

Interactive Visual Exploration of Peridynamic-Based Fracture Simulation

Chakrit Watcharopas

joint work with

Joshua A. Levine and Robert M. Geist

18 Mar 2015 @ NVIDIA GTC



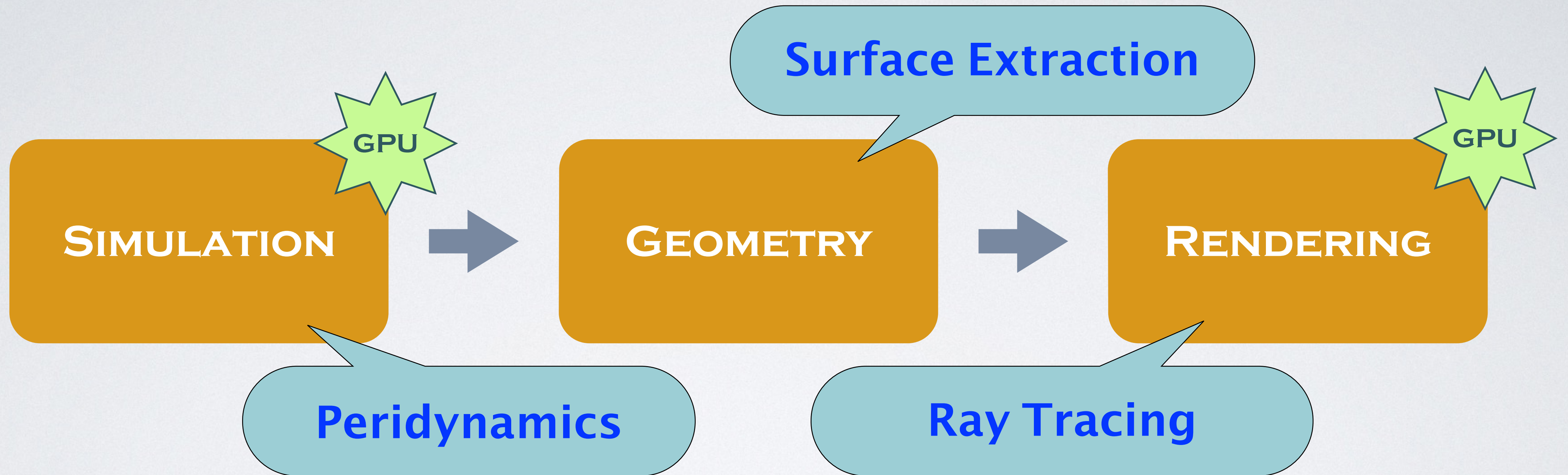
Our Previous Works

- “*Modeling Fracture on the GPU with Peridynamics*” @ GTC 2014
 - ♦ Presented by Joshua Levine
- “*A Peridynamic Perspective on Spring-Mass Fracture*” @ SCA 2014
 - ♦ Authored by Joshua Levine, Adam Bargteil, Christopher Corsi, Jerry Tessendorf, and Robert Geist
- Motivation from:
 - ♦ Silling S. *Journal of Mechanics and Physics of Solids*. 48(1): 175-209, 2000.
 - ♦ many others...

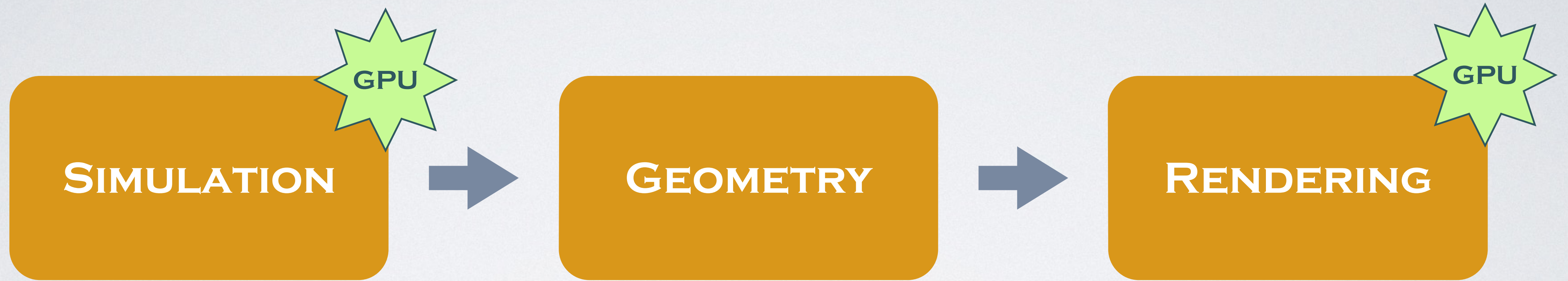
Vase fractured
on the table in
slow motion



Our Workflow



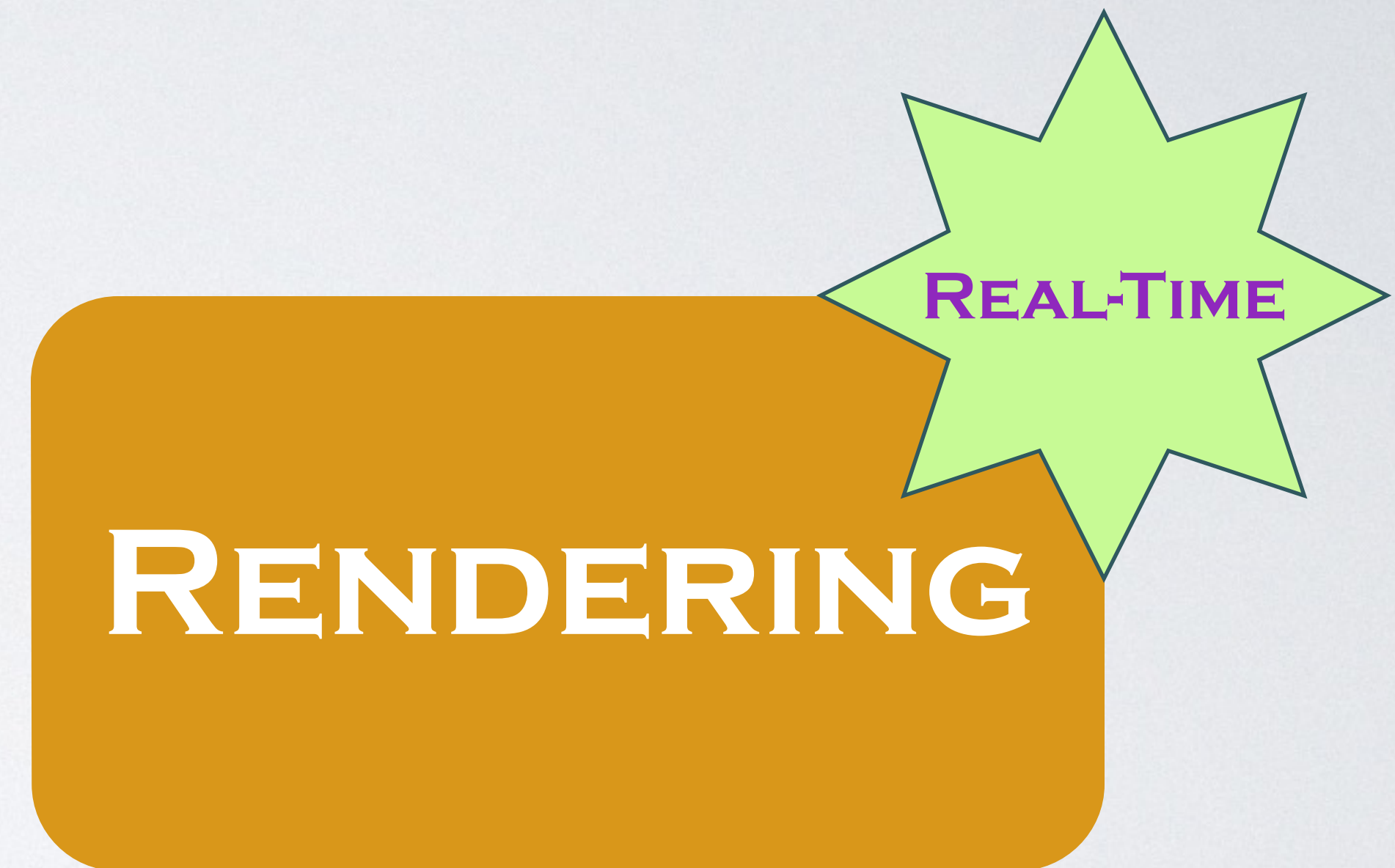
Our Workflow



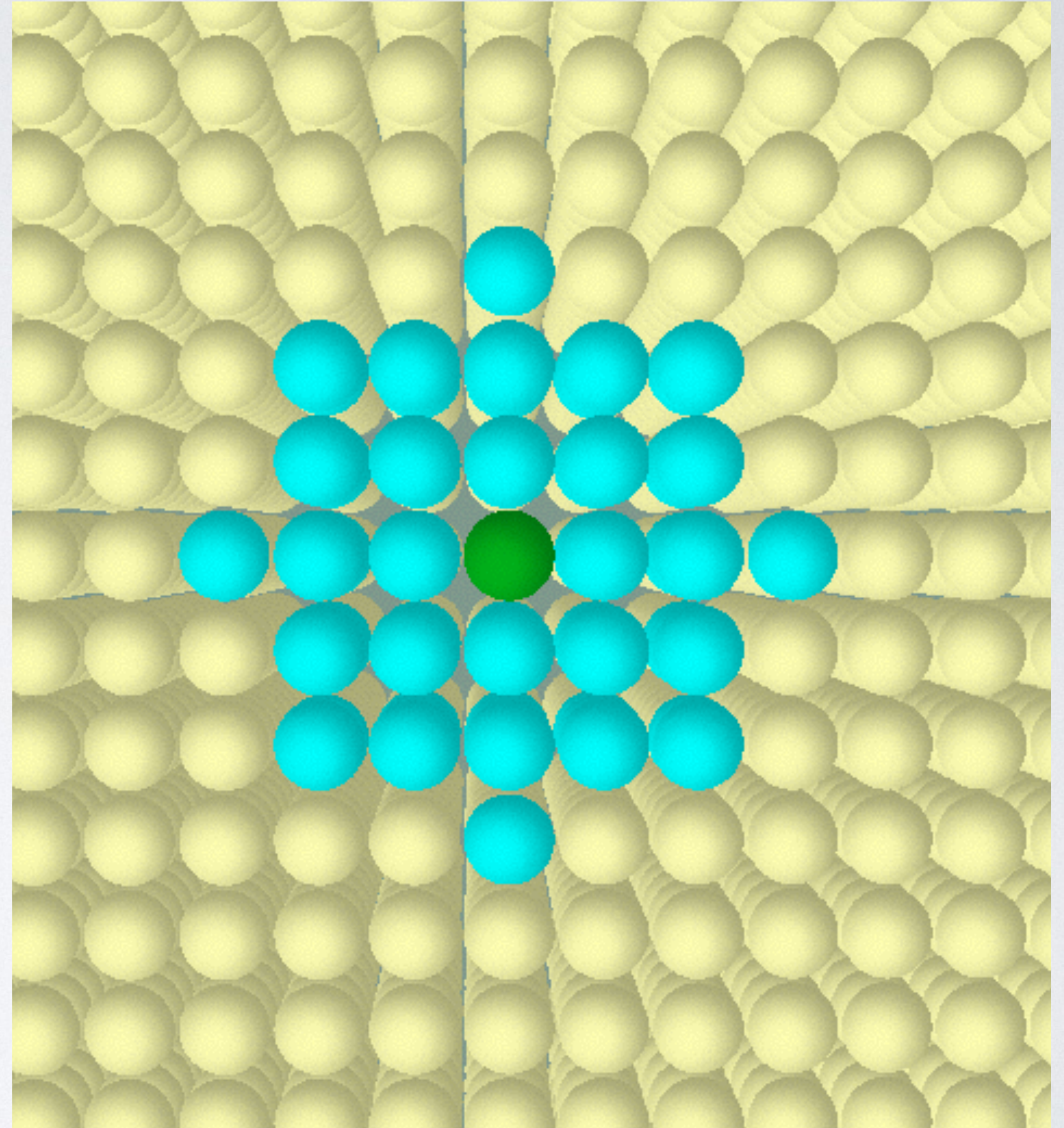
time(simulation) ~ time(rendering) >>>>> time(geometry)

Our Modified Workflow

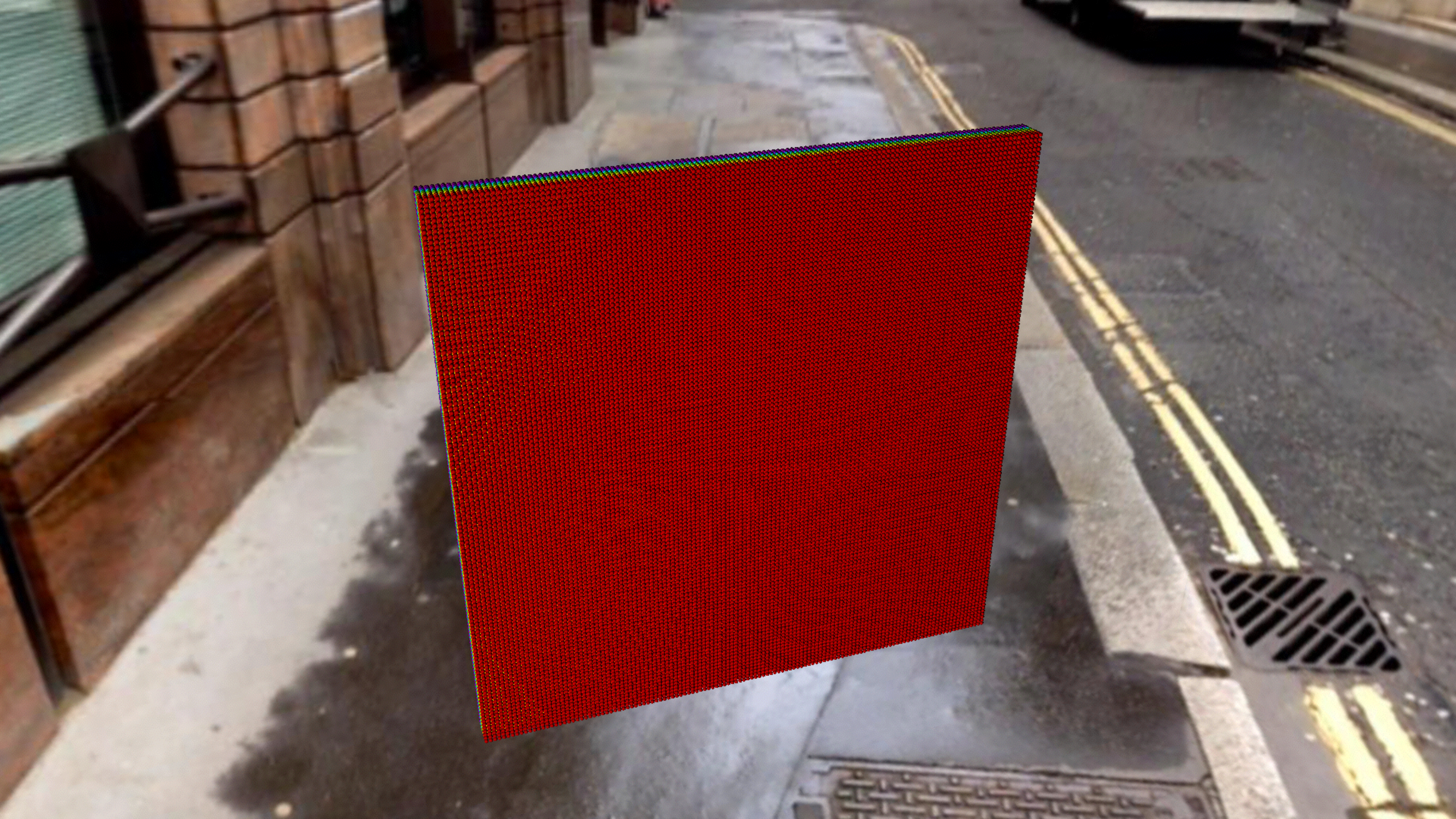
- We make the rendering faster; make it real-time
- We build an Interactive Visual Exploration Tool

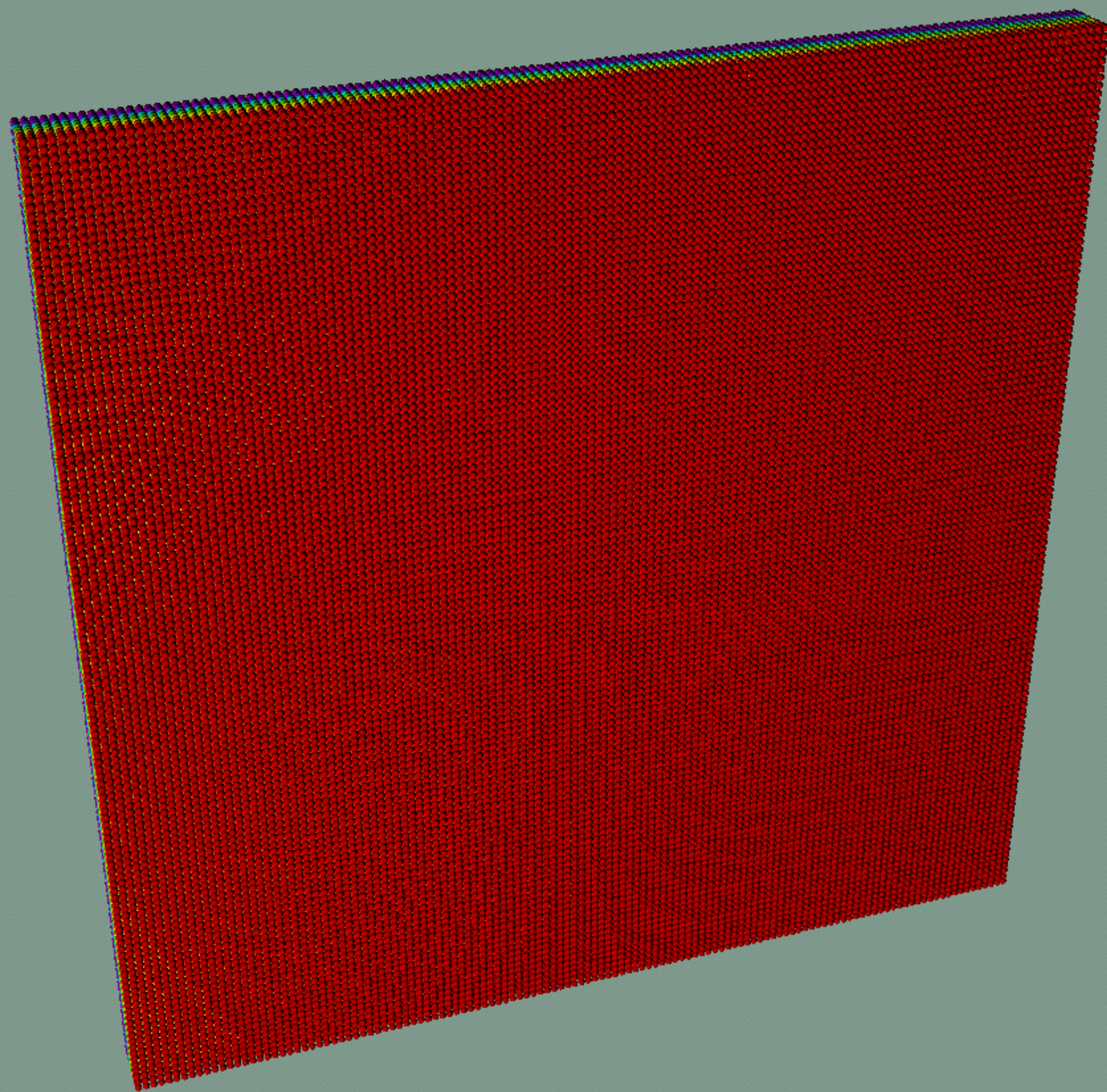


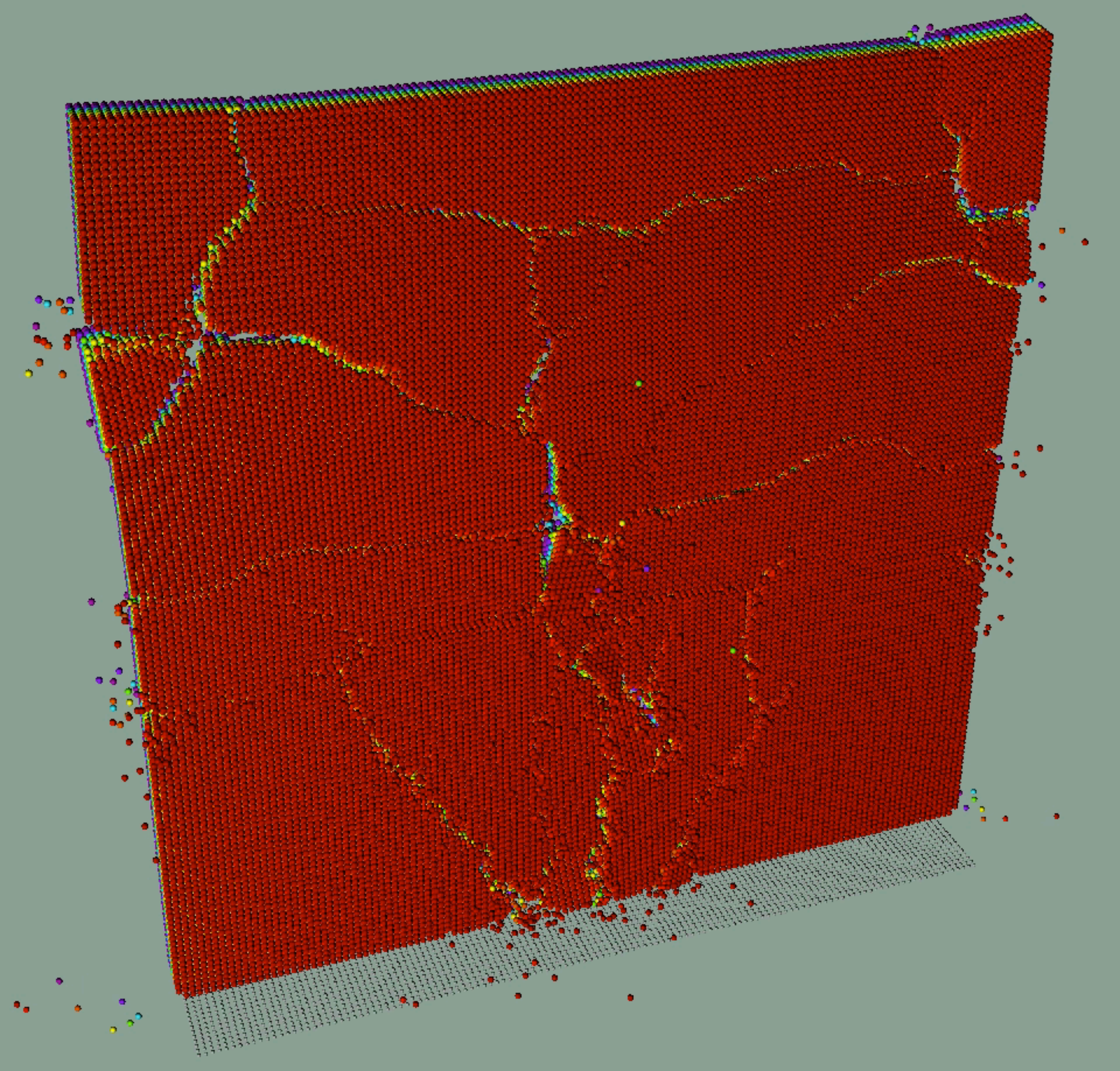
What is Peridynamics?

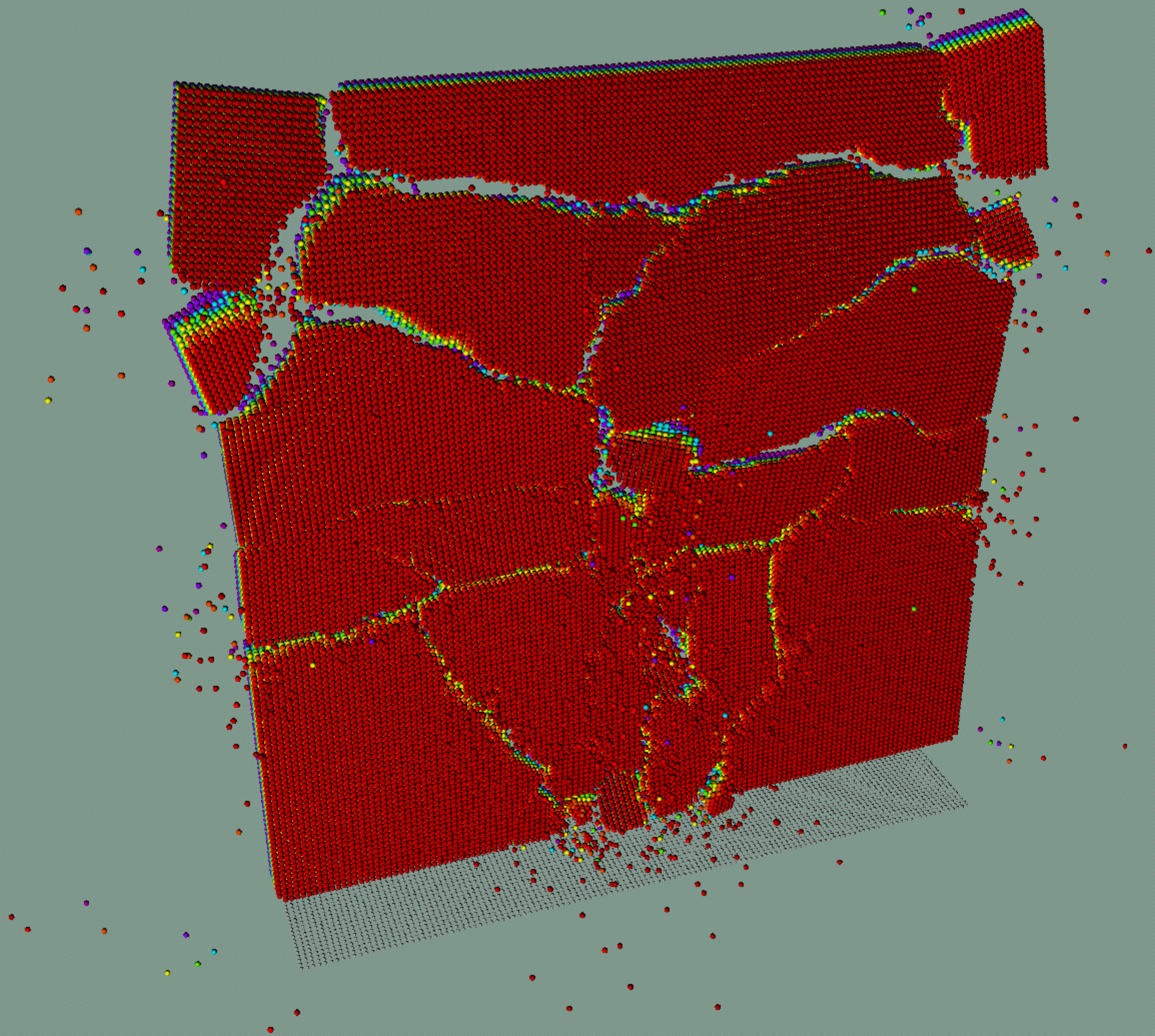


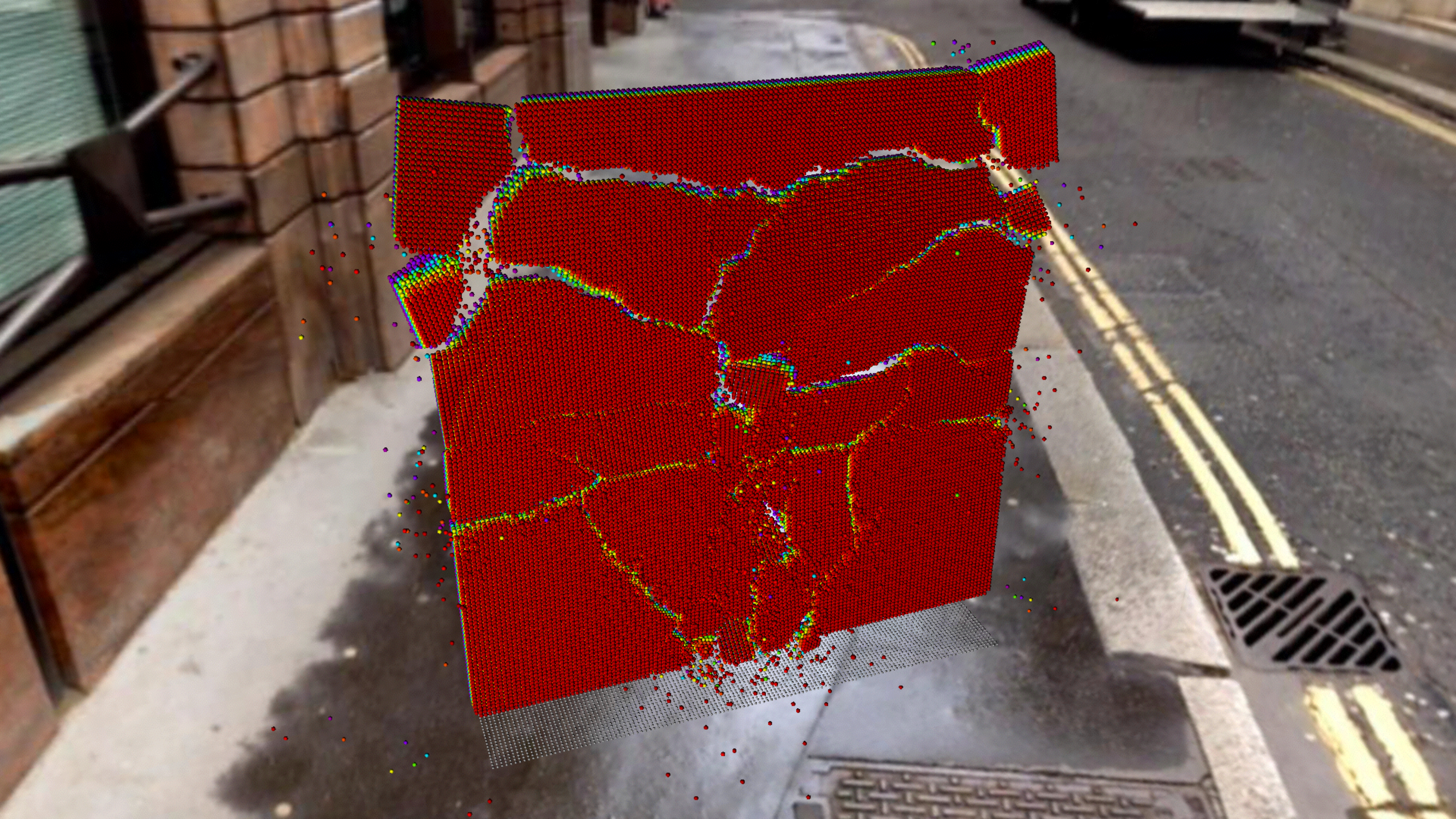














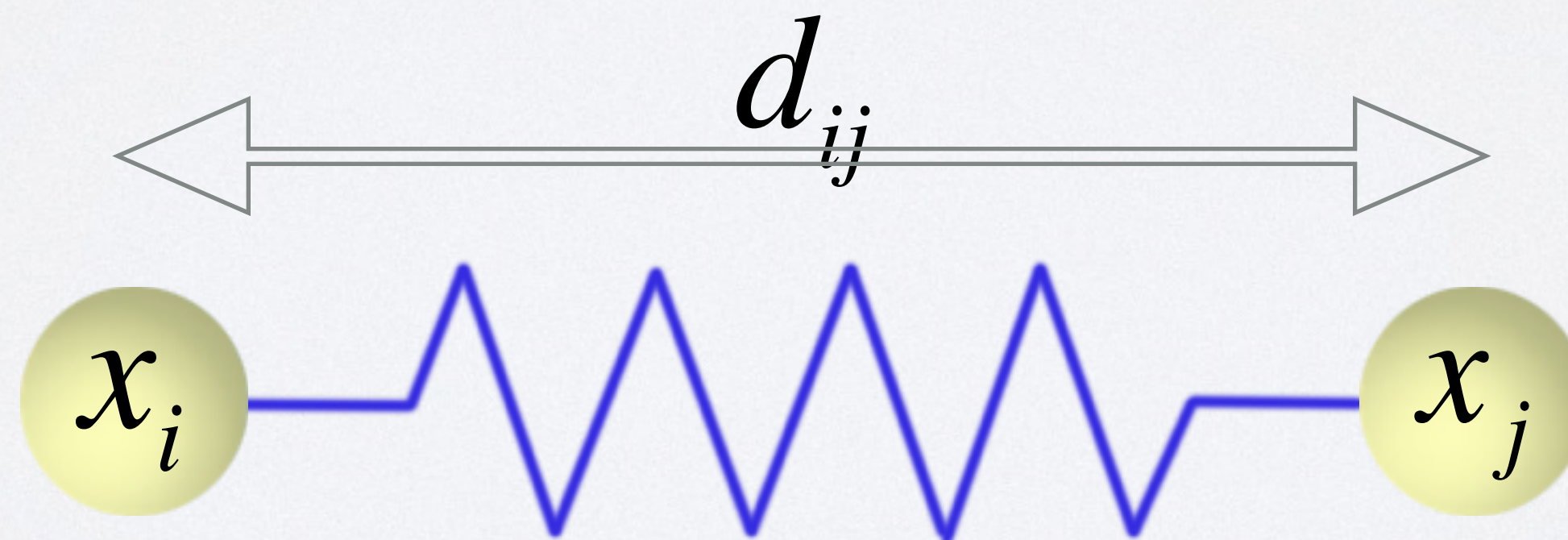
Peridynamic Formula

$$\rho(x) = -G(-x^2)/[xH(-x^2)]$$
$$0 - \alpha_0 \leq \pi/2 + 2\pi k, \quad p = 2\mathcal{V}_0 + (1/2)[1 - \text{sg } A_1]$$
$$A_j \rho^j \cos [(p - j)\theta - \alpha_j] + \rho^n$$
$$\mu \quad \rho^p > \sum_{j=0, j \neq p}^n A_j \rho^j, \quad \Delta_L \arg f(z) =$$
$$= \prod_{k=1}^n (u + u_k) G_0(u),$$
$$\rho(x) = -G(-x^2)/[xH(-x^2)]$$
$$p = 2\mathcal{V}_0 + (1/2)[1 - \text{sg } A_1], \quad \rho^p > \sum_{j=0, j \neq p}^n A_j \rho^j, \quad (\lambda - \lambda_0)$$
$$- \pi/2 +$$
$$(\pi/2)(S_1 + S_2) \quad G(u) =$$
$$\prod (u + u_k) G_0(u), \quad K_n^{(r)}(x, y) = K_n$$

Spring Force

- Traditional spring force exerted on particles i by j

$$f_s = -k_s \left(\underbrace{\|x_i - x_j\|}_{\text{scalar term}} - d_{ij} \right) \underbrace{\frac{x_i - x_j}{\|x_i - x_j\|}}_{\text{vector}}$$



Spring Force

- Traditional spring force exerted on particles i by j

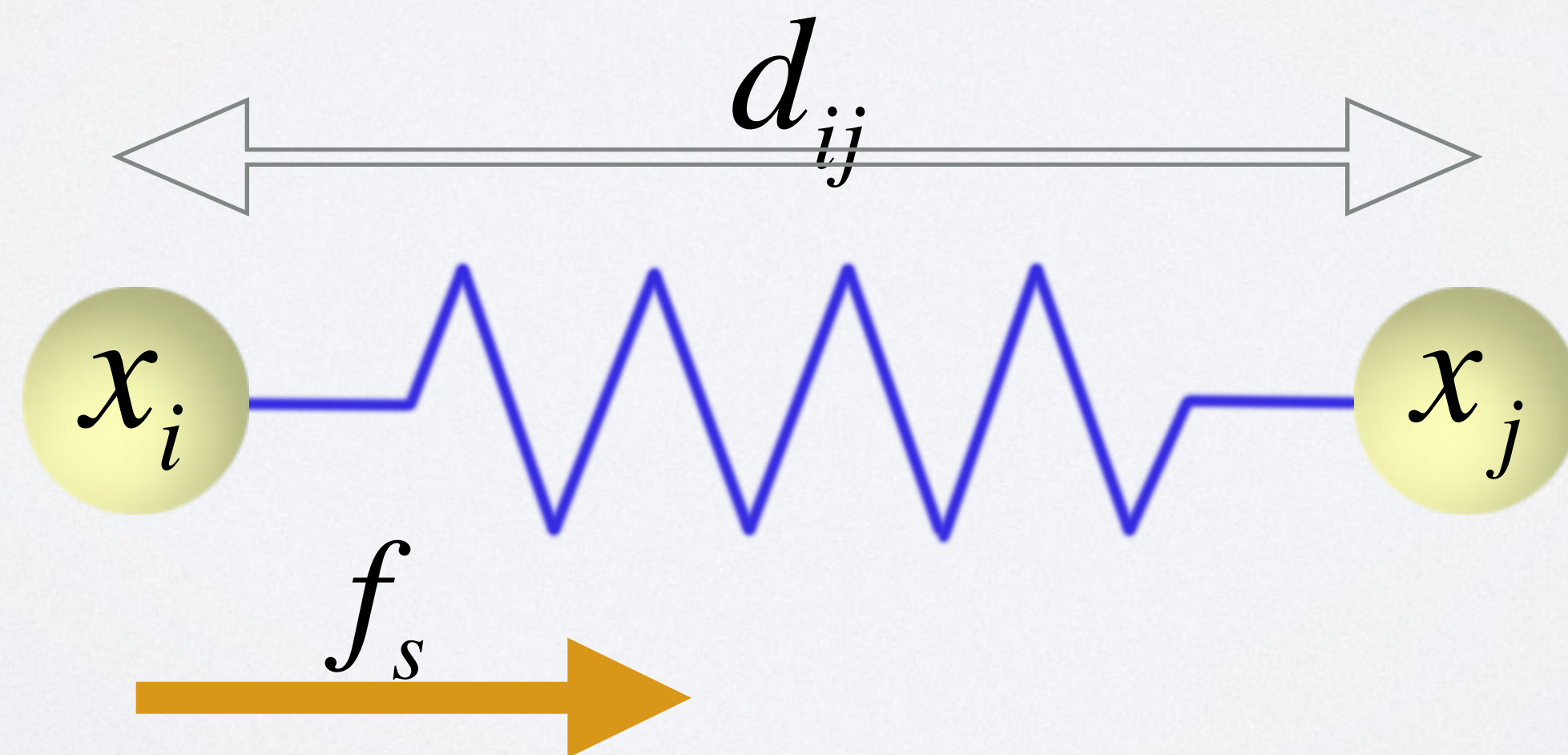
$$f_s = -k_s (\|x_i - x_j\| - d_{ij}) \frac{x_i - x_j}{\|x_i - x_j\|}$$



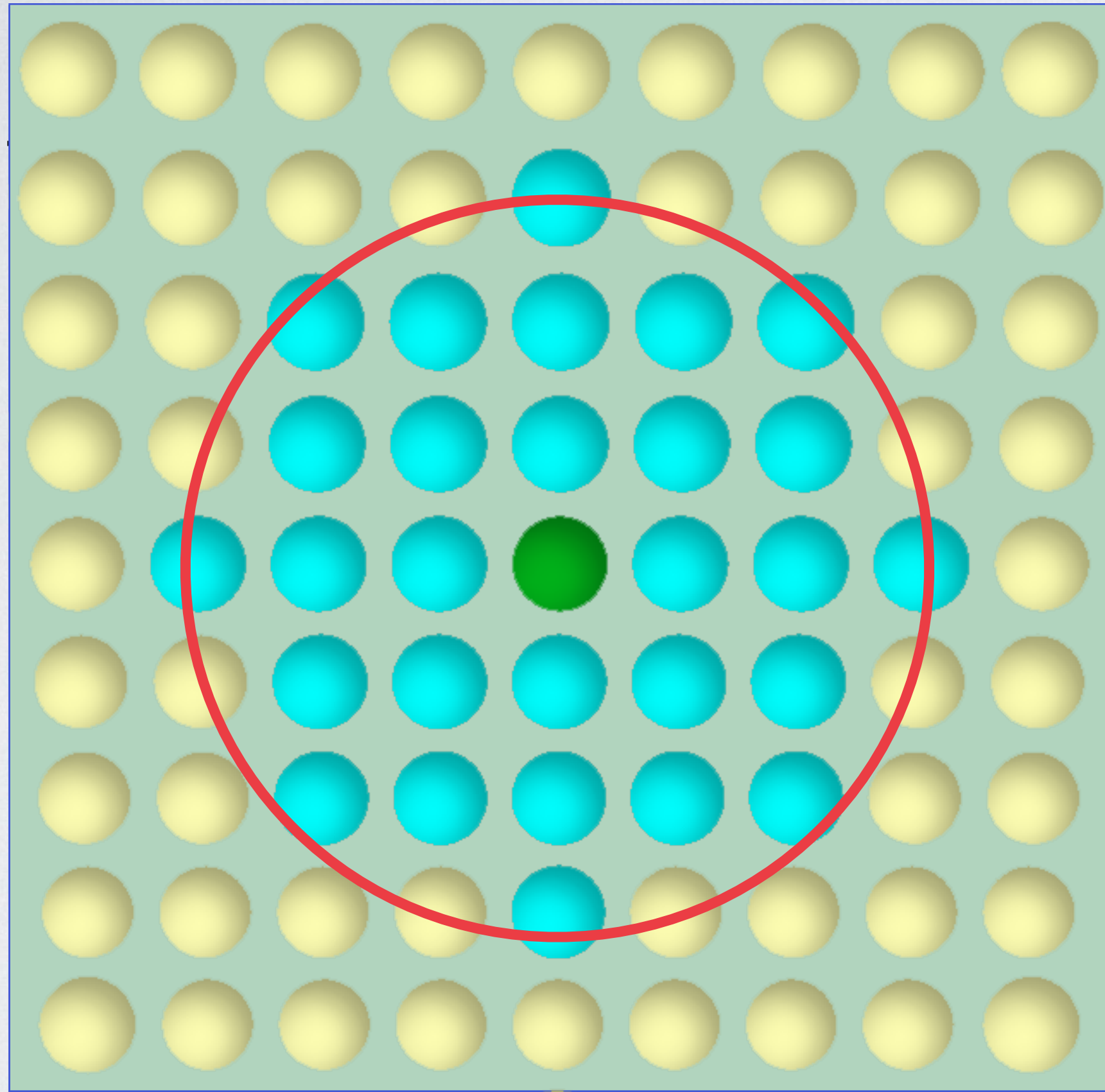
Spring Force

- Traditional spring force exerted on particles i by j

$$f_s = -k_s (\|x_i - x_j\| - d_{ij}) \frac{x_i - x_j}{\|x_i - x_j\|}$$



Traditional Spring Force & Peridynamic Force



- Peridynamic force^{1,2}

$$f_s = -k_s \varepsilon \frac{x_i - x_j}{\|x_i - x_j\|}$$

$$\varepsilon = \frac{\|x_i - x_j\| - d_{ij}}{d_{ij}}$$



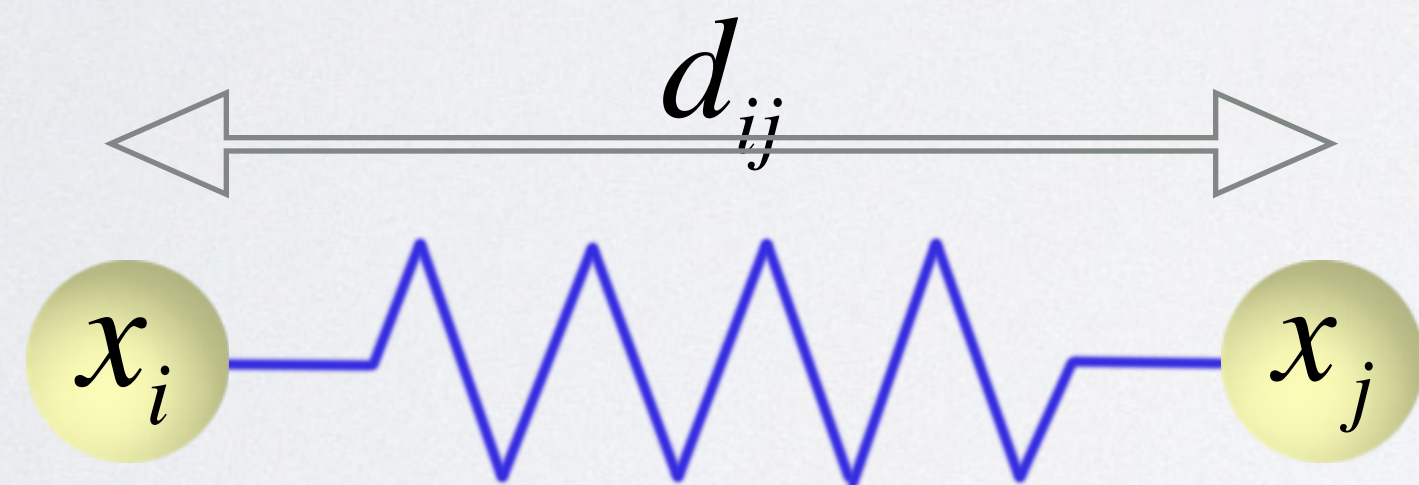
¹ Silling. J. of Mechanics and Physics of Solids. 48(1): 175-209, 2000.

² Emmrich, Lehoucq, and Puhst. In Meshfree Methods for Partial Differential Equations VI, vol. 89 of LNCSE, 45–65, 2013.

Traditional Spring Force & Peridynamic Force

- Traditional spring force

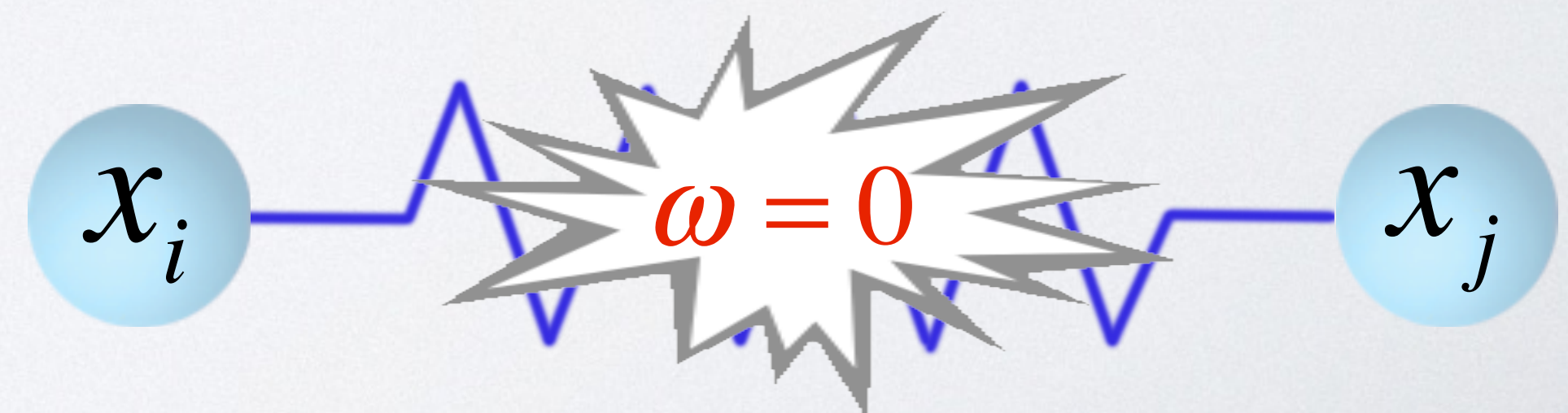
$$f_s = -k_s (\|x_i - x_j\| - d_{ij}) \frac{x_i - x_j}{\|x_i - x_j\|}$$



- Peridynamic force^{1,2}

$$f_s = -k_s \omega \varepsilon \frac{x_i - x_j}{\|x_i - x_j\|}$$

$$\varepsilon = \frac{\|x_i - x_j\| - d_{ij}}{d_{ij}}$$

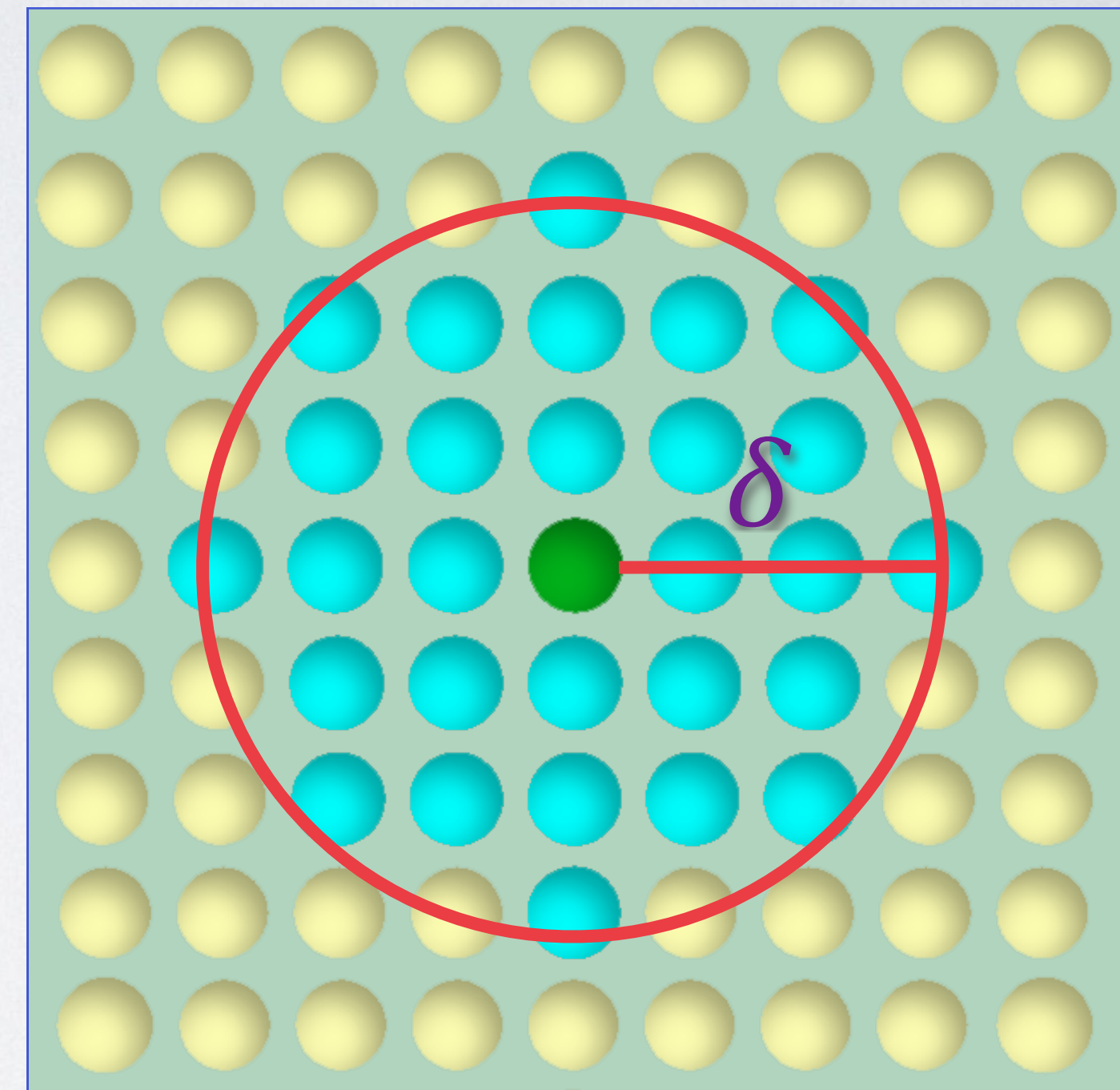


¹ Silling. J. of Mechanics and Physics of Solids. 48(1): 175-209, 2000.

² Emmrich, Lehoucq, and Puhst. In Meshfree Methods for Partial Differential Equations VI, vol. 89 of LNCSE, 45–65, 2013.

Peridynamic Particles

- Particles within radius δ are initially bonded
- When a bond stretches too far, the bond breaks
 - ✦ its strain ϵ exceeds the strain limit τ
 - ✦ $\omega \rightarrow 0$



Particle-Particle Collision

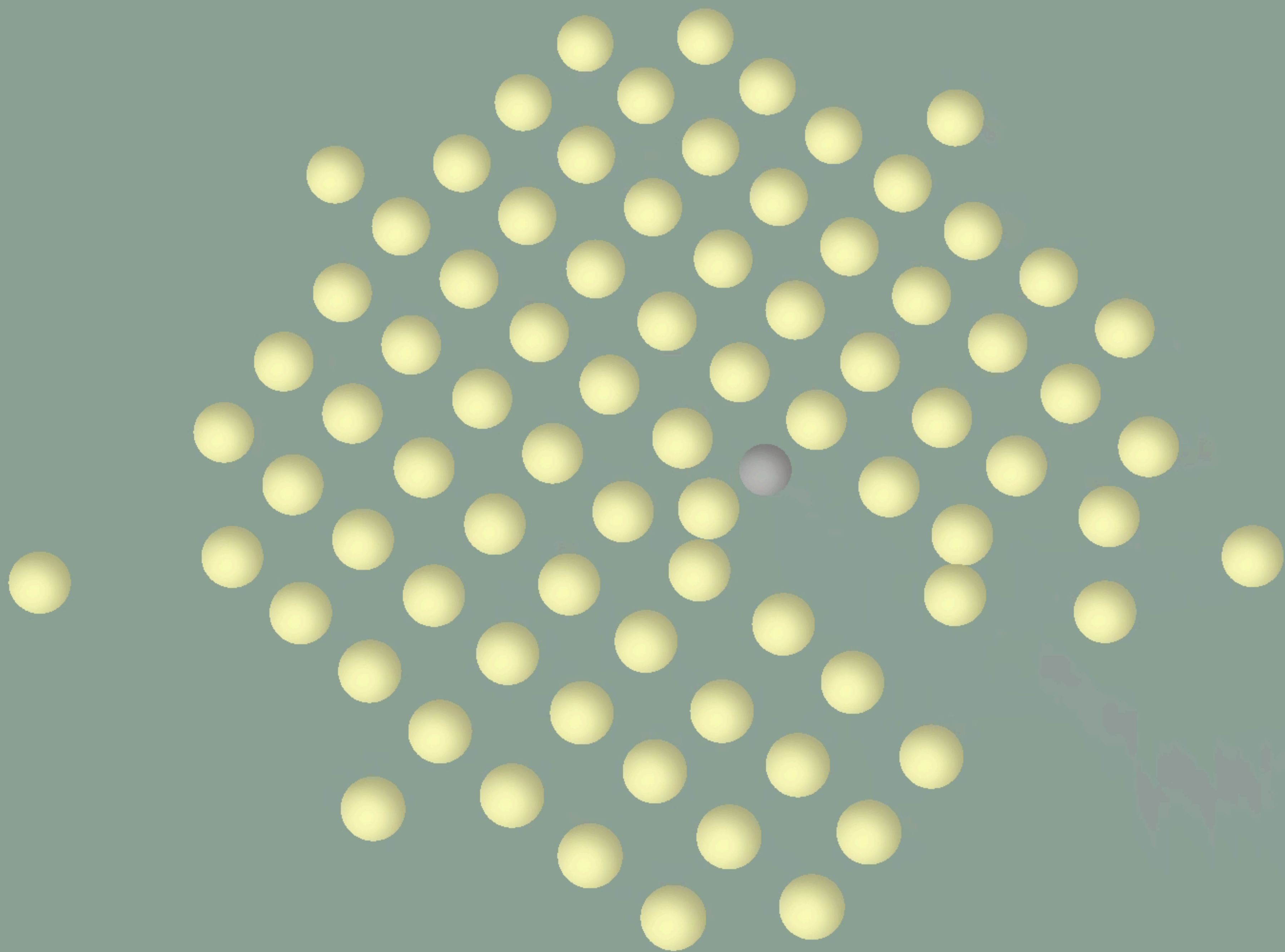
- Force model for collision is quadratic repulsion
- The force exerted on particle i by j :

$$f_c = -k_c \left(\left\| x_i - x_j \right\| - \frac{\lambda}{2} \right)^2 \frac{x_i - x_j}{\left\| x_i - x_j \right\|}$$

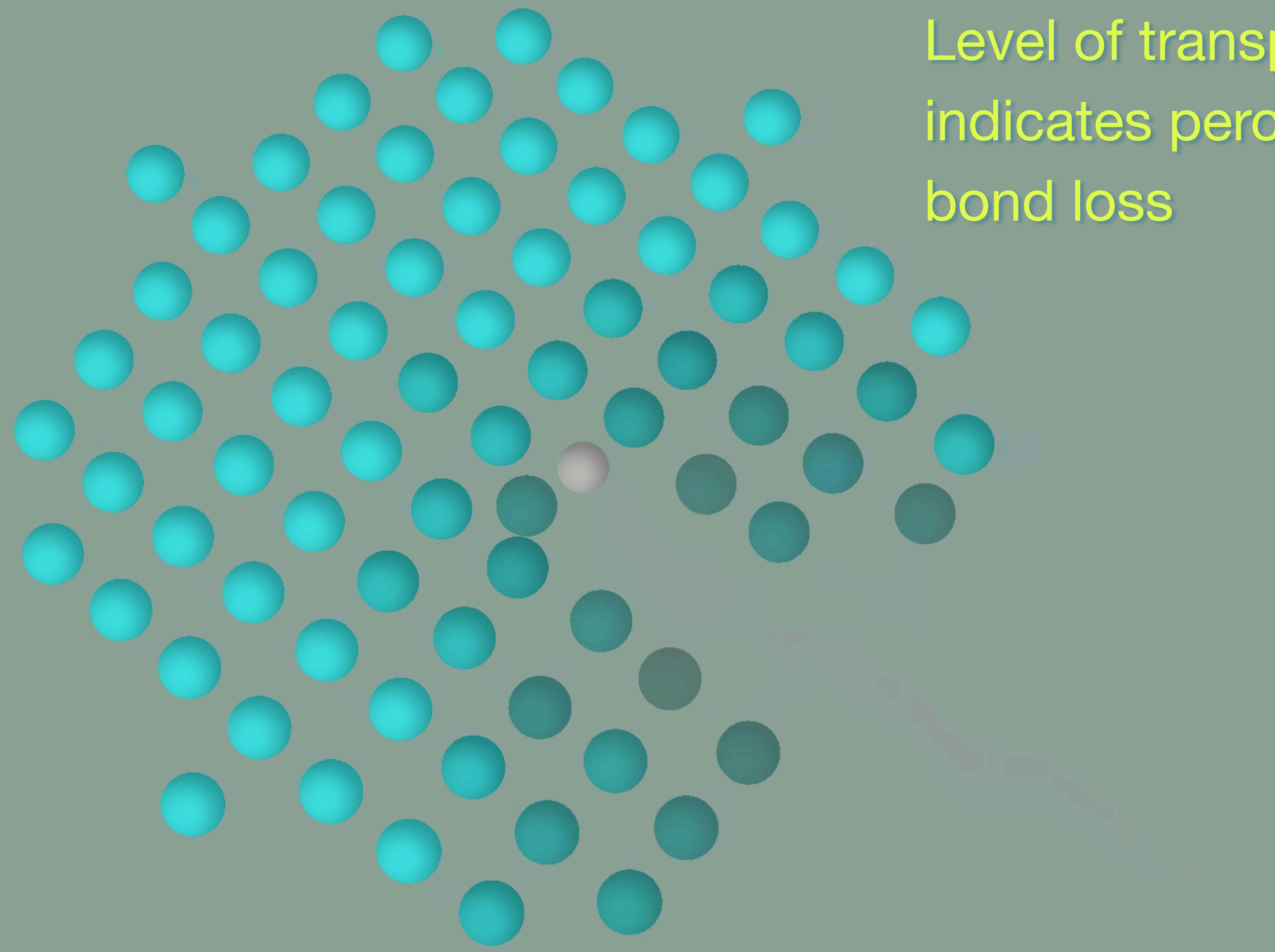
where k_c is a collision constant, e.g. 10^8 Pa

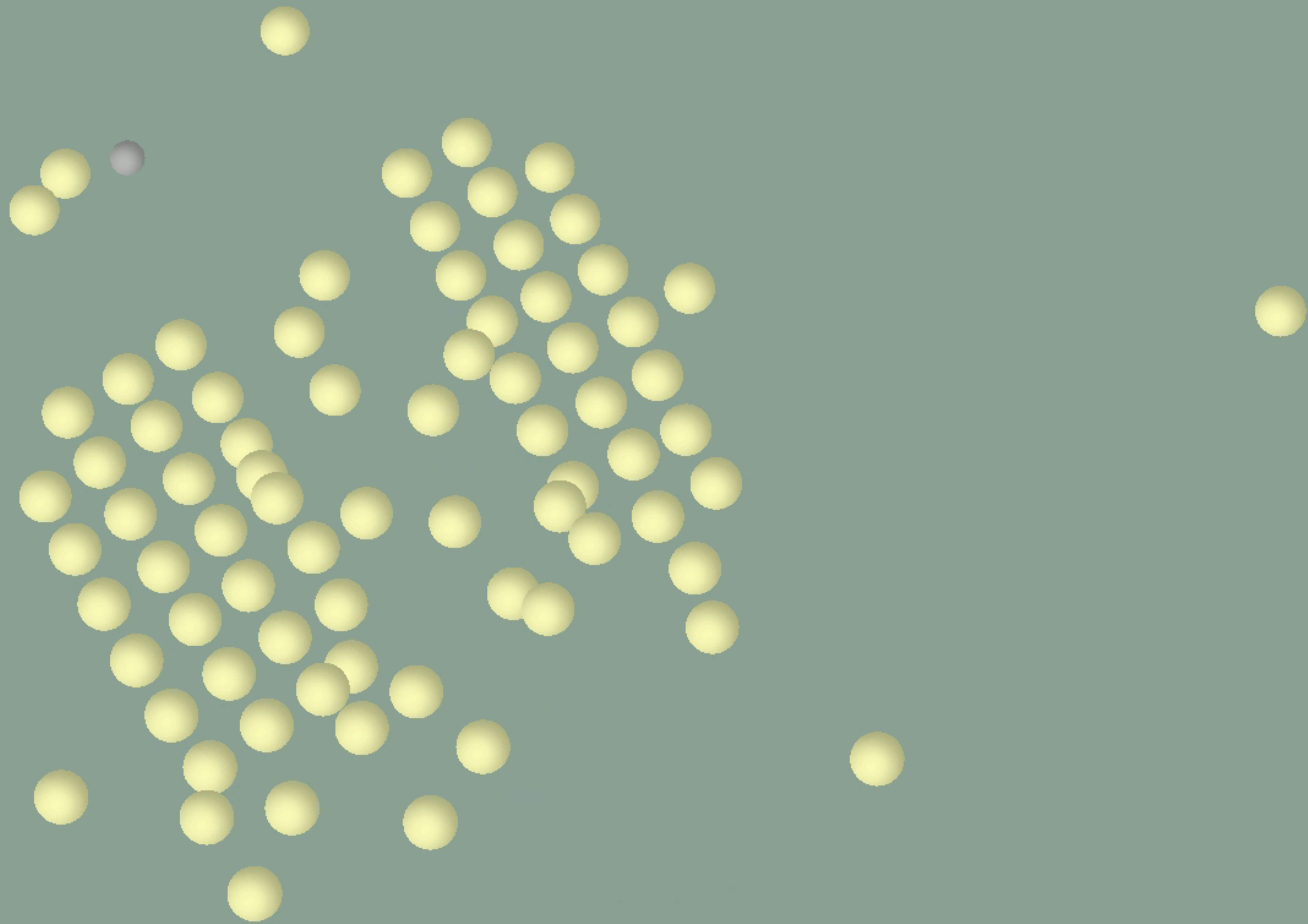
λ is a minimum bond distance

- Particles in same connected component don't collide
- Collision applied to particles at distance less than $\frac{\lambda}{2}$

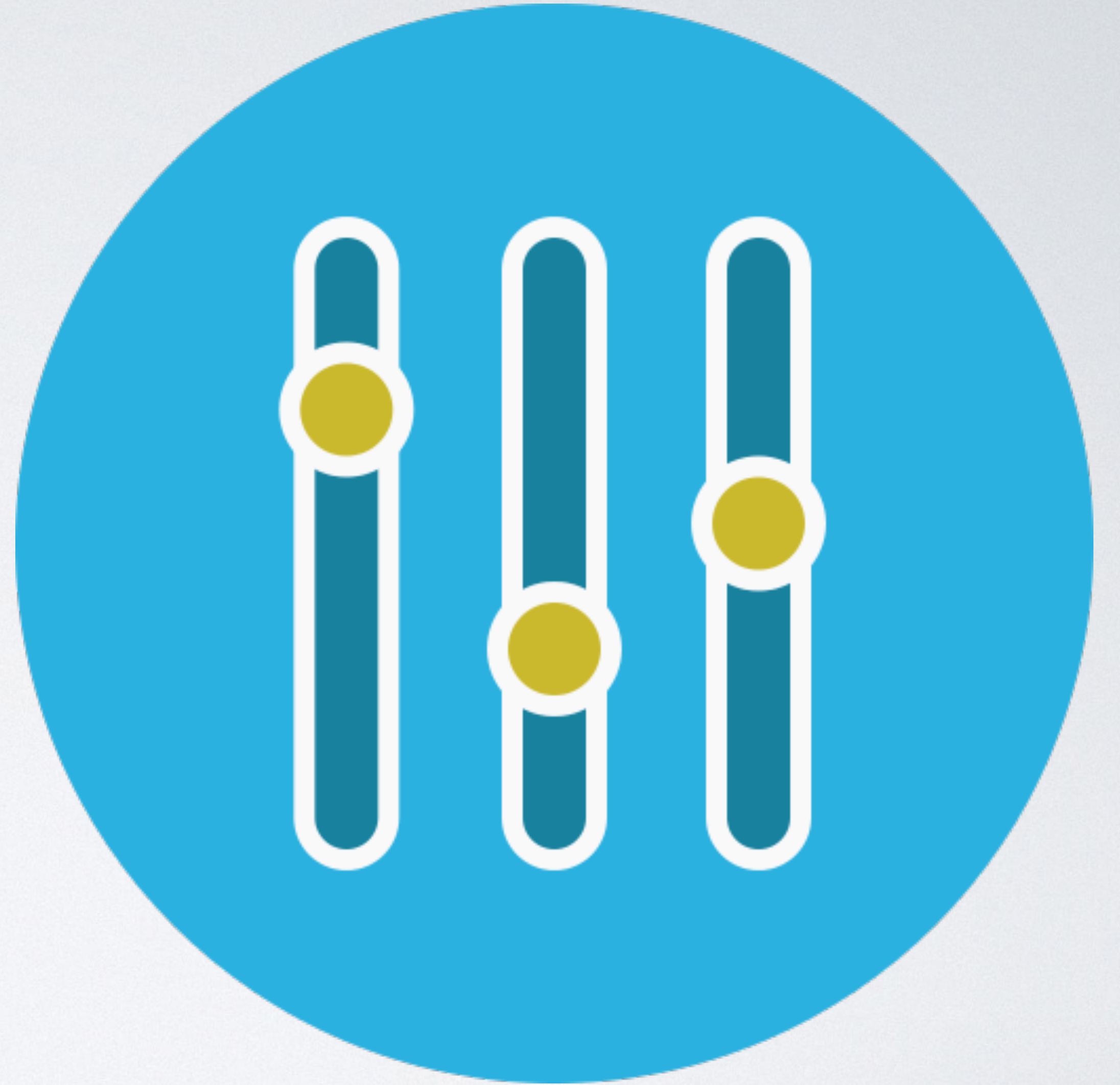


Level of transparency
indicates percentage of
bond loss





Peridynamic Parameters



Peridynamic Parameters

- A peridynamic spring constant k_s is given by

$$k_s = \frac{18K}{\pi\delta^4}$$

- ♦ K is a bulk modulus of the material
 - ♦ e.g. 35 GPa for glass, 160 GPa for steel

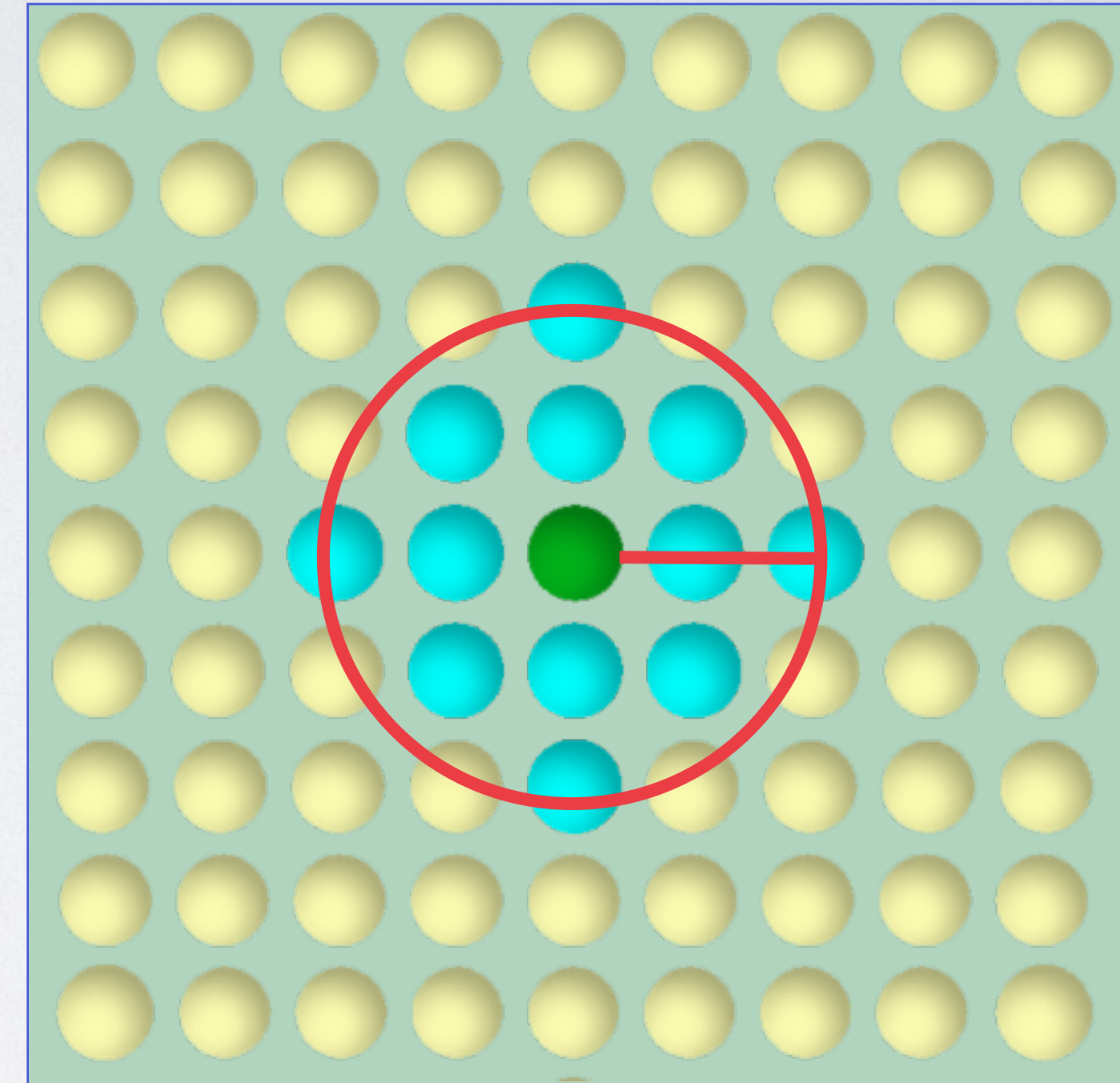
Peridynamic Parameters

$$\delta = 2\lambda$$

- A peridynamic spring constant k_s is given by

$$k_s = \frac{18K}{\pi\delta^4} = \frac{18K}{\pi(N\lambda)^4}$$

- ♦ K is a bulk modulus of the material
 - ♦ e.g. 35 GPa for glass, 160 GPa for steel
- ♦ N is a scaling integer, typically a value between 2 and 6
- ♦ λ is a minimum bond distance



Peridynamic Parameters

- A strain limit τ is given by¹

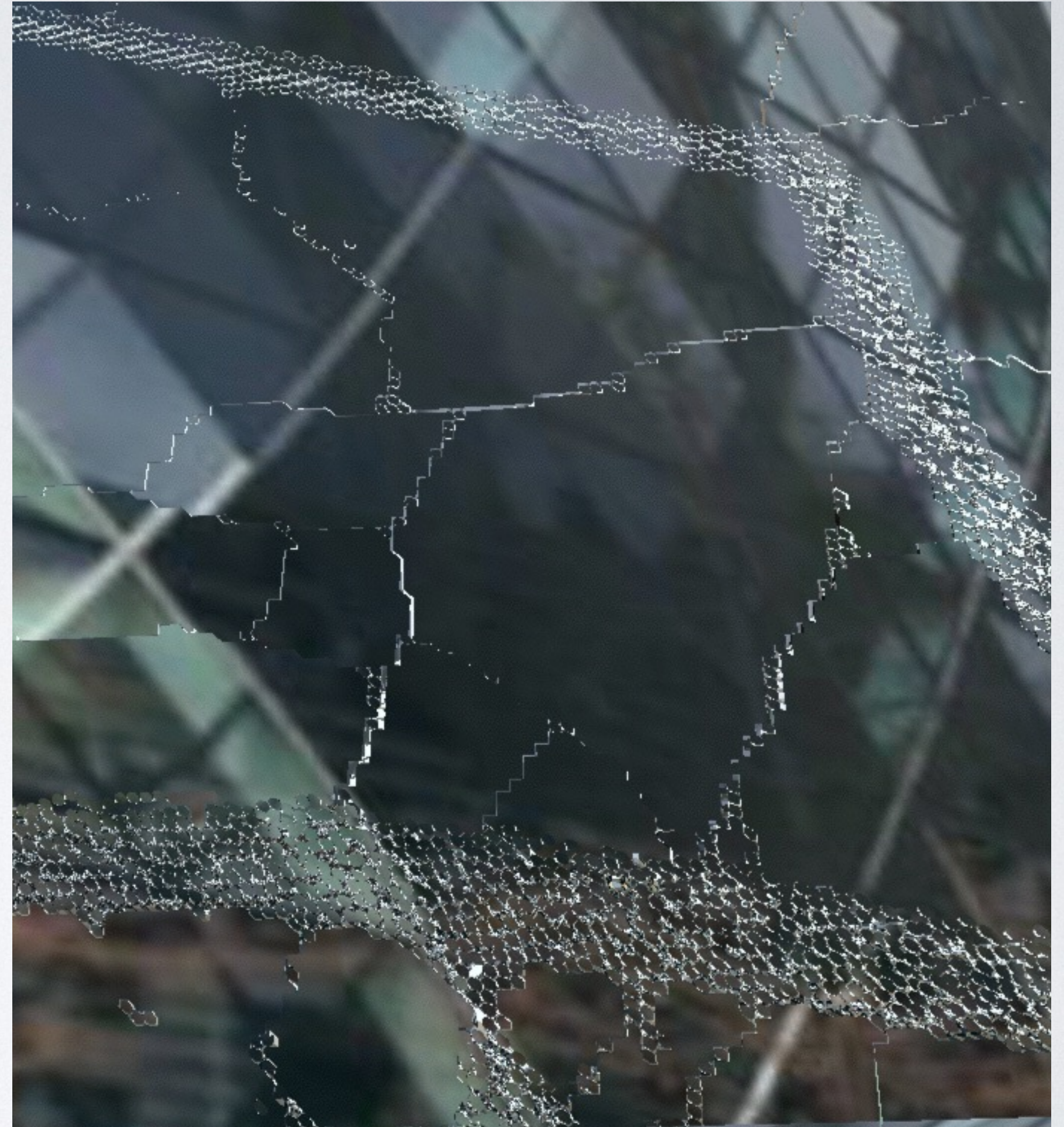
$$\tau = \sqrt{\frac{5G}{K\delta}} = \sqrt{\frac{5G}{K(N\lambda)}}$$

- G is the fracture energy of the material
- We also allow a user to give a specific value to it.

¹ Silling S., Askari E.: Peridynamic modeling of impact damage. In *ASME Conference Proceedings* (2004), pp. 197–205.

Tool Design

Visual Exploration Tool

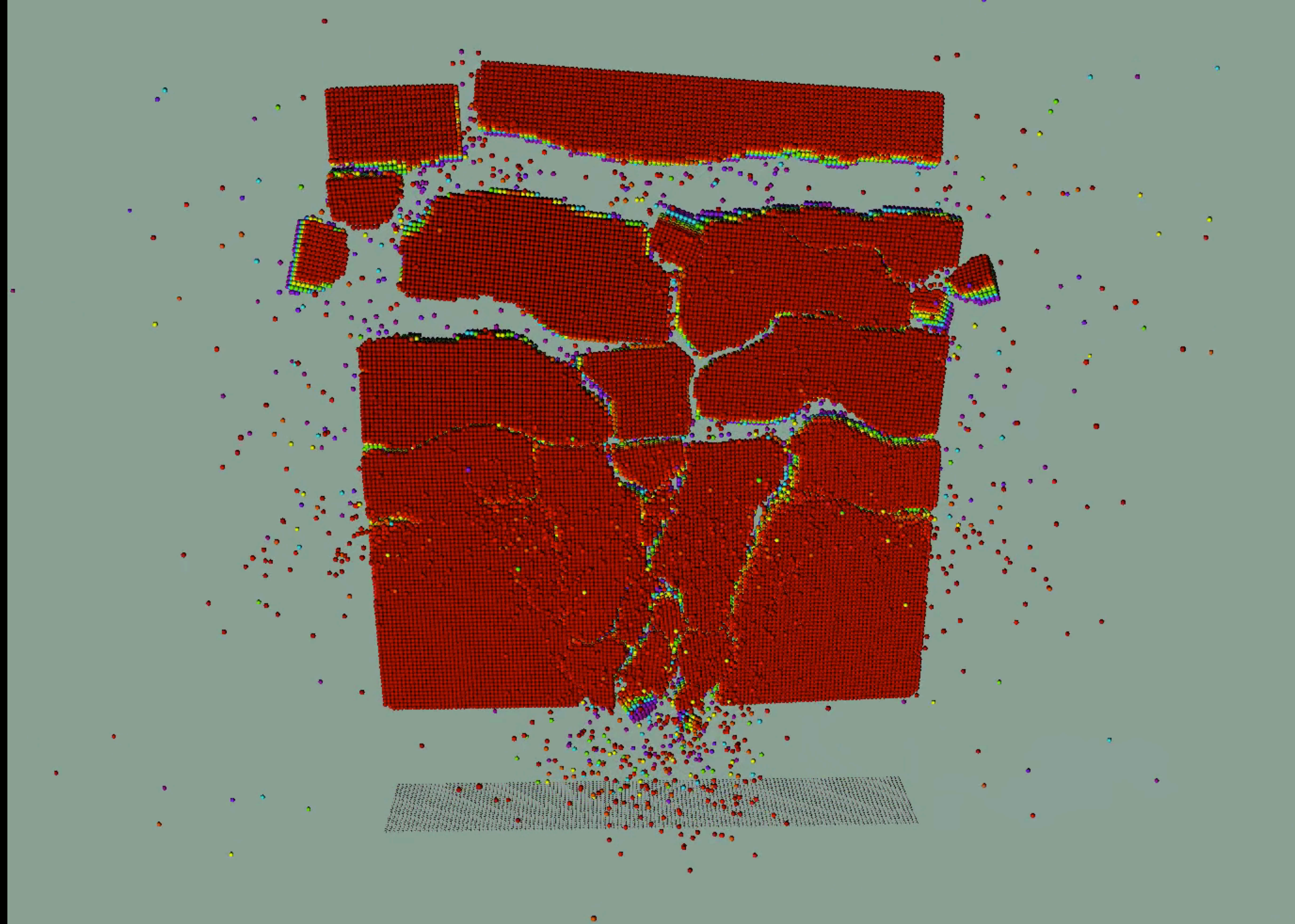


Visual Exploration Tool

- Simulation takes many small time steps to compute
 - ♦ considerably small time step, e.g. 120 ns
- Record simulation data on the disk for later manipulation
- Rapid development with Python
 - ♦ using PyOpenGL with GLSL for display
 - ♦ using PyCUDA for intensive calculation

Overview:

spectral colors
forward
backward
pause
step through
resume



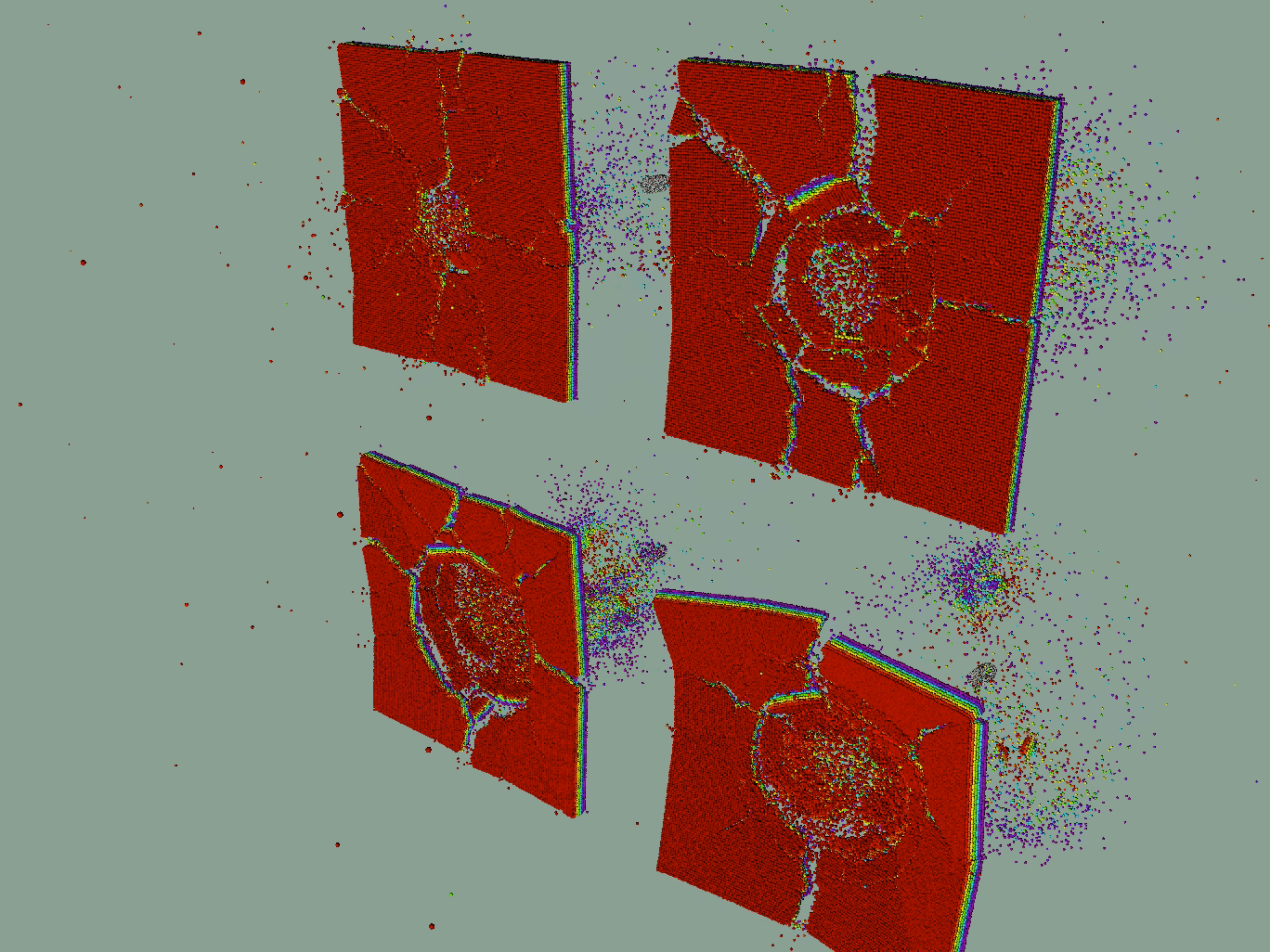
clock = 71500 steps_per_render: 500

18254.39 fps

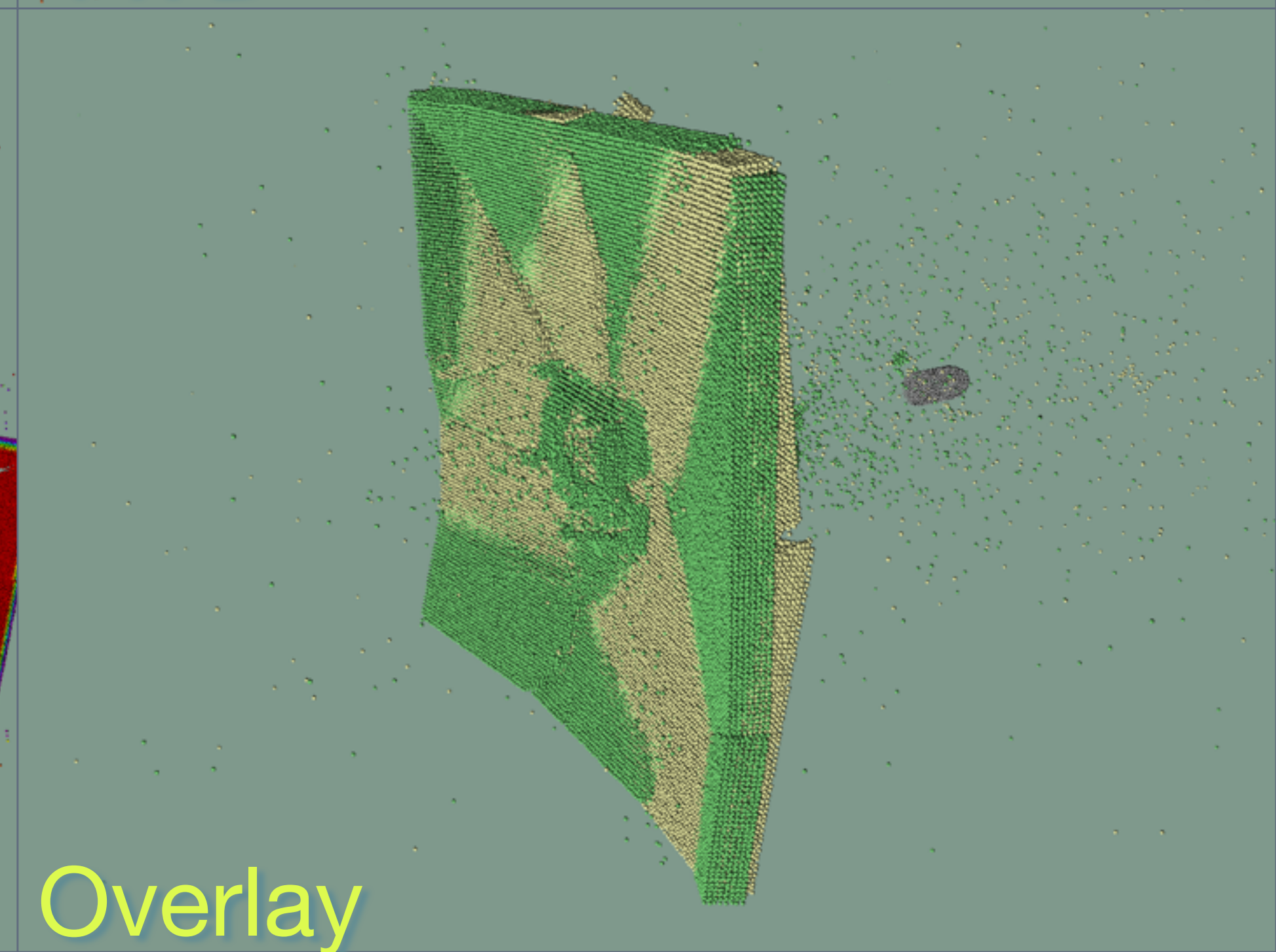
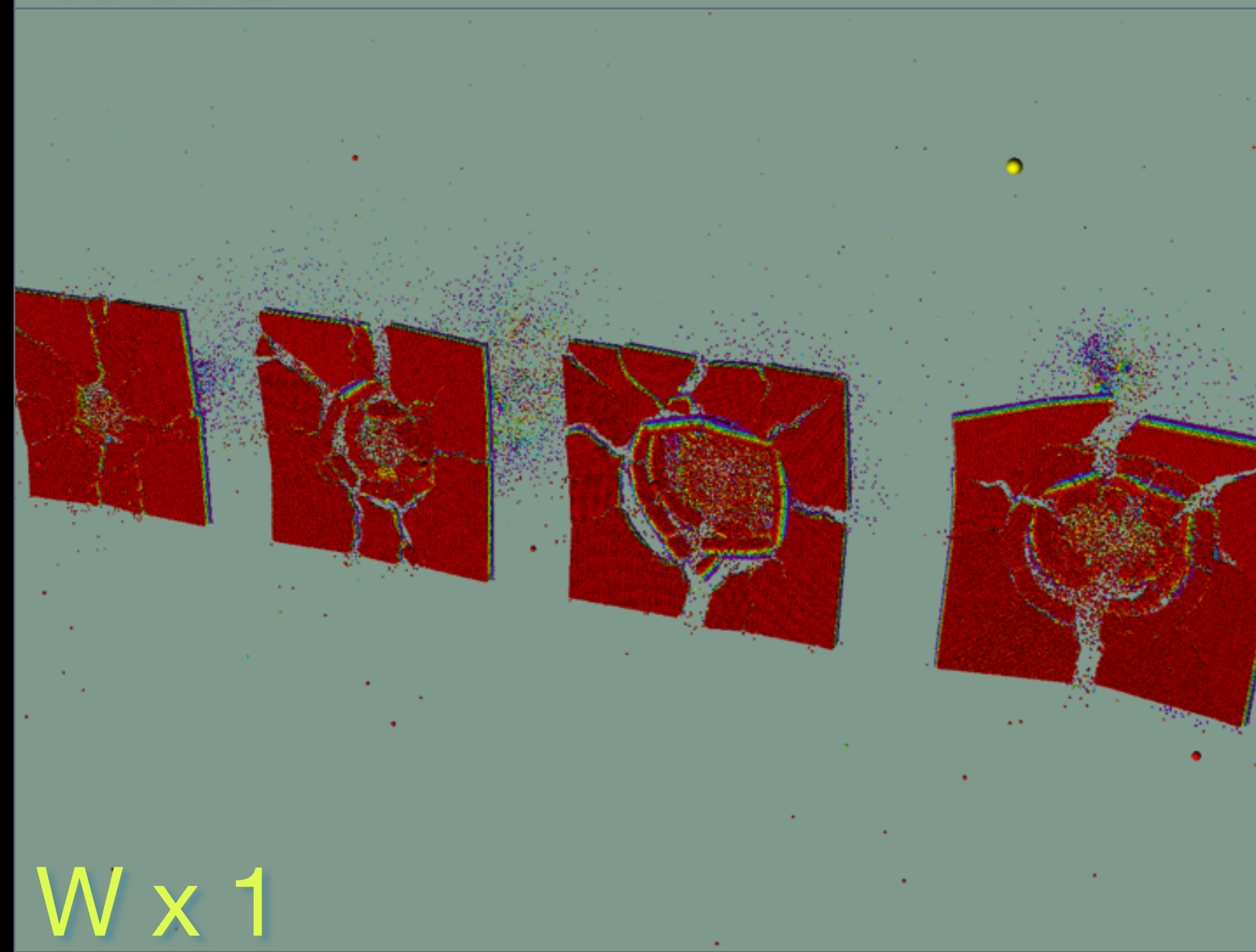
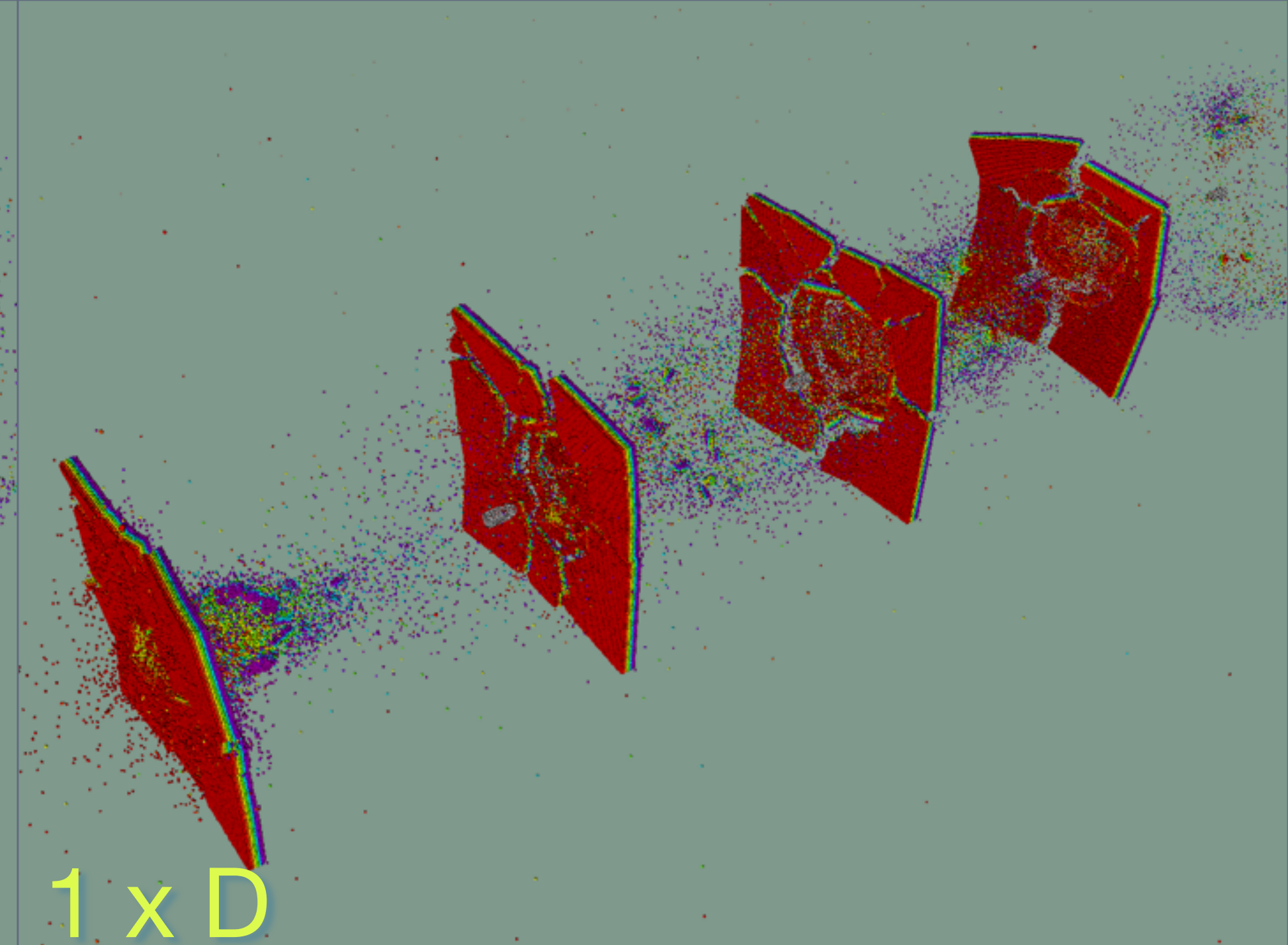
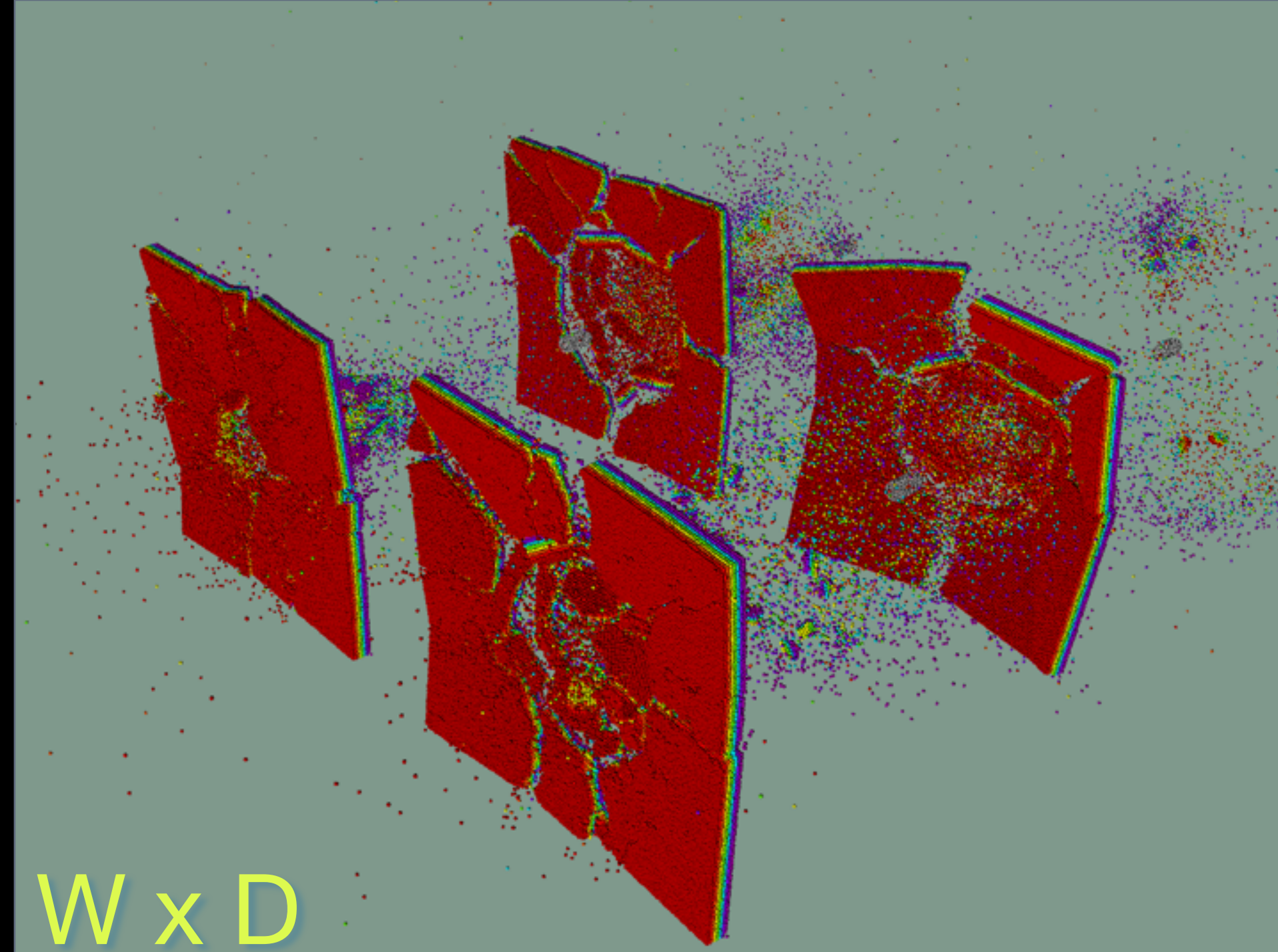
Single World:

Show multiple
simulation runs
simultaneously
in same space

Front Layout

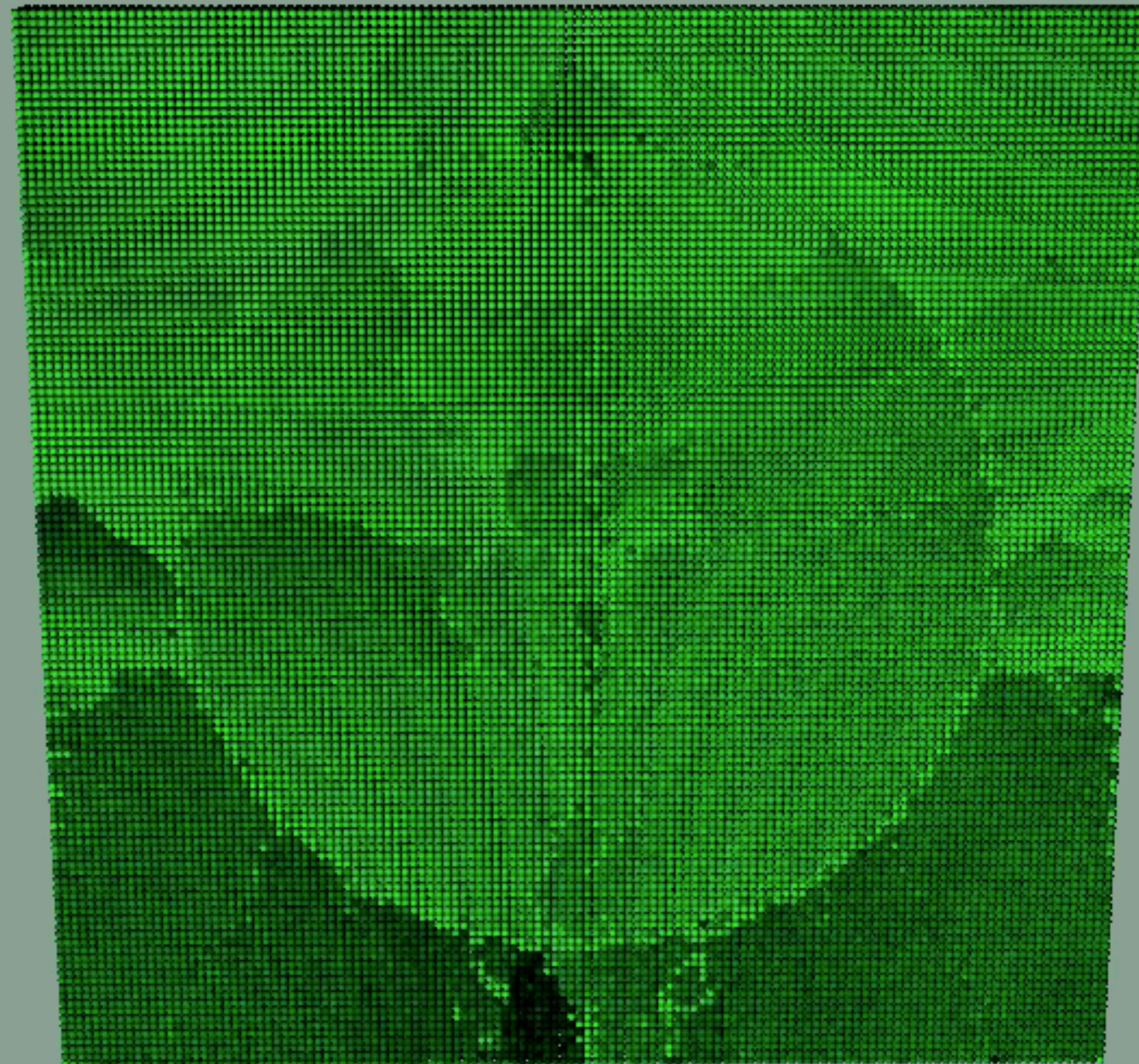


Single World: Other Layouts

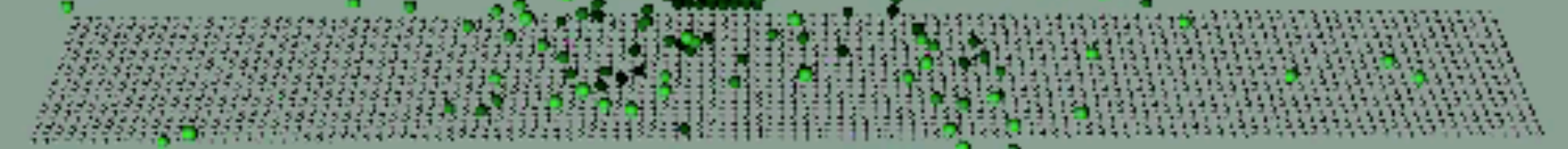


Particle Colors

Visualizing
magnitude of
particle velocity



clock = 76000 part_sprite_size: 0.0100

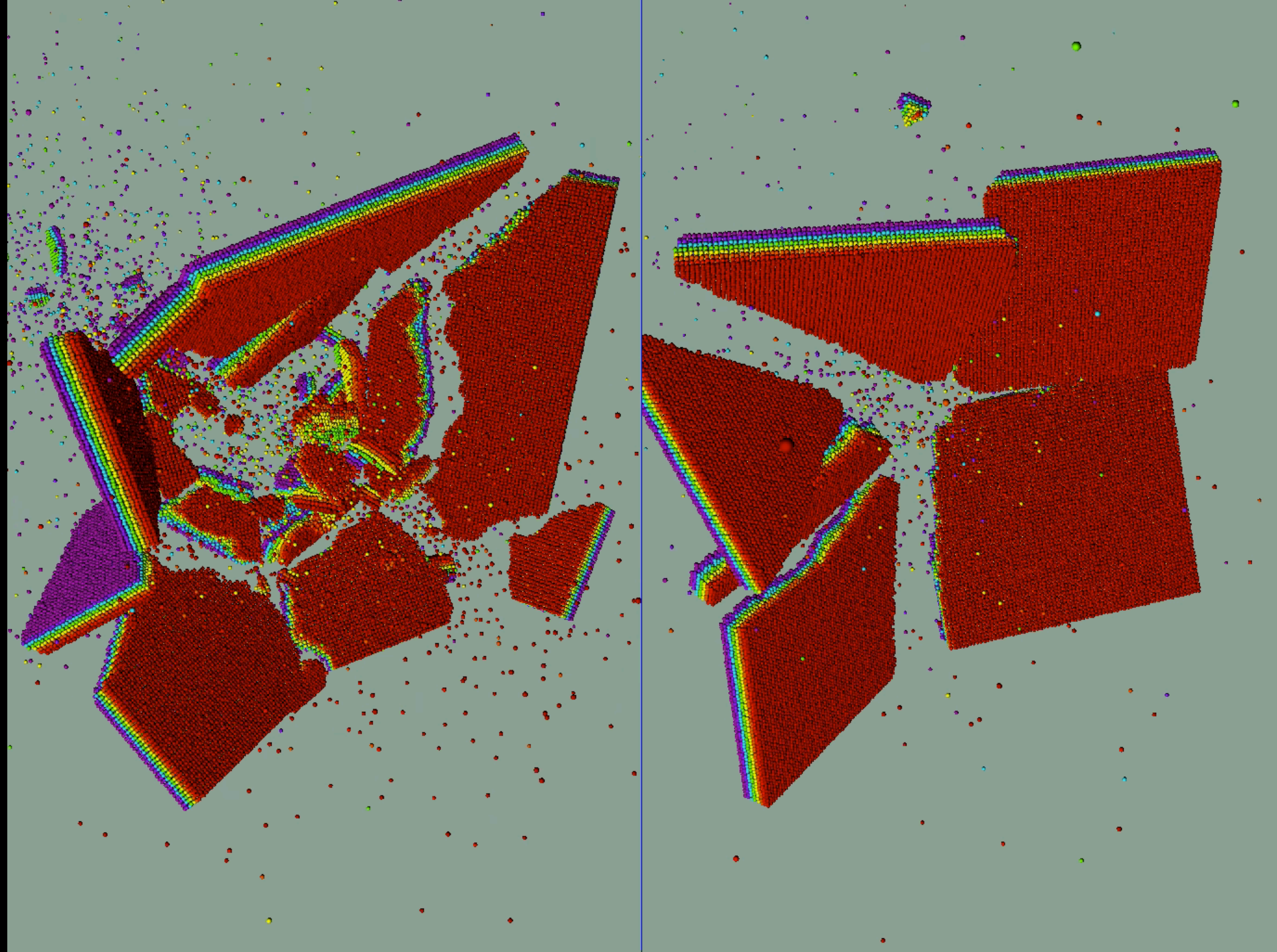


Freeze Multi-Viewport LColVis: 1 RColVis: 1

5.65 fps

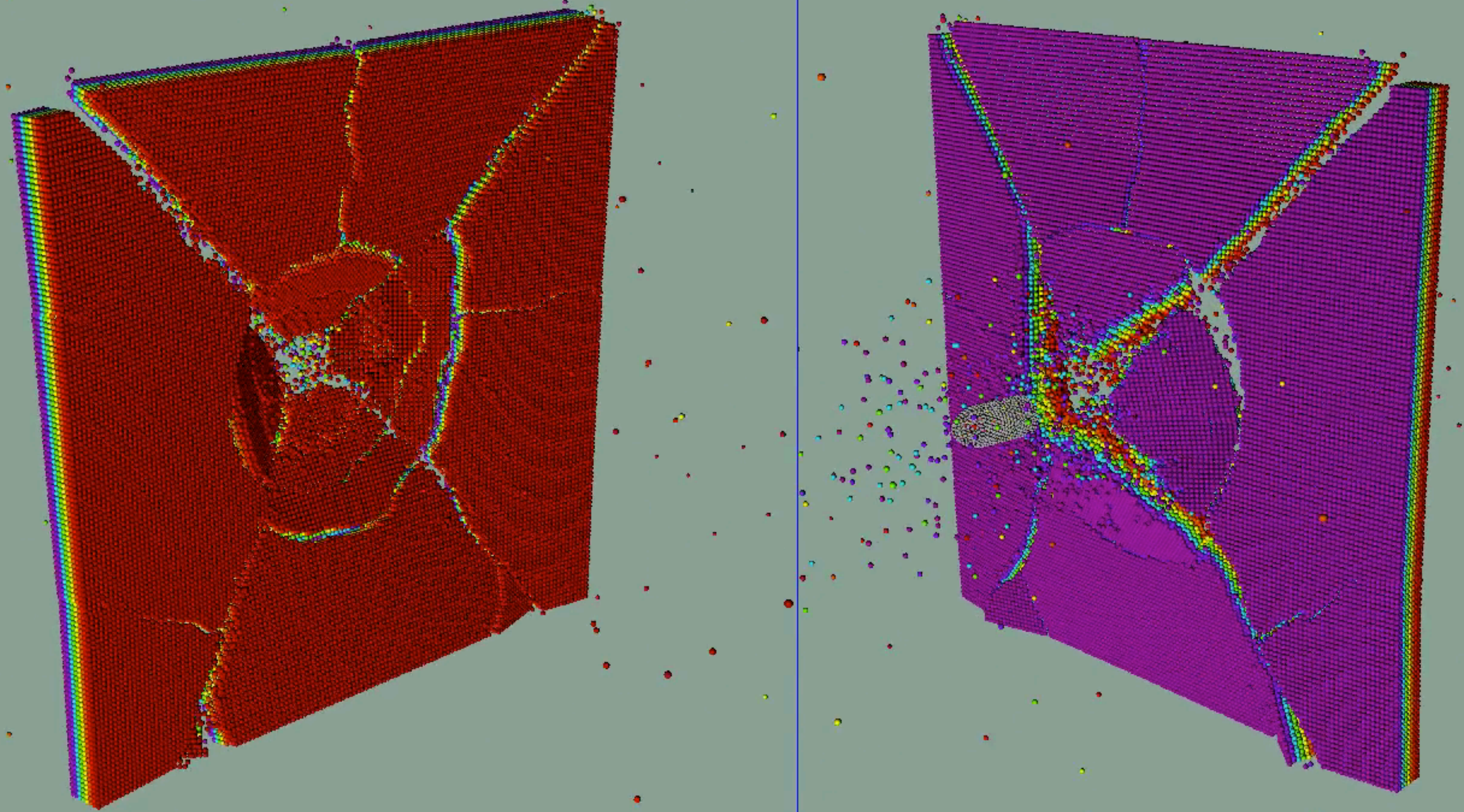
Multi-Viewport:

Side by side
comparison



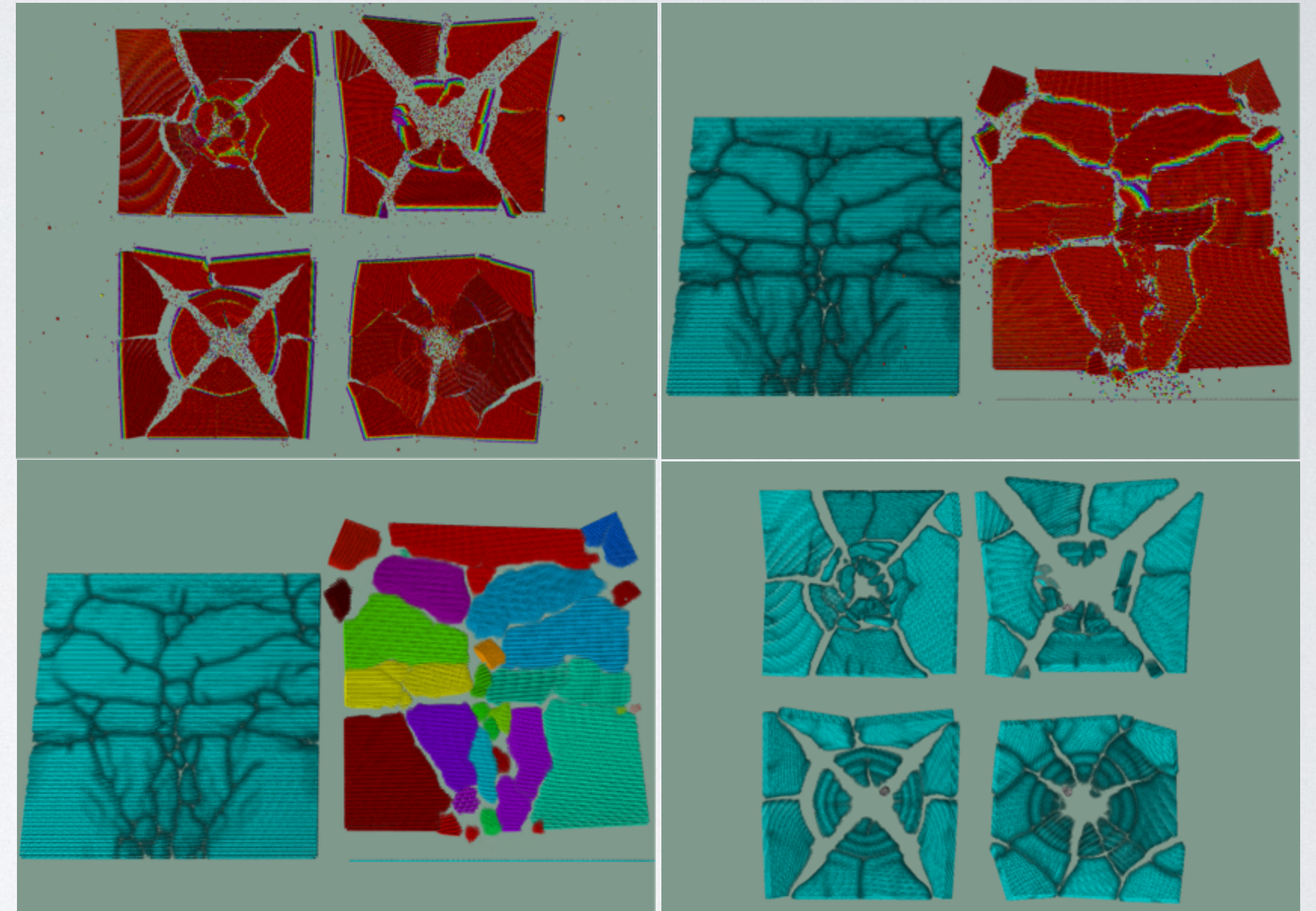
Multi-View:

Show impacts at
front and back
simultaneously



Visualizing The Simulation

The “Results” of The Tool



Parameter N:
varying from
4 to 6

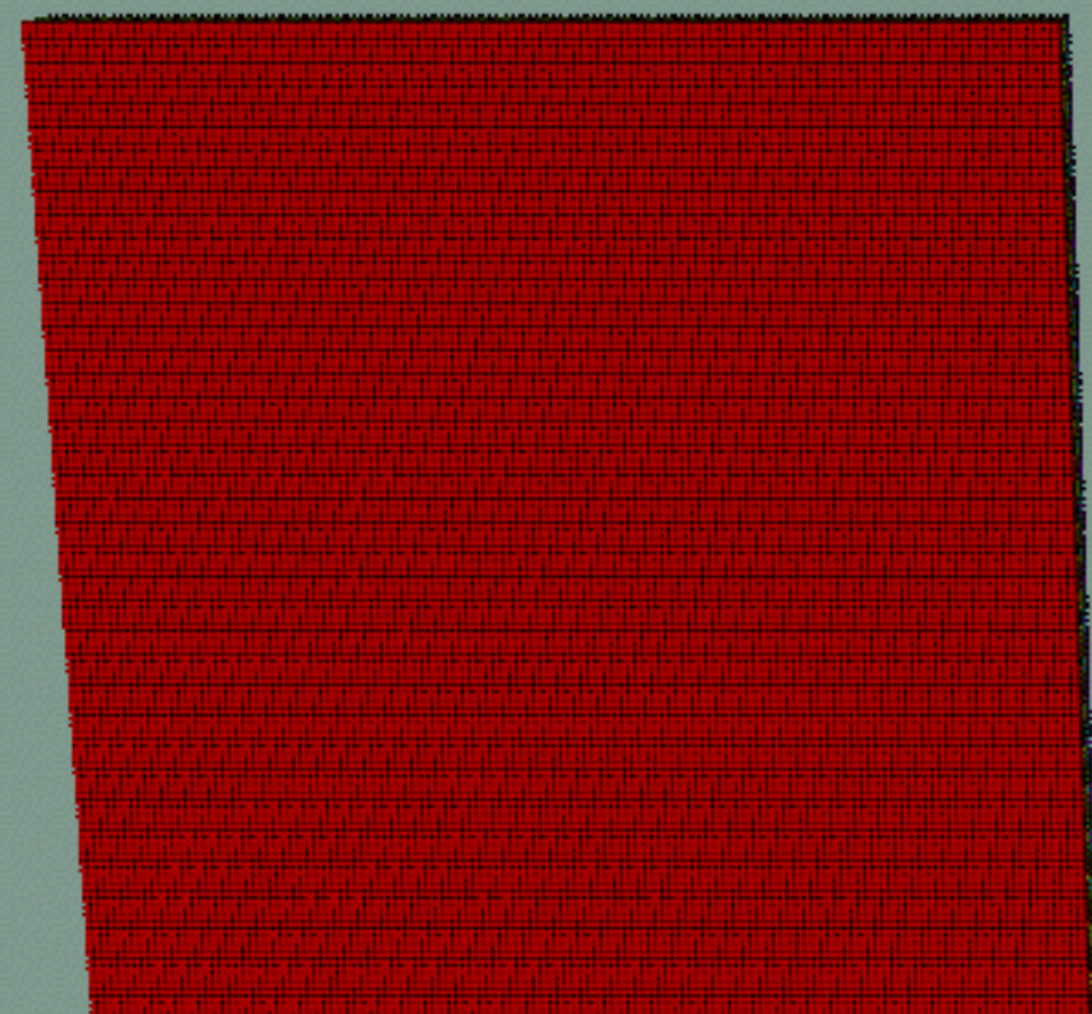
No. of particles
 $131,072 + 3,072$

$K = 35$ GPa

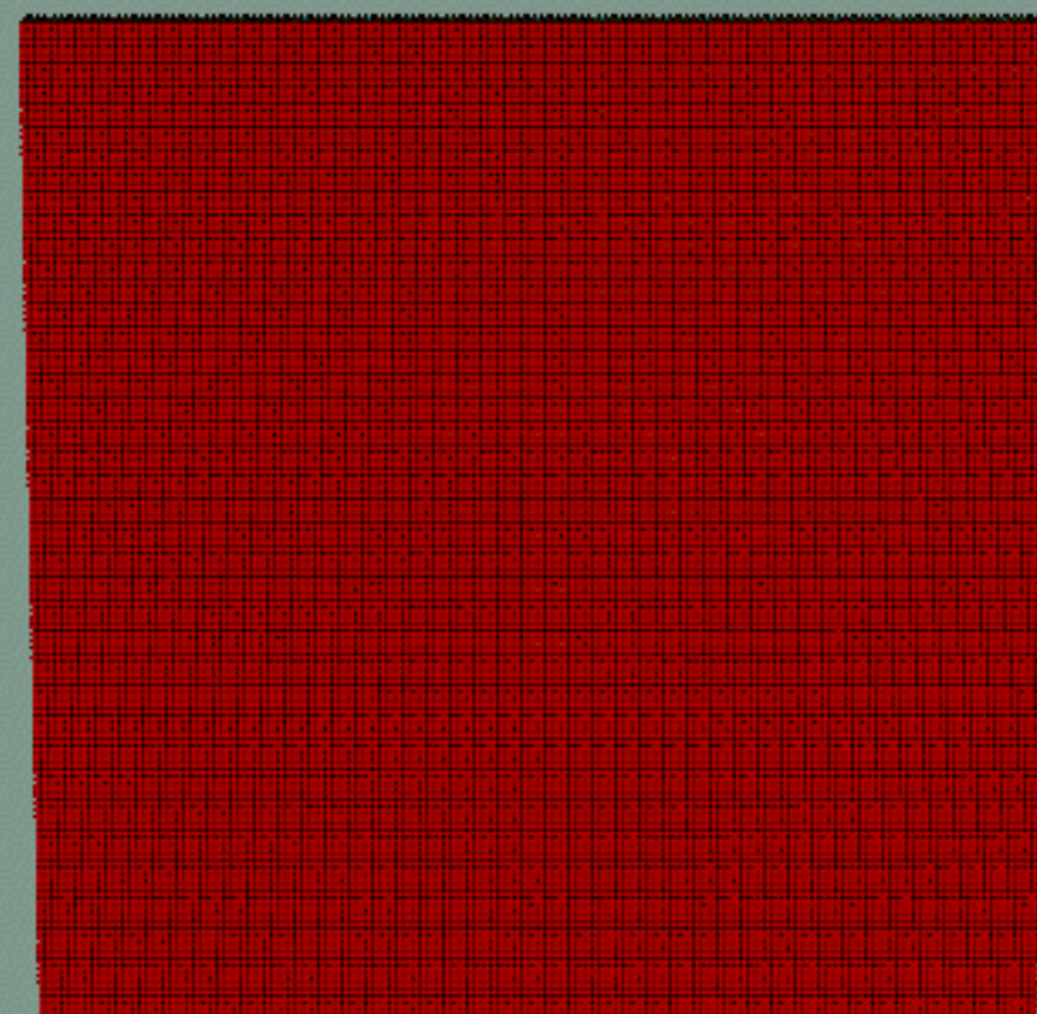
$k_{C:g-g} = 0.1$ GPa

$k_{C:f-g} = 10$ GPa

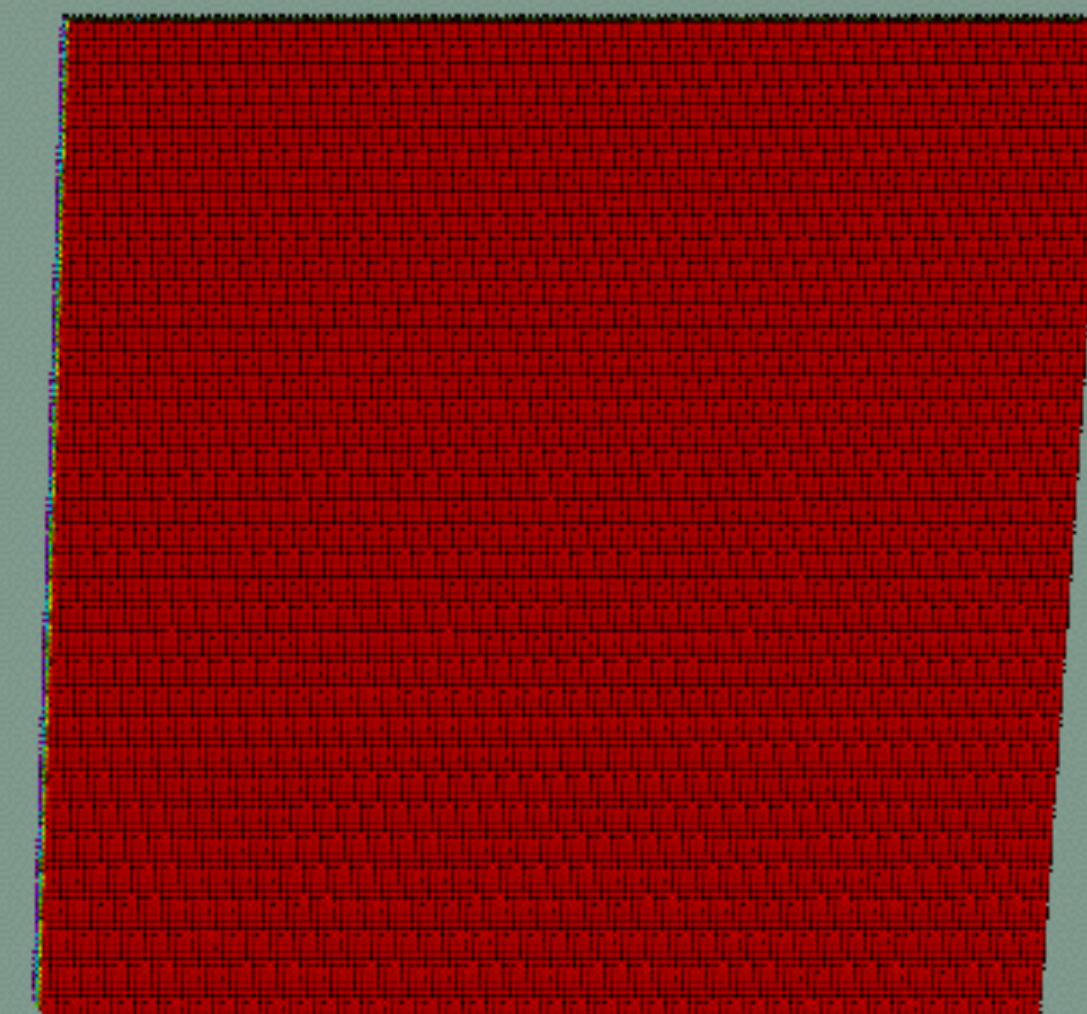
$\tau = 0.005$



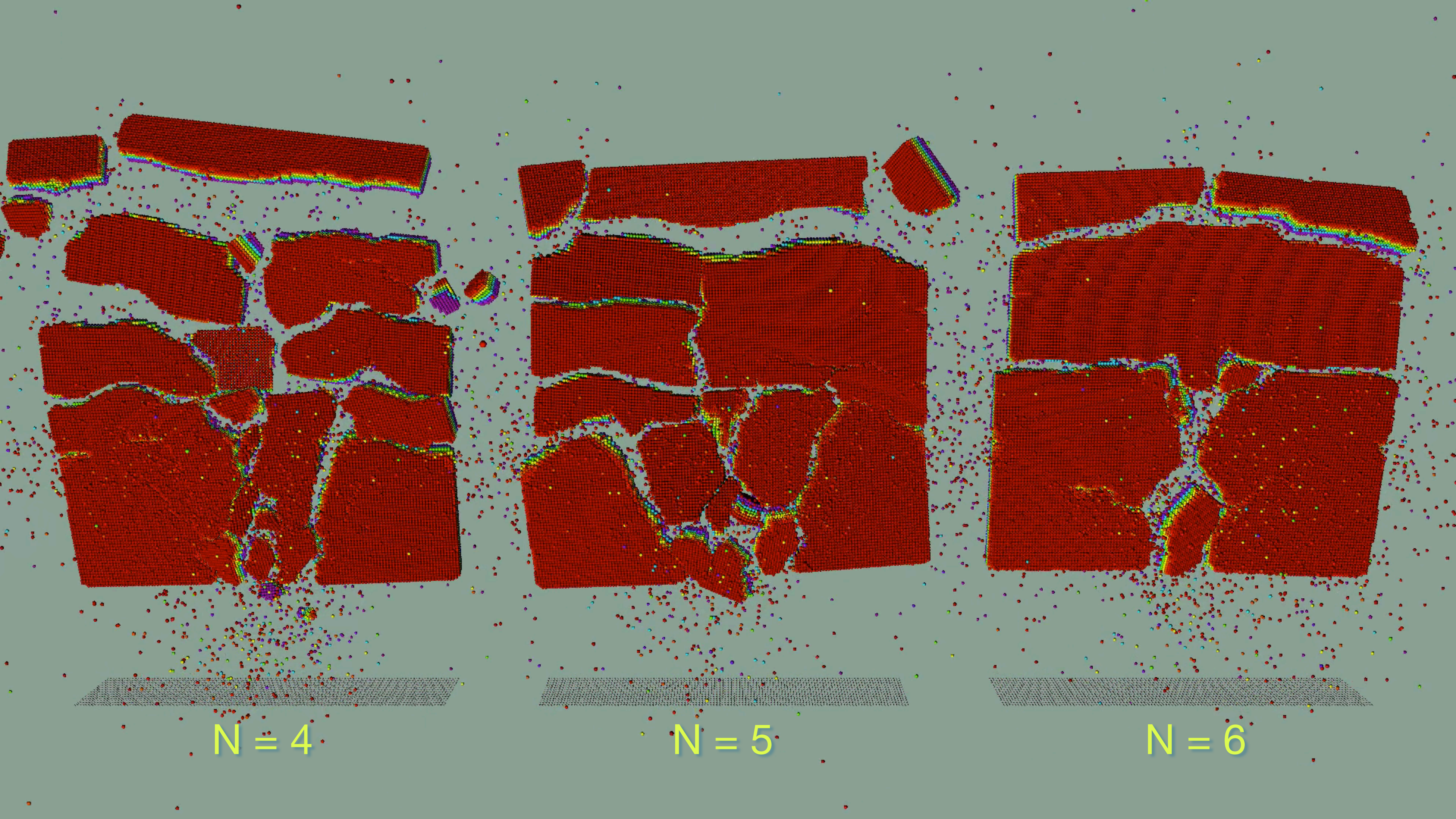
$N = 4$
maxbonds = 255



$N = 5$
maxbonds = 483



$N = 6$
maxbonds = 779



Parameter κ , τ :

No. of particles
131,072 + 1,093

$N = 3$

maxbonds = 117

$k_{c:g-g} = 0.1 \text{ GPa}$

$k_{c:b-g} = 10 \text{ GPa}$

$\kappa = 35 \text{ GPa}$
 $\tau = 0.0050$



$\kappa = 70 \text{ GPa}$
 $\tau = 0.0050$



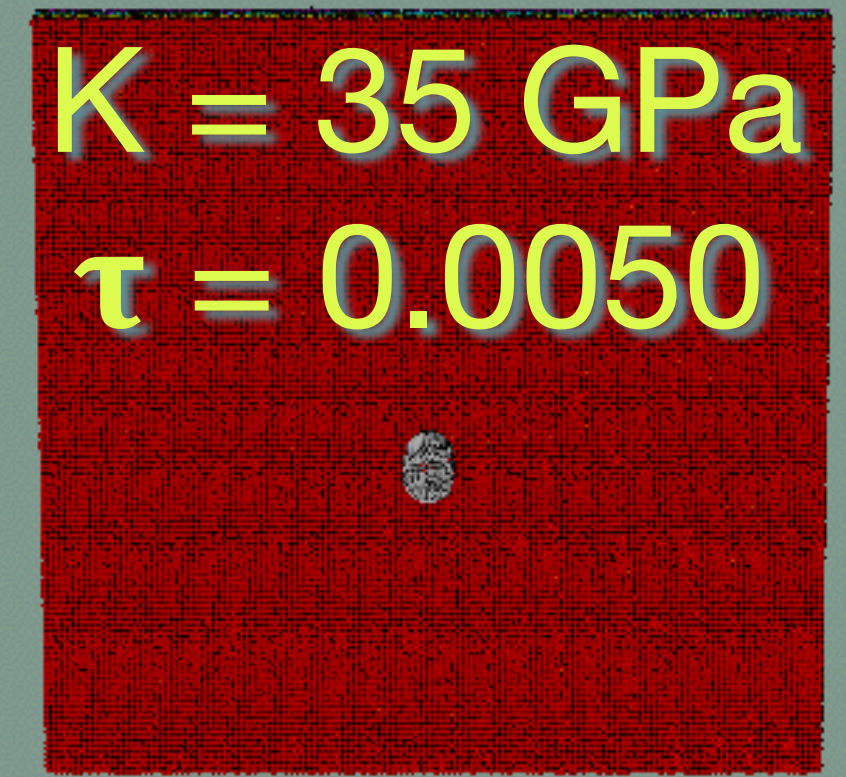
$\kappa = 140 \text{ GPa}$
 $\tau = 0.0050$



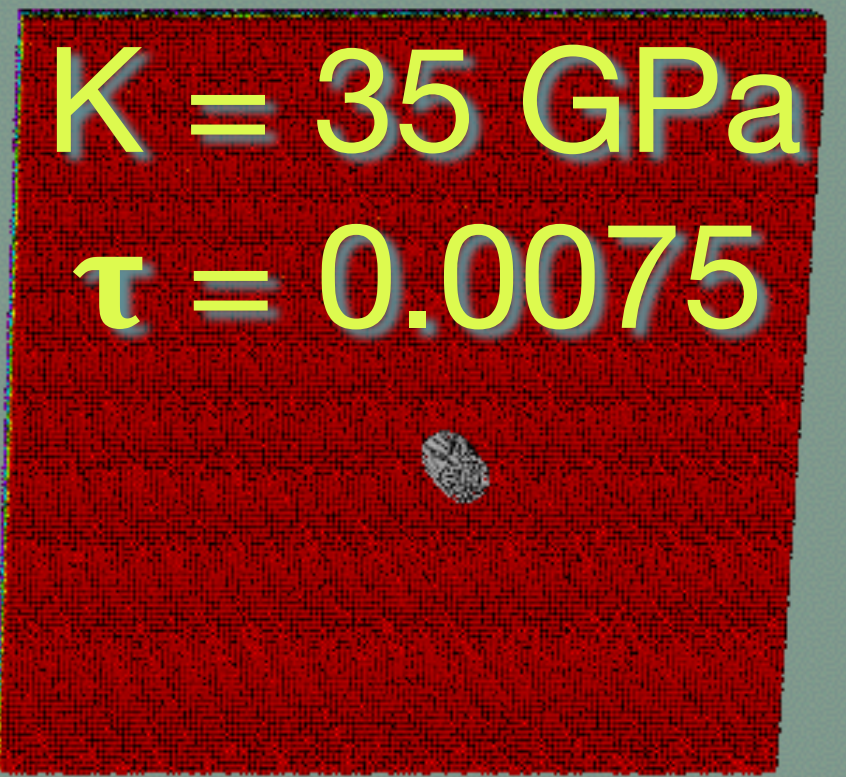
$\kappa = 35 \text{ GPa}$
 $\tau = 0.0025$

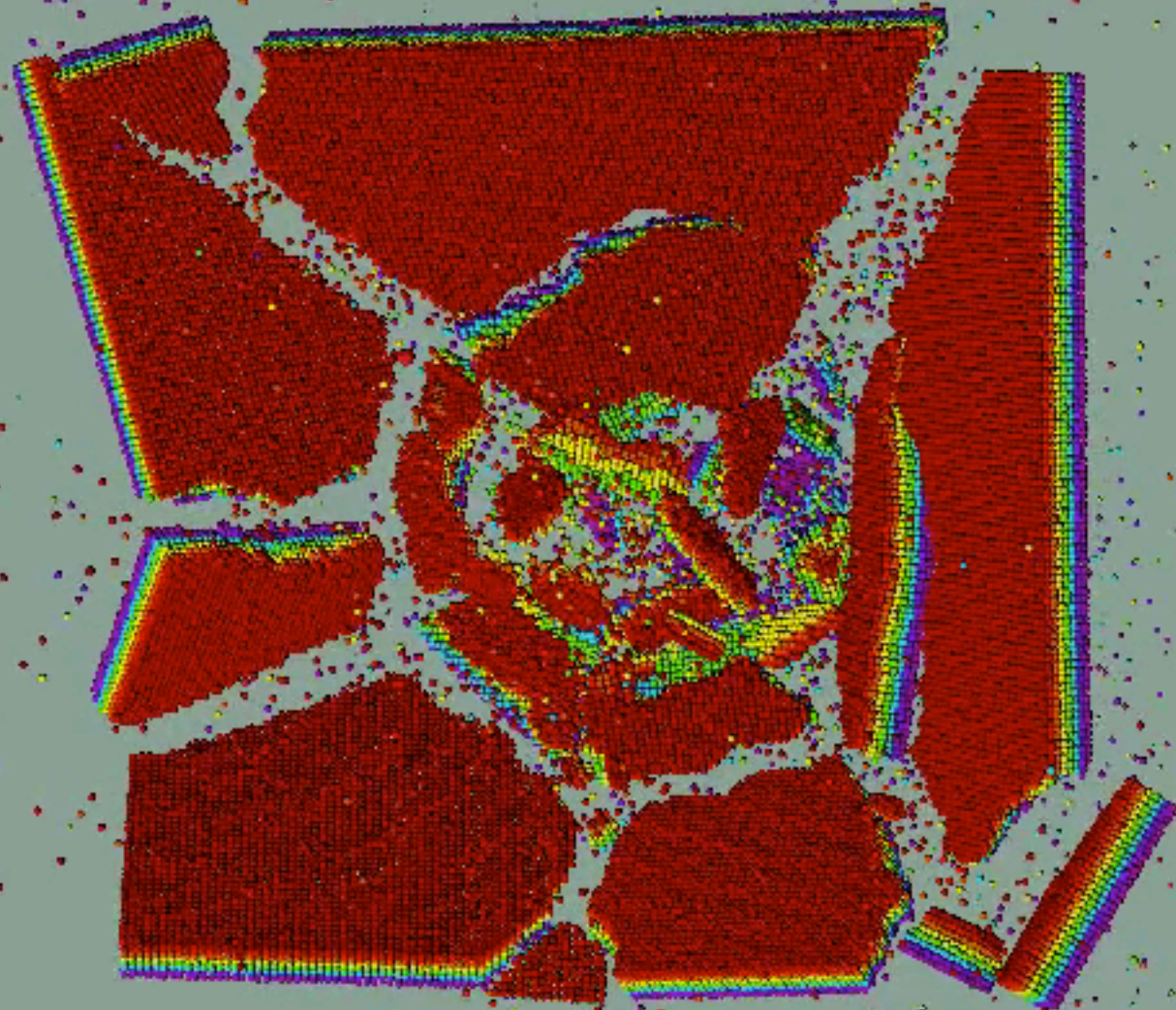


$\kappa = 35 \text{ GPa}$
 $\tau = 0.0050$

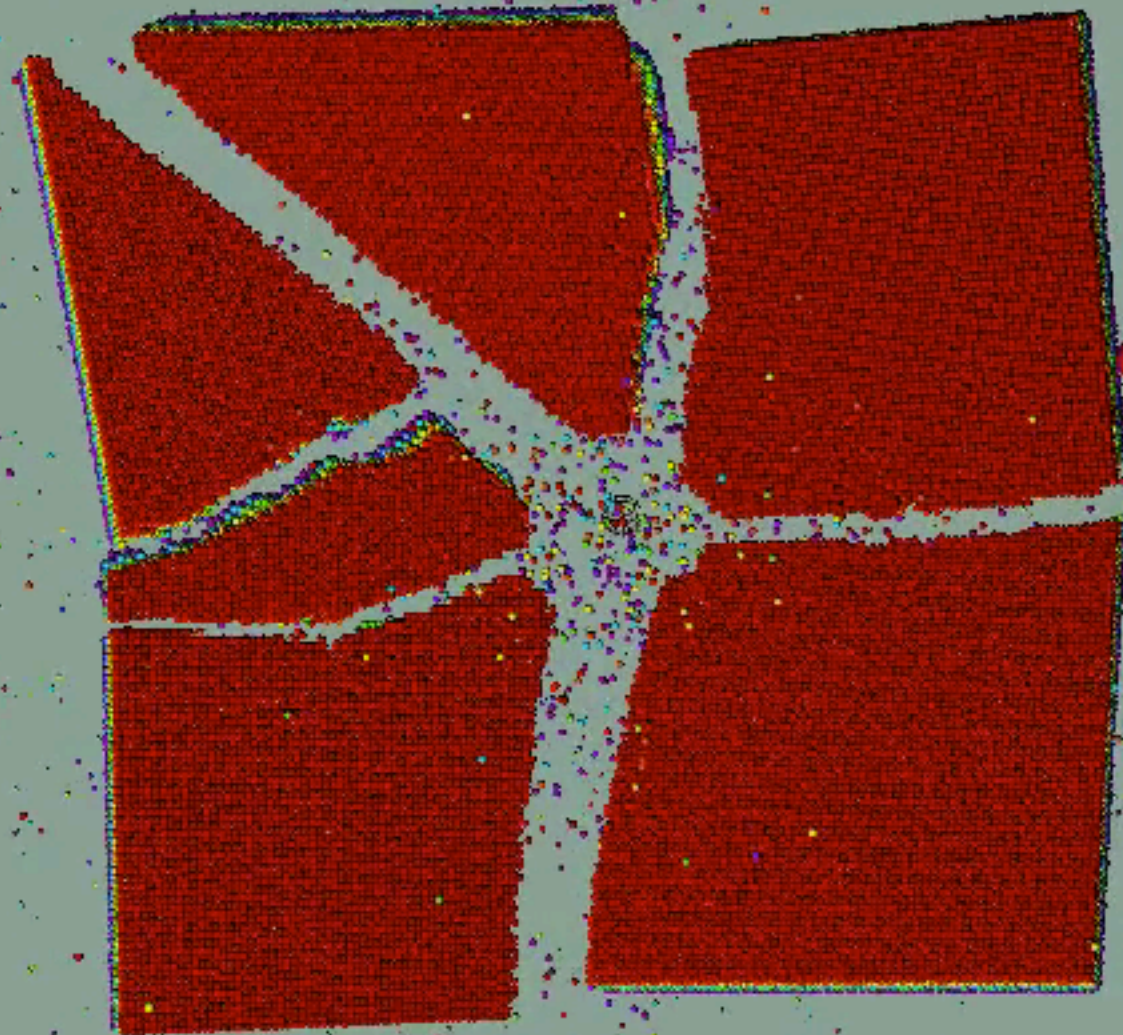


$\kappa = 35 \text{ GPa}$
 $\tau = 0.0075$

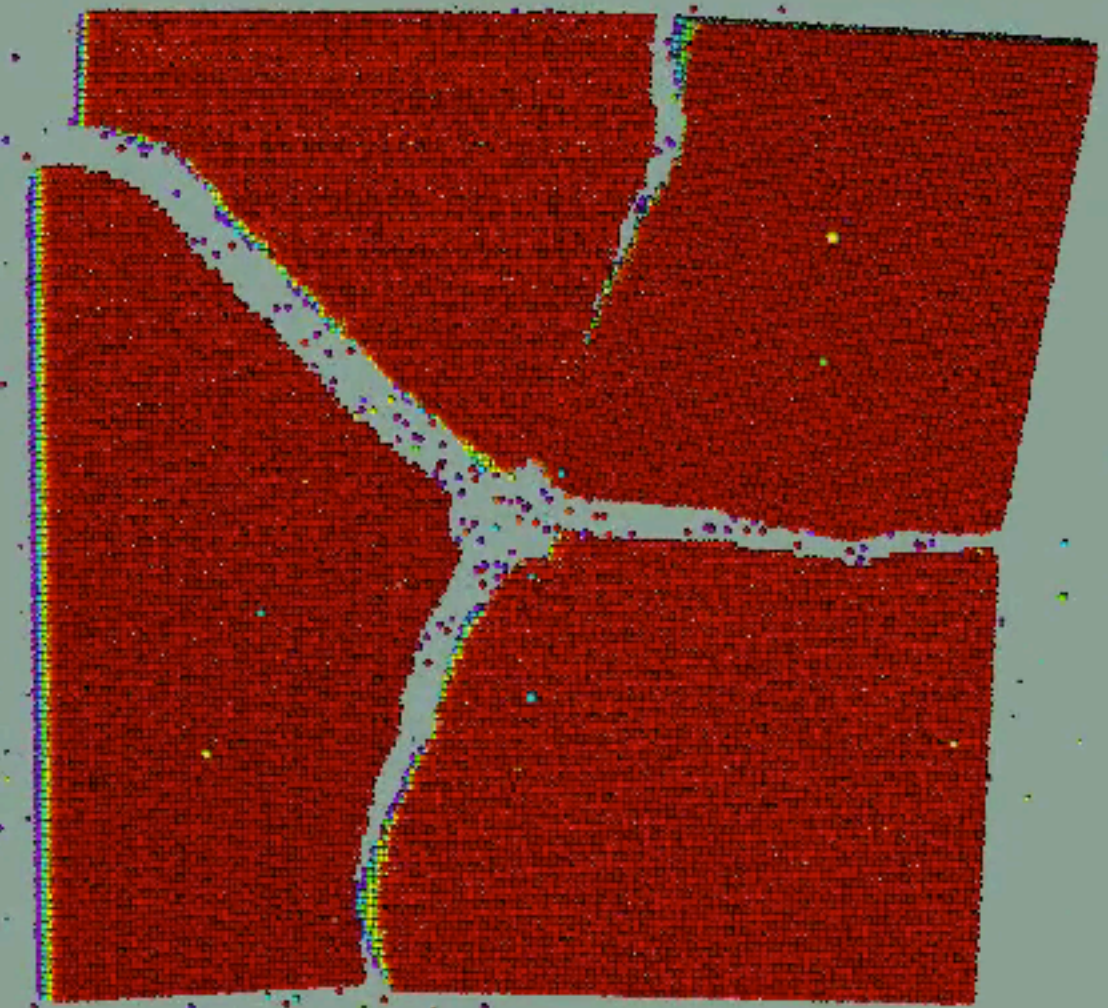




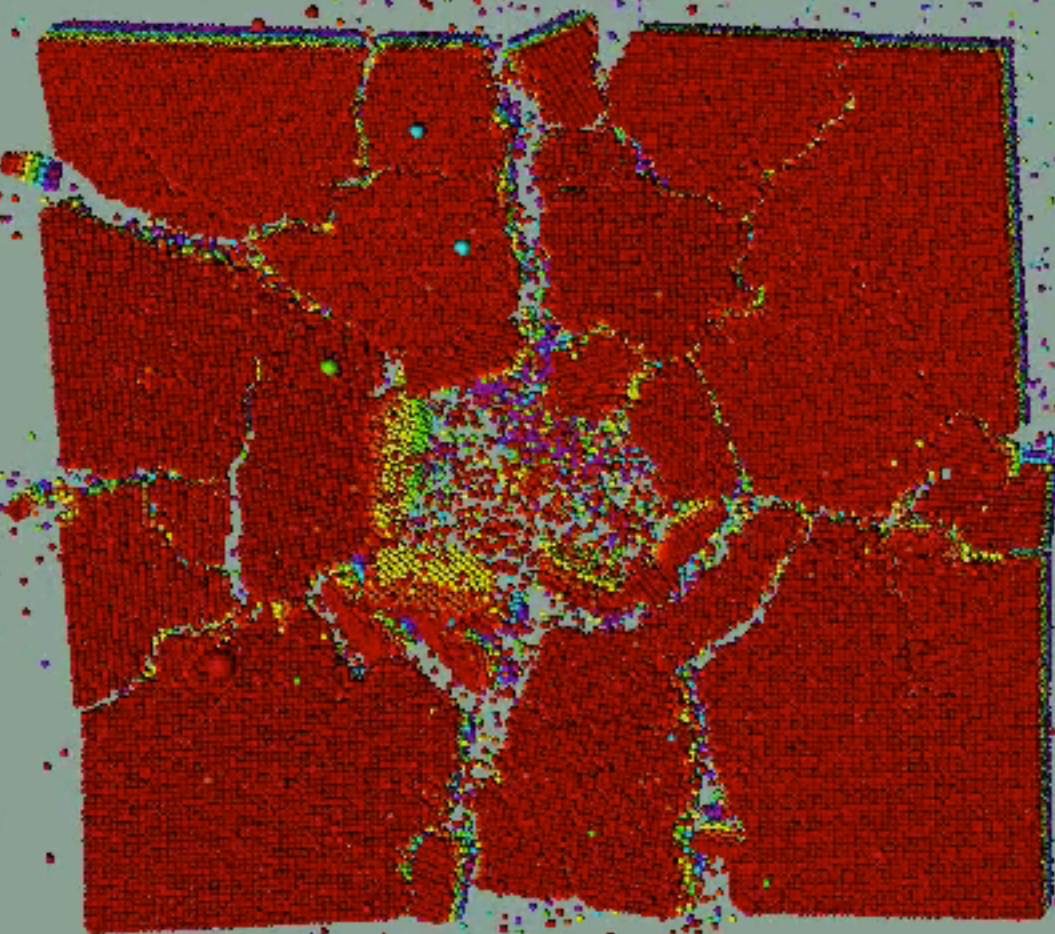
$K = 35 \text{ GPa}$
 $\tau = 0.0050$



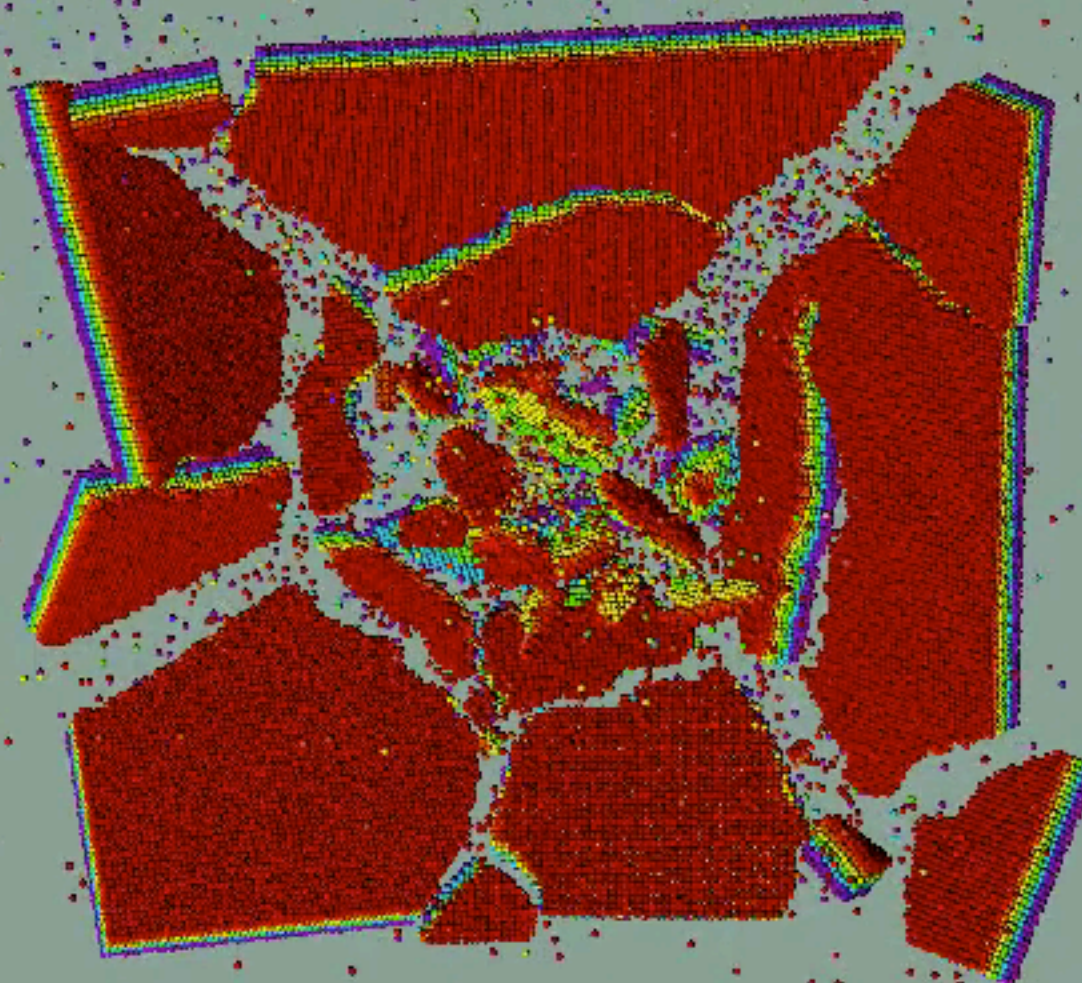
$K = 70 \text{ GPa}$
 $\tau = 0.0050$



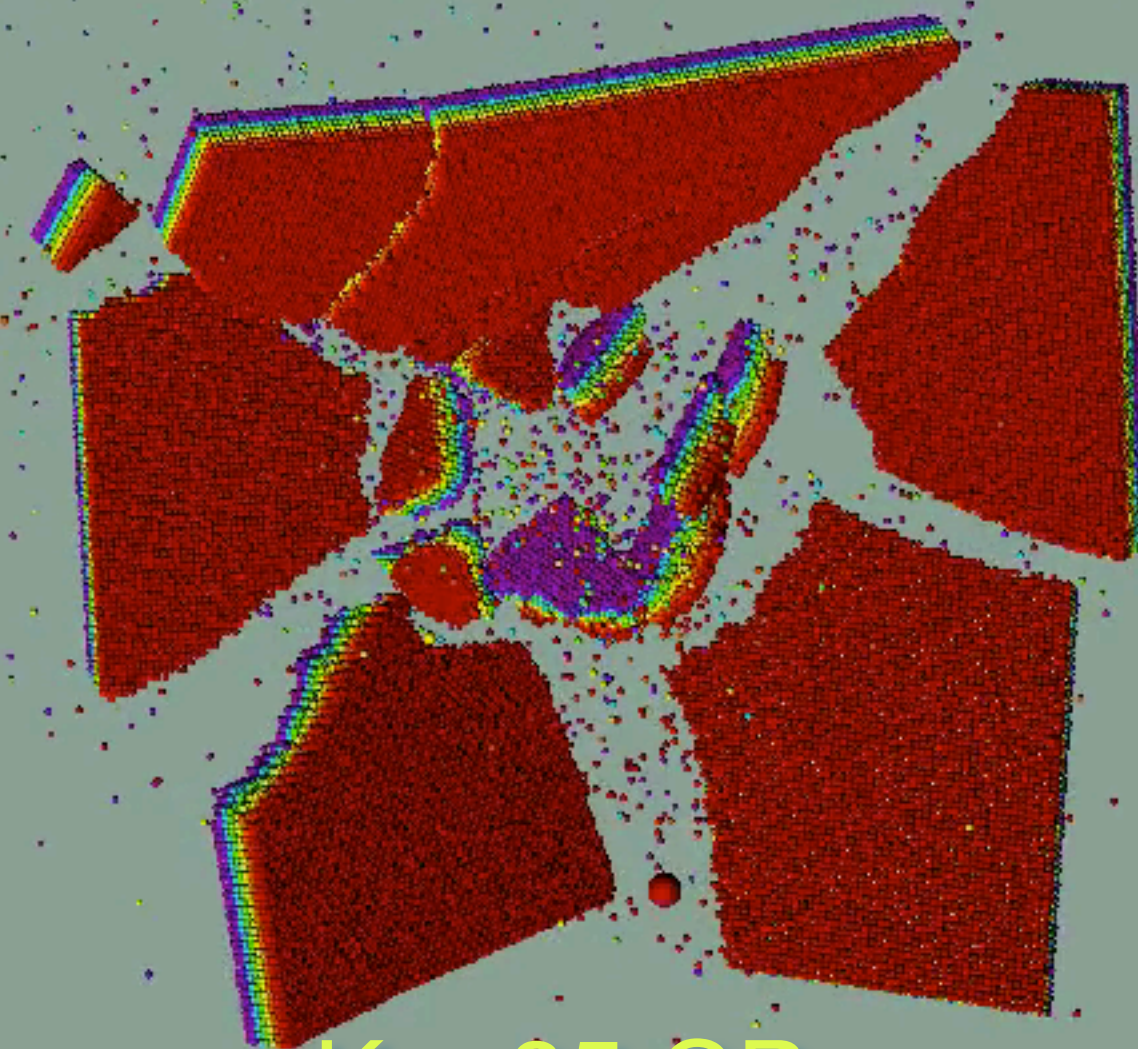
$K = 140 \text{ GPa}$
 $\tau = 0.0050$



$K = 35 \text{ GPa}$
 $\tau = 0.0025$



$K = 35 \text{ GPa}$
 $\tau = 0.0050$



$K = 35 \text{ GPa}$
 $\tau = 0.0075$

Bullet Shapes

No. of particles

131,072

(L) Round 1,093

(R) Sniper 2,158

$N = 4$

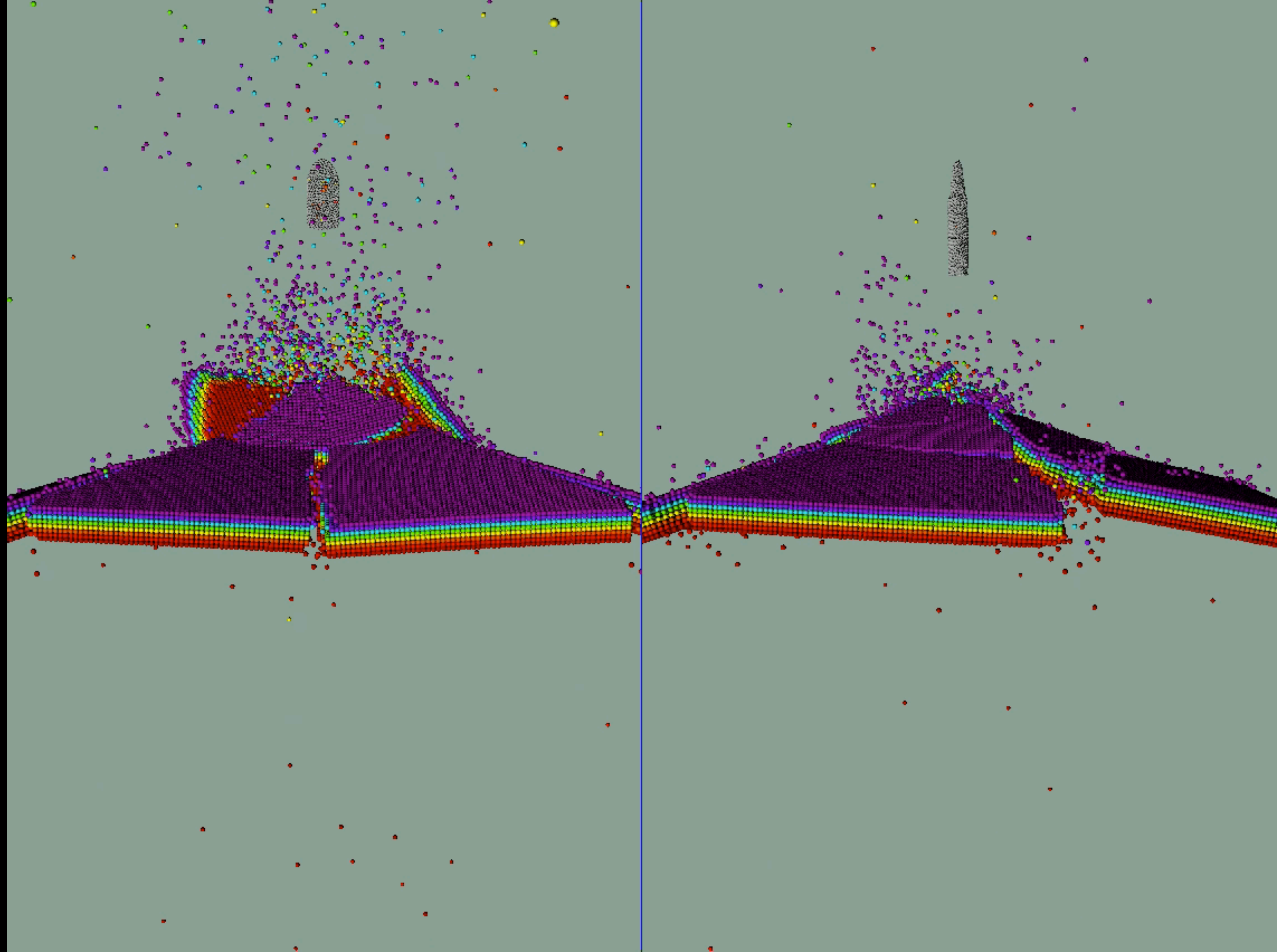
maxbonds = 255

$K = 35$ GPa

$k_{c:g-g} = 0.1$ GPa

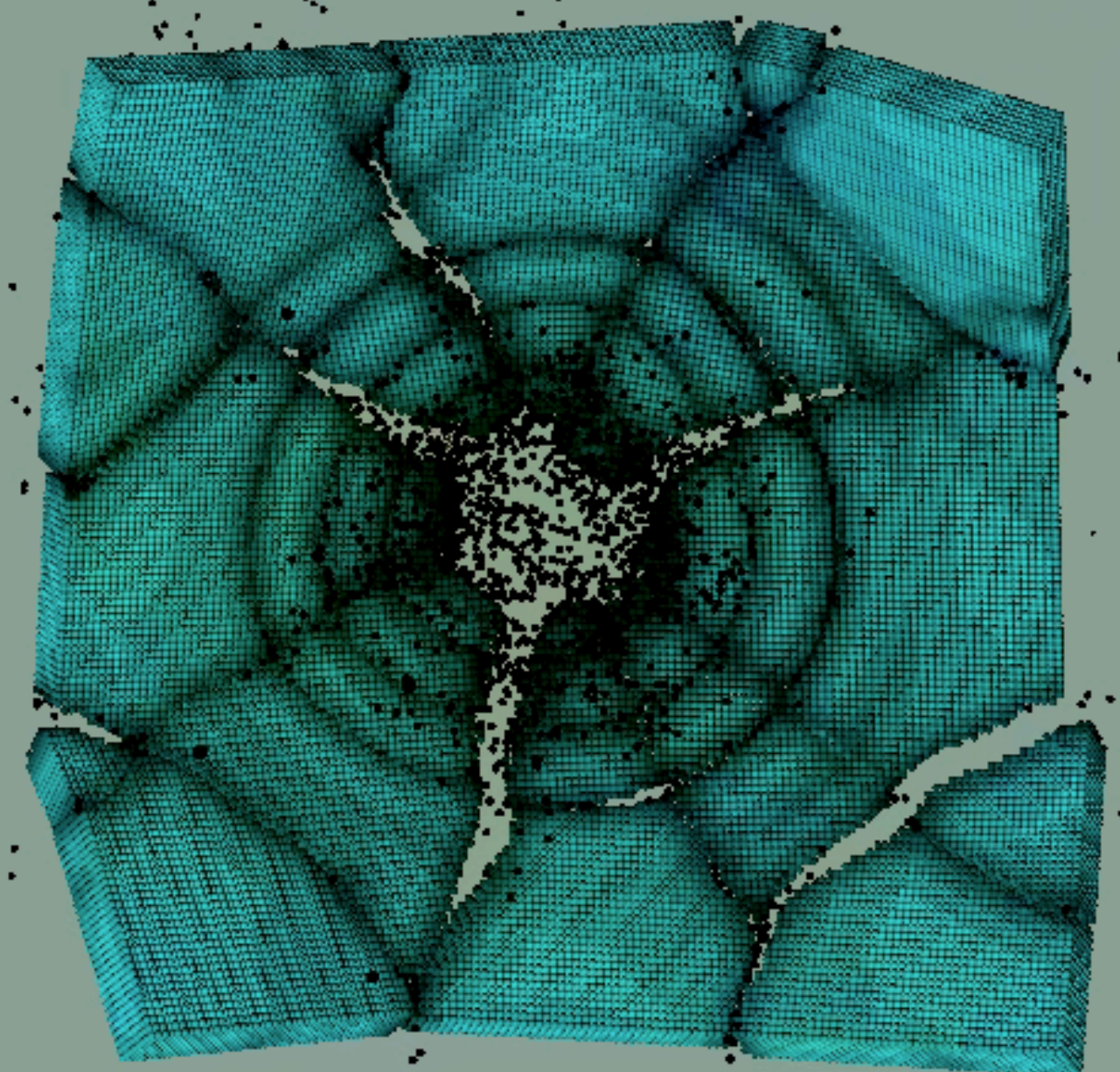
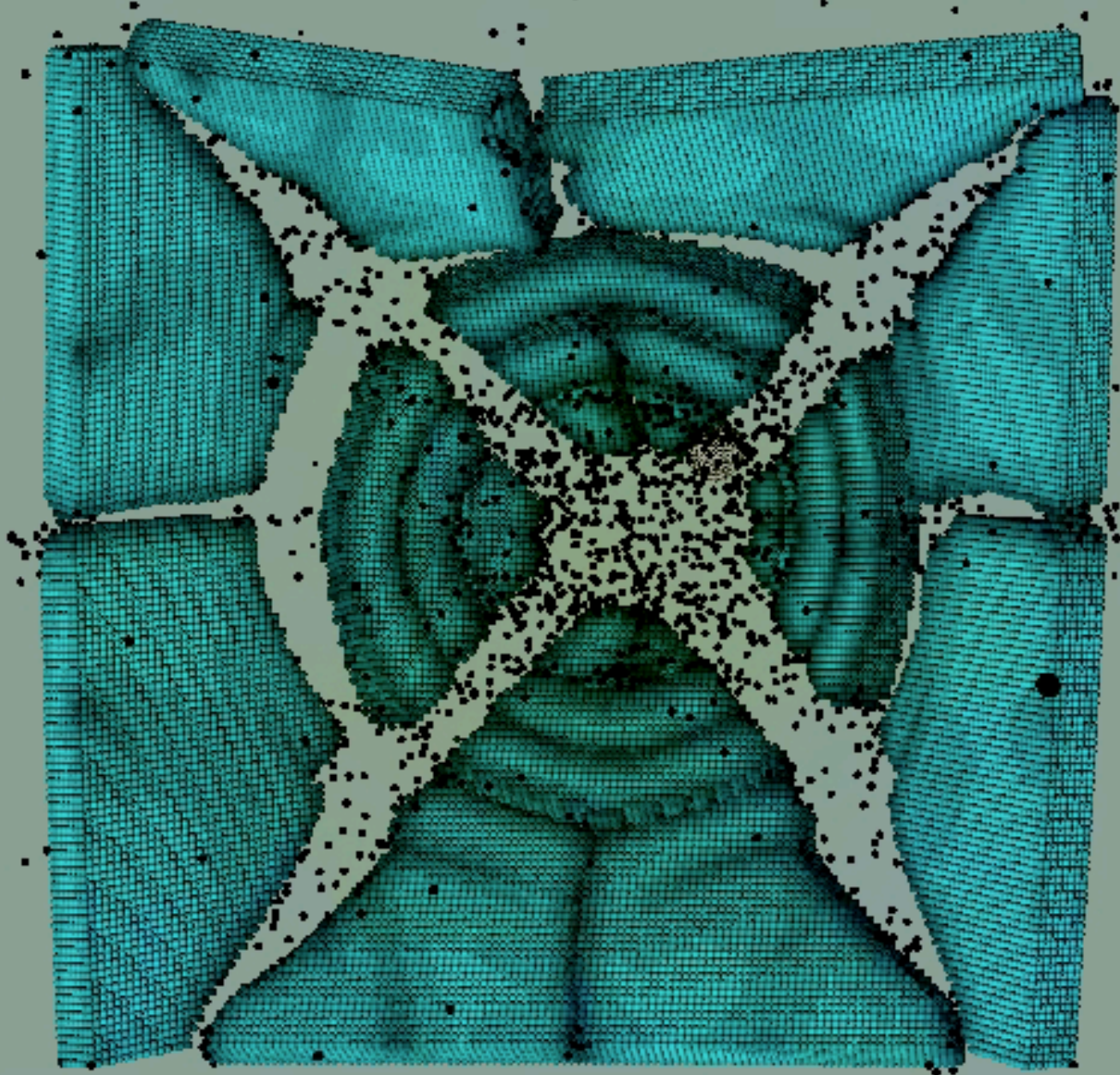
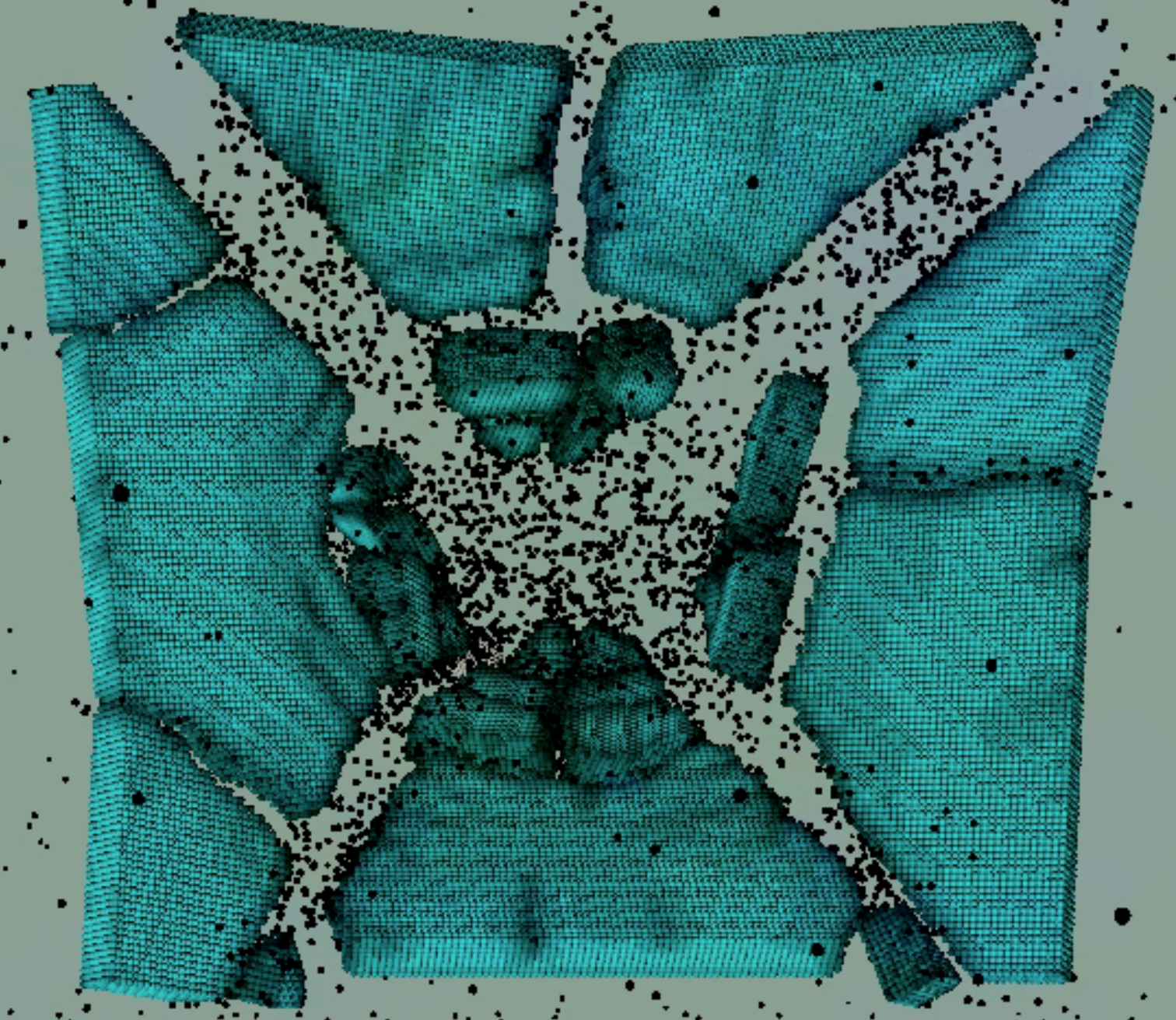
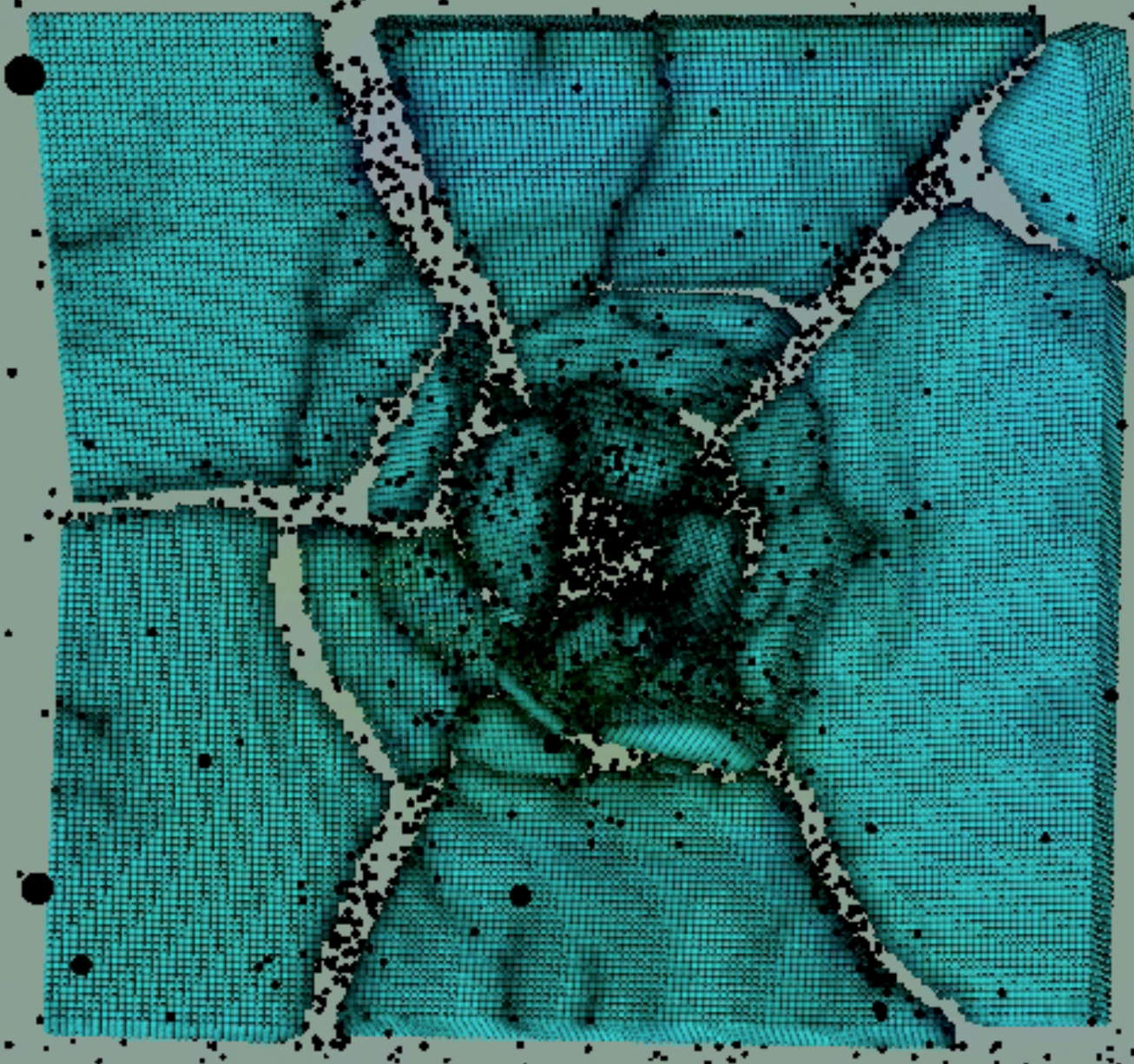
$k_{c:b-g} = 10$ GPa

$\tau = 0.005$



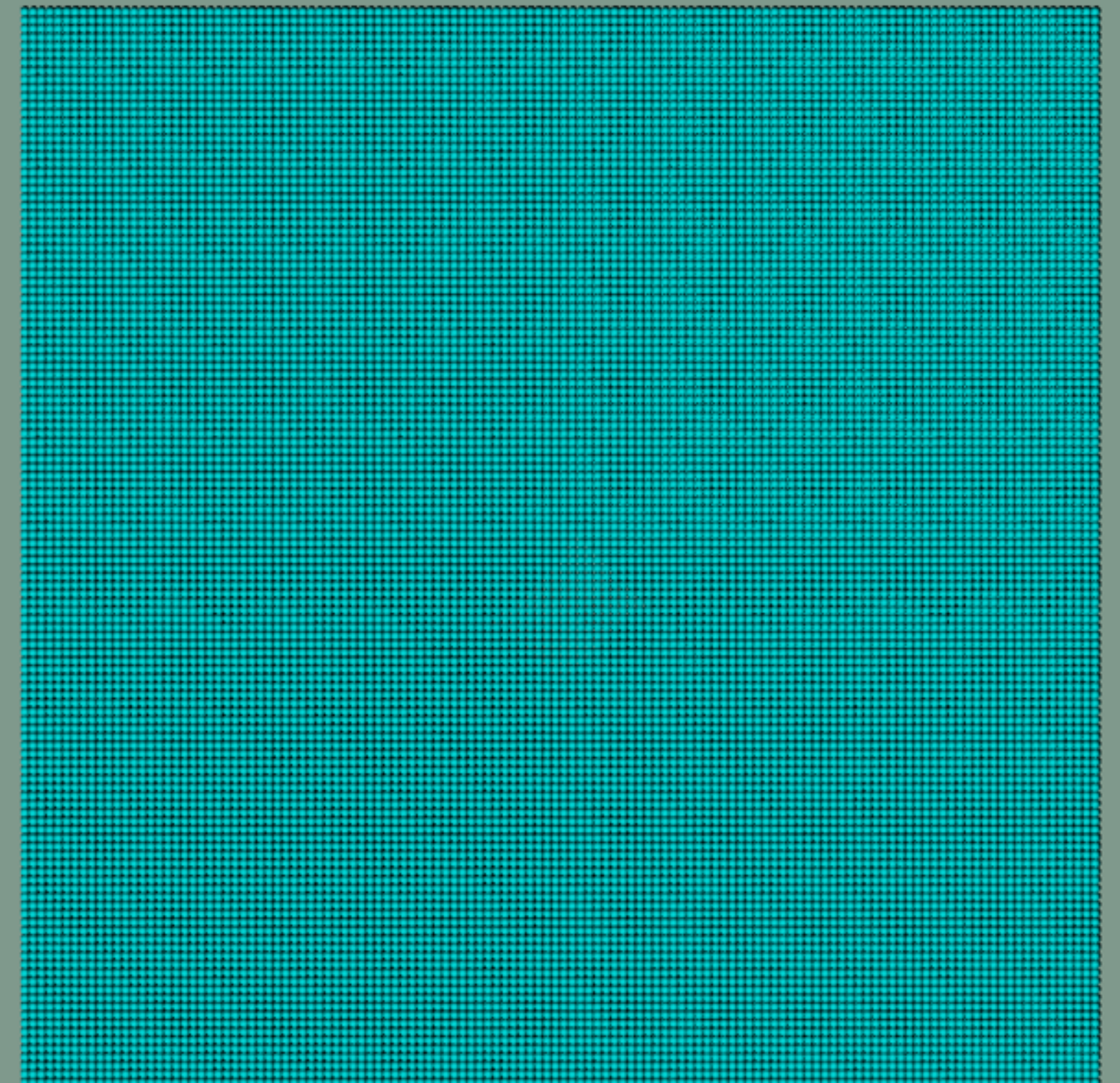
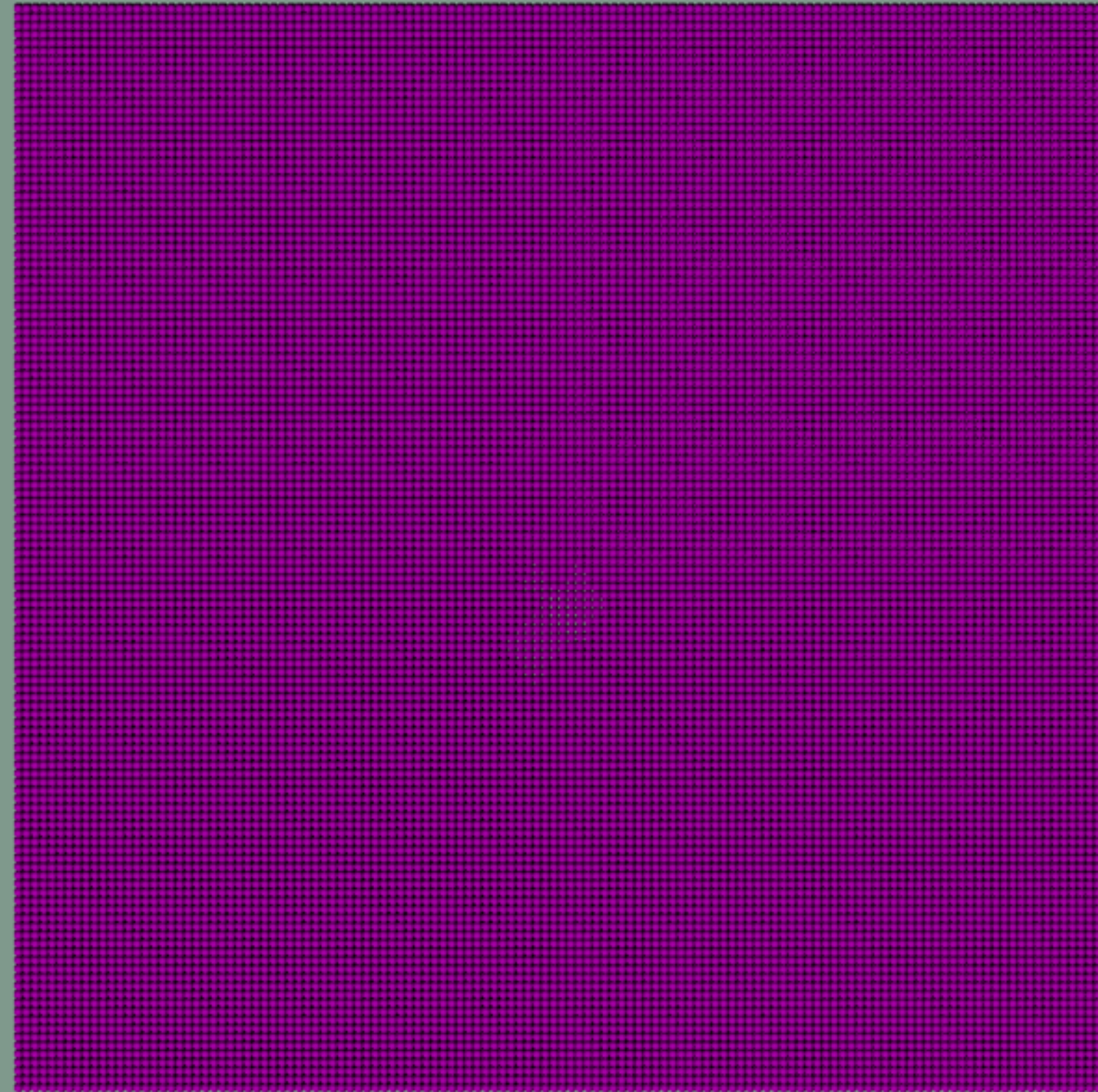
Visualizing
damages

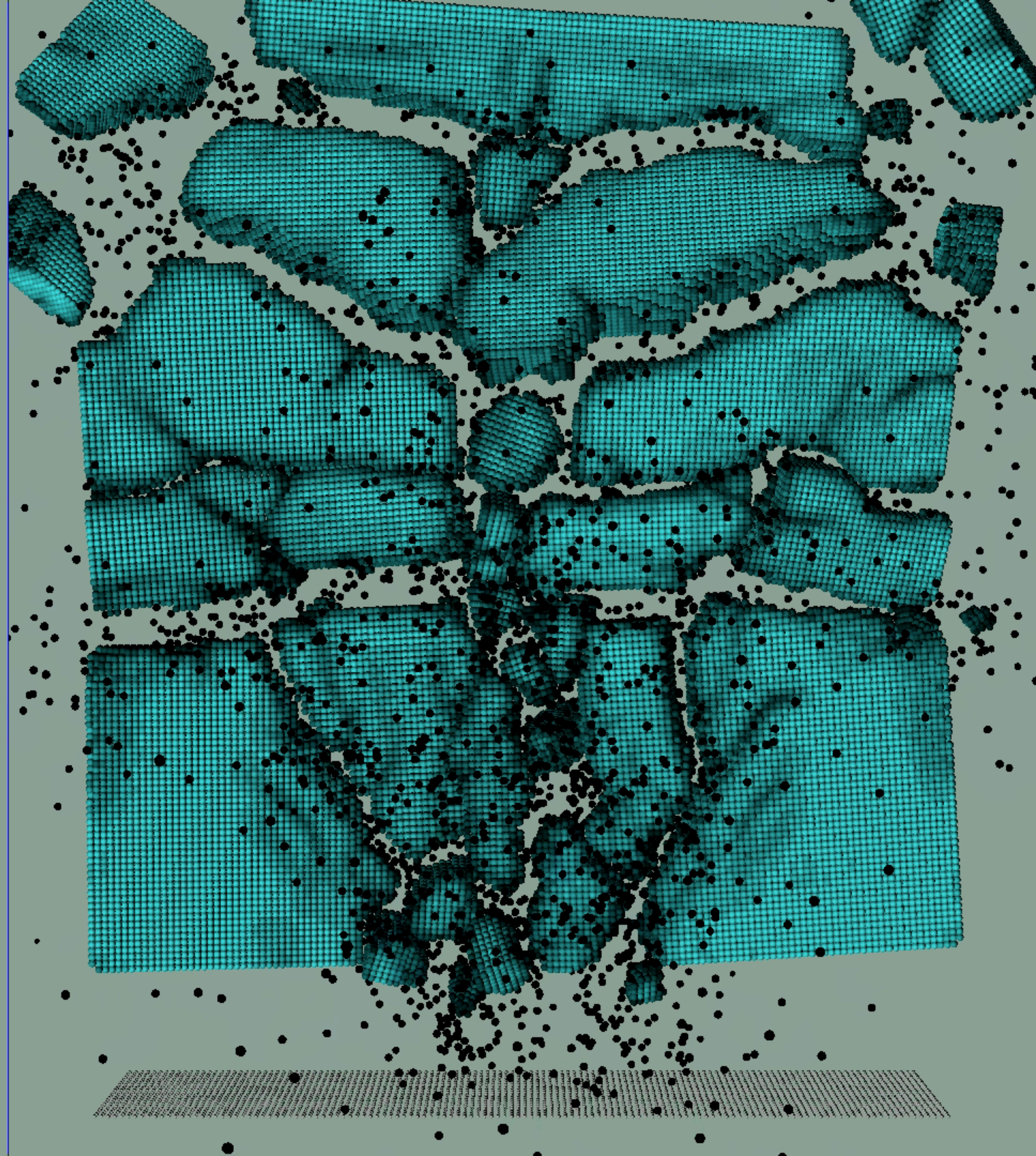
Color intensity
Transparency



Visualizing connected components

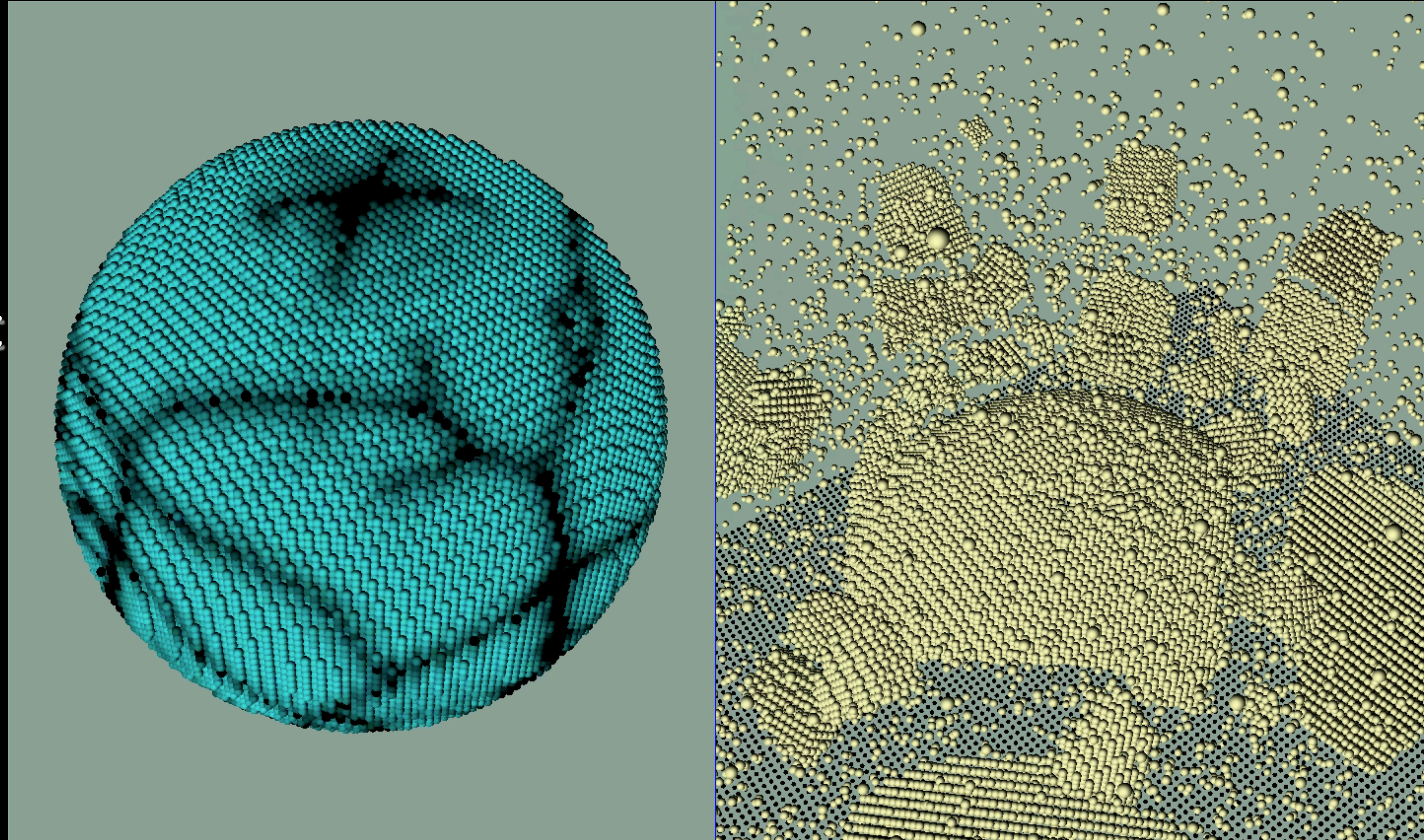
Particles: 131,072
 $N = 3$
max bonds = 122





Data Visualization

View fractured
line development



Conclusion and Future Directions

- Simulations are not in real time, and parameter setting can be nontrivial
- Parallelism across multiple GPUs
- Real-time surface extraction
- Anti-aliasing on point cloud rendering
 - ♦ Screen space ambient occlusion

Acknowledgments

- Chakrit Watcharopas (cwatcha@clemson.edu)
- Special thanks to Cliff Woolley, Dave Luebke, and Chandra Cheij (NVIDIA)
- Research generously supported by:



Please complete the Presenter Evaluation sent to you by email or through the GTC Mobile App. Your feedback is important!