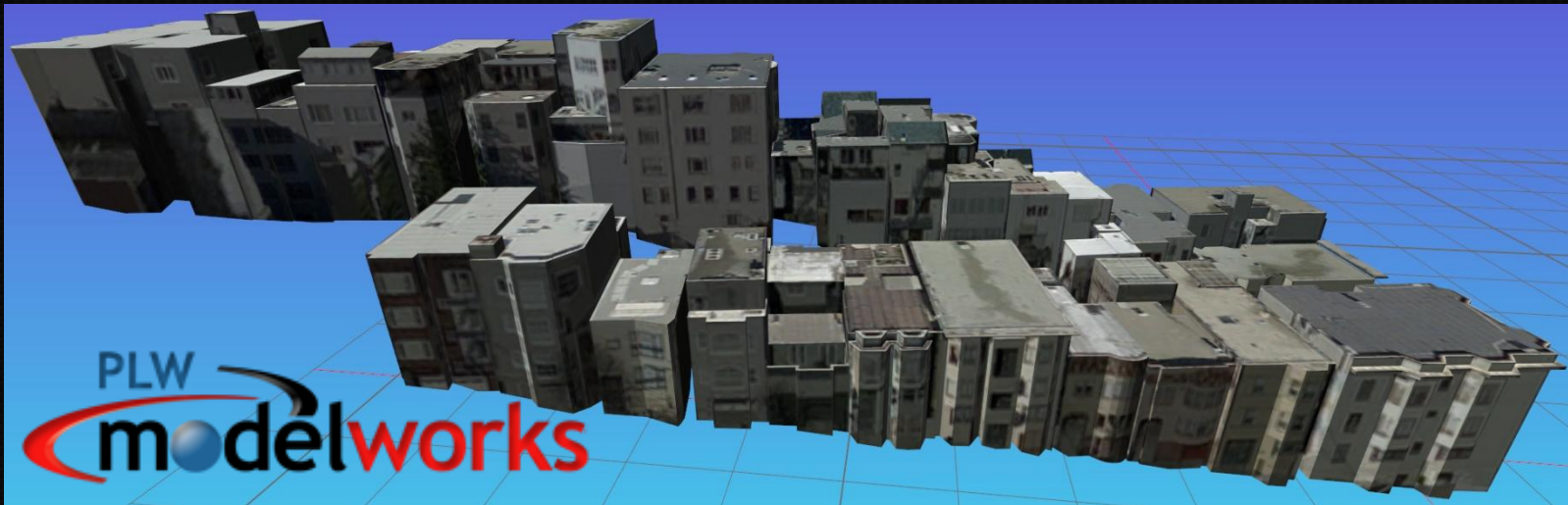
Much better...



- ▷ On-the-fly construction of LODs
- ▷ Highly parallelized CPU
- ▷ Construction targets GPU for optimal performance
- ▷ Uses minimal amount of storage space

San Francisco Dataset Statistics

- ▶ Quadro M6000 stress test – expected result: 30% speedup
 - ▶ Over 85K 3D models, 13.5M polys
 - ▶ Over 4 GB of compressed textures

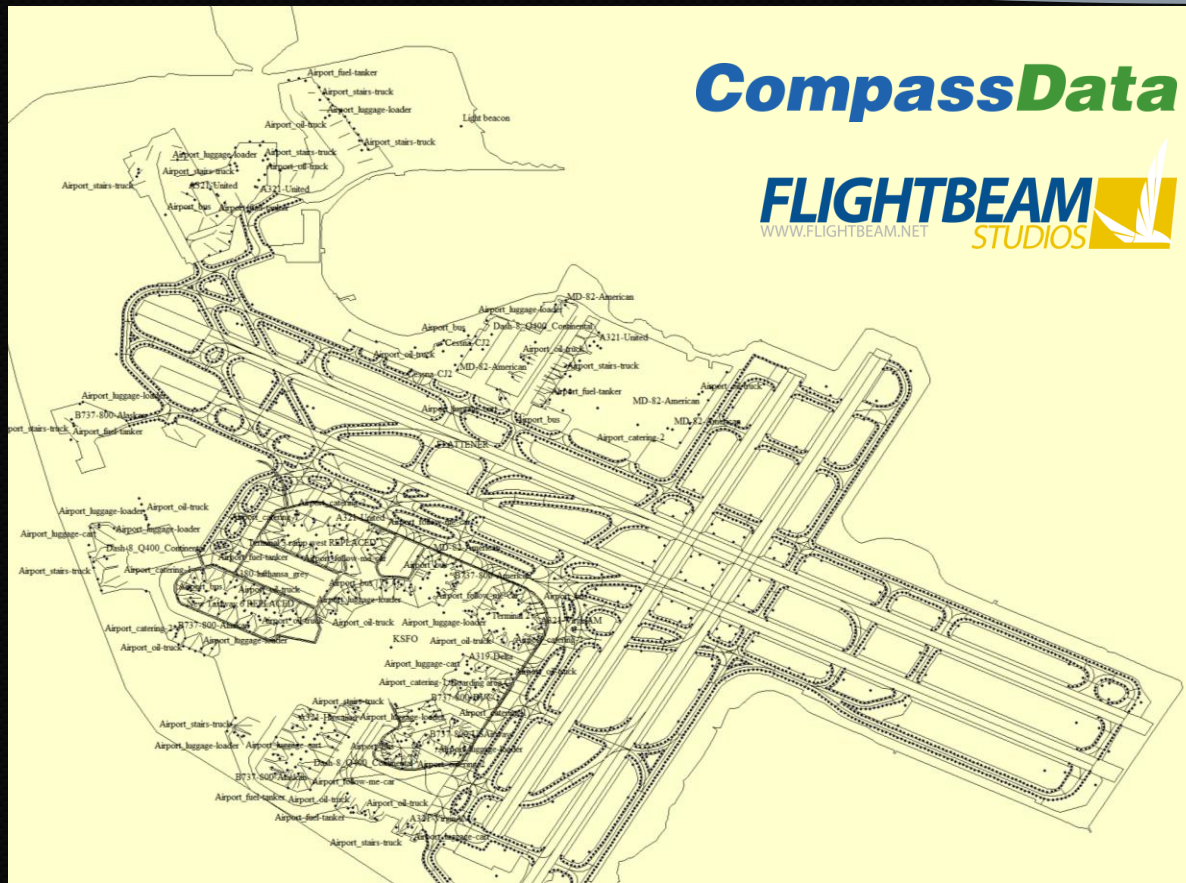


San Francisco Dataset Statistics

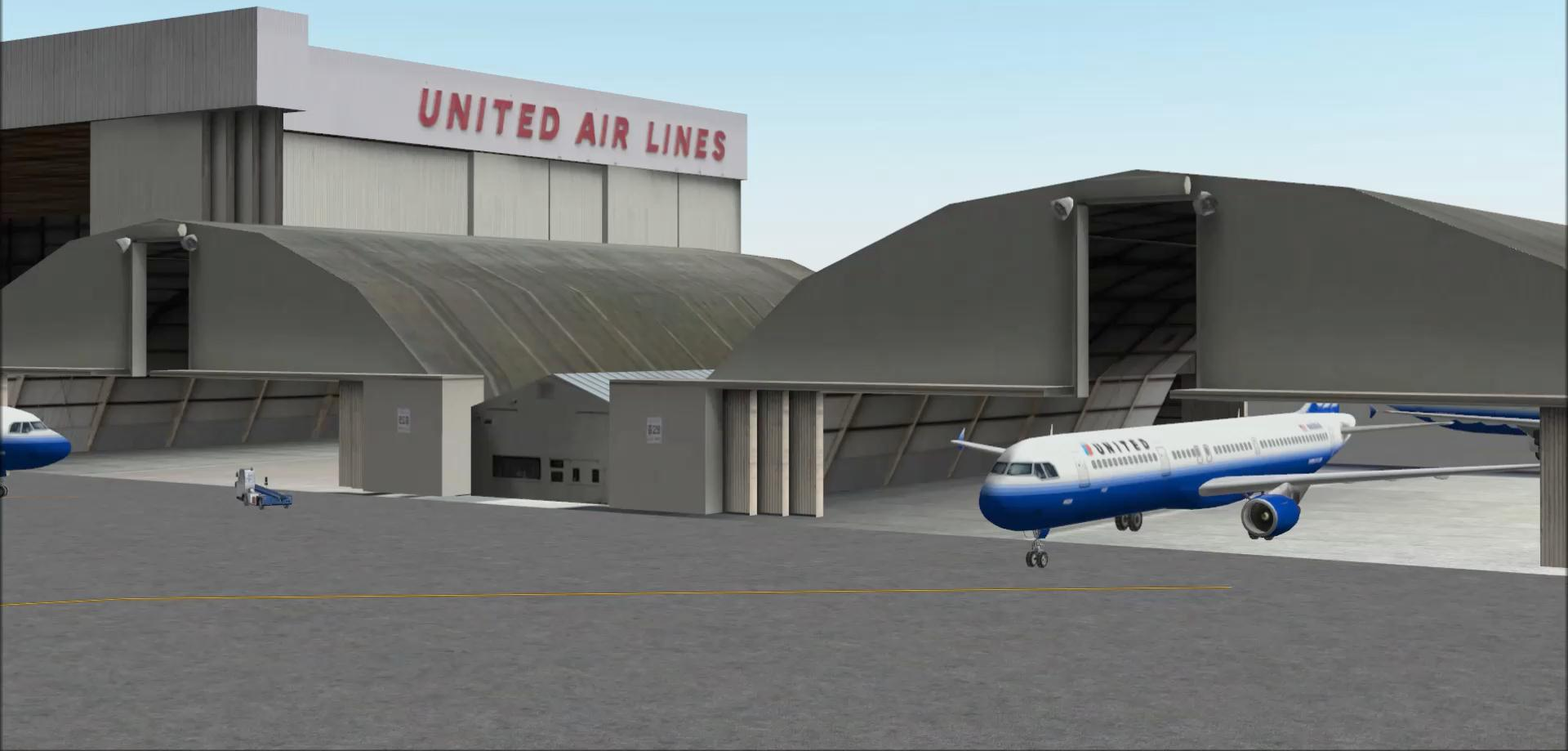
- ▷ All the roads in CA
- ▷ Light points and pools generated for all of them



SFO Vector Features



- ▷ Quadro M6000 over 100% faster than K6000!
- ▷ Applying modern OpenGL
 - ▷ 75% reduction in draw calls by using bindless and MDI
 - ▷ 2.5+ ms / frame CPU time reduction
- ▷ Still more room for improvement
 - ▷ 99% reduction by using `NV_command_list`
 - ▷ 8+ms / frame CPU time reduction
- ▷ Typical results
 - ▷ CPU: 9.8 -> 7.2 = 1.4x speedup
 - ▷ GPU: 13.8 -> 6.1 = 2.2x speedup









SOUTH
SAN FRANCISCO
THE INDUSTRIAL CITY













Questions?

Related talks:

- S5135 – GPU-Driven Large Scene Rendering in OpenGL
- S5258 – Dense 3D Culture Rendering using NVIDIA Solutions in Immersive Fast-Jet Simulators
- S5142 - See the Big Picture: Scalable Visualization Solutions for High Resolution Displays
- S5451 - The Graphics Debugger for Linux

Exhibit hall: PNY and Concurrent

Tim Woodard

timw@dvcsim.com

Thank you!

Please complete the Presenter Evaluation sent to you by email or through the GTC Mobile App. Your feedback is important!

