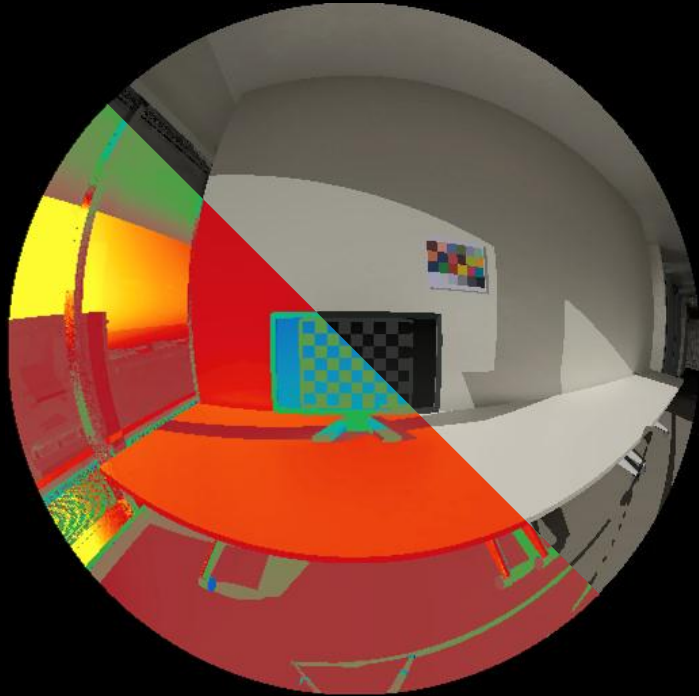


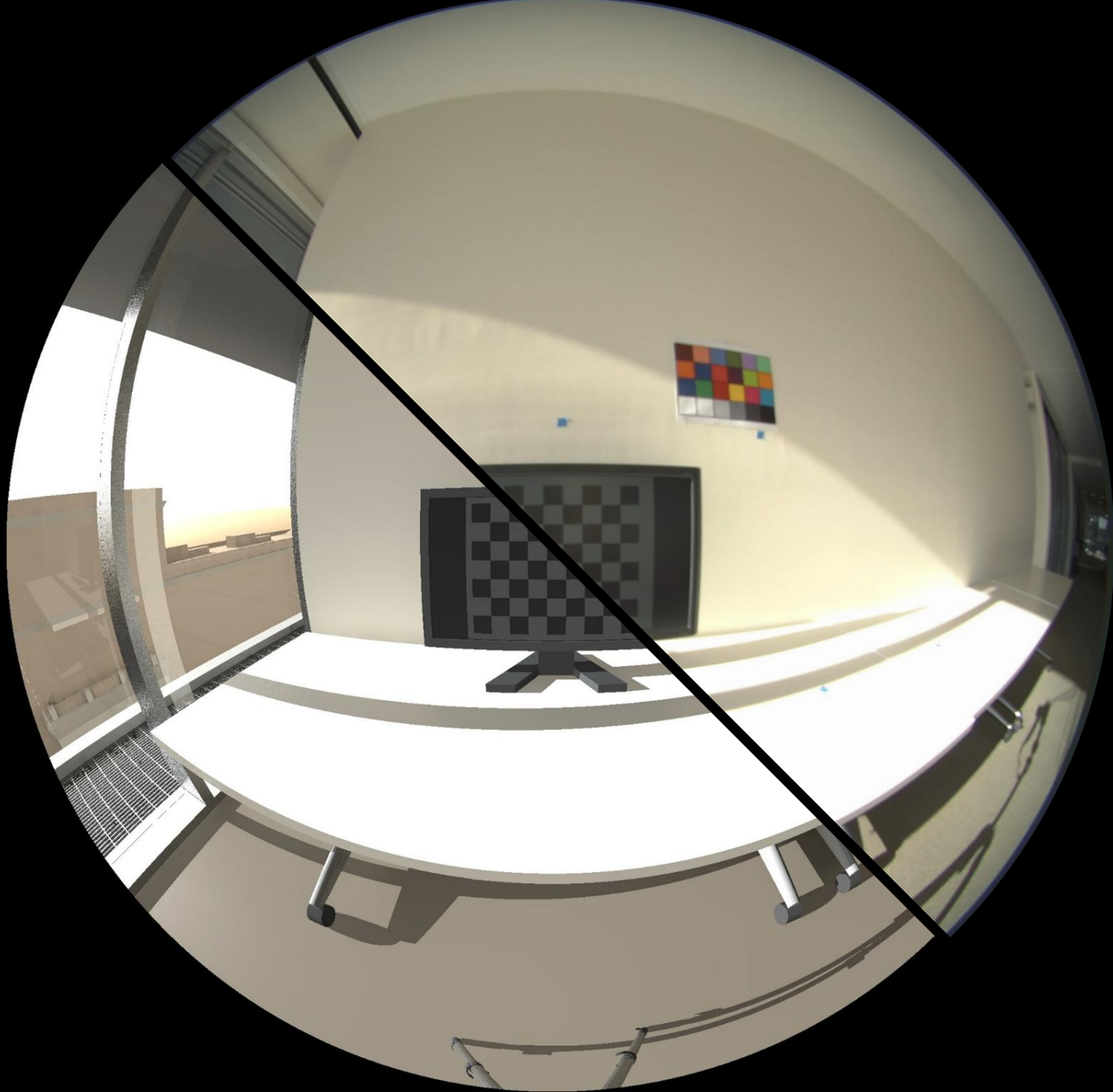


Accelerad: Daylight Simulation for Architectural Spaces Using GPU Ray Tracing

Nathaniel Jones and Christoph Reinhart
GPU Technology Conference 2015



Massachusetts Institute of Technology
Sustainable Design Lab



What is Architectural Lighting Simulation?

Experiential qualities of light

- Orientation
- Safety
- Aesthetics

Quantifying performance of buildings

- How often a space is **sufficiently lit** to perform a task
- Whether a space may cause **visual discomfort**

Why Simulate Daylight?

Predict **appearance** with physical accuracy

Reduce demand for **electric lighting**

Balance lighting and views with **cooling loads**

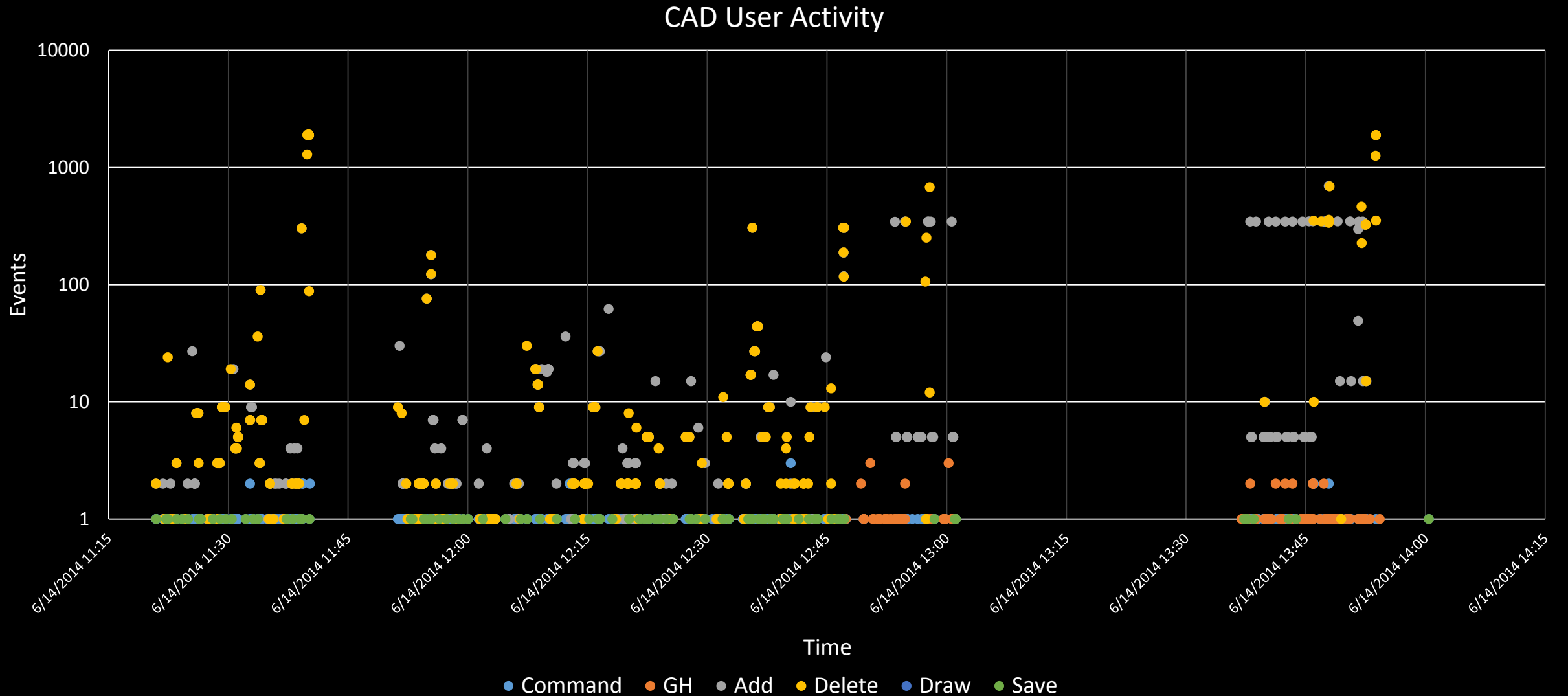
Light levels affect **worker productivity**

Daylight spectrum affects **alertness** and **health**

Simulation contributes to USGBC **LEED certification**

Increasingly an input for **other simulations**

When to Simulate Daylight?



How Long Does It Take?

Point sensor	10^3 primary rays
Sensor grid	10^5
Glare prediction	10^6
Annual glare prediction	10^8
Adaptive glare prediction	10^{10}
Glare mapping	10^{12}



Global Illumination
Irradiance Caching
Validation Testing

Radiance

Industry standard for architectural
lighting and **daylighting** simulation

Whitted-style recursive **ray tracing**

Well **validated** and **open source**

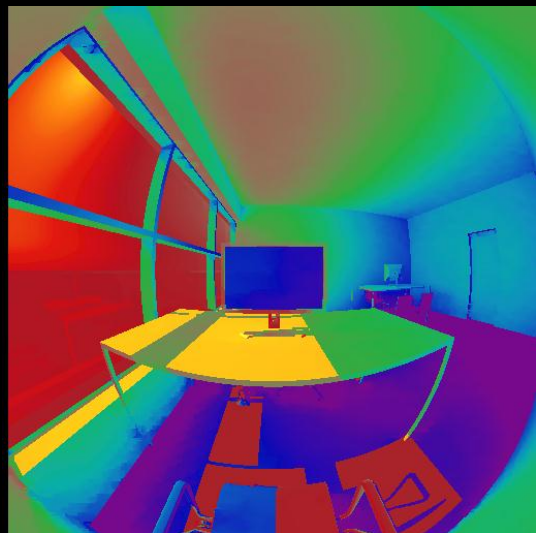
Simulation engine used by:

- Adeline
- **DAYSIM**
- Desktop Radiance
- DesignBuilder
- **DIVA**
- Ecotect
- IES<VE>
- OpenStudio
- **SHADERADE**
- **umi**

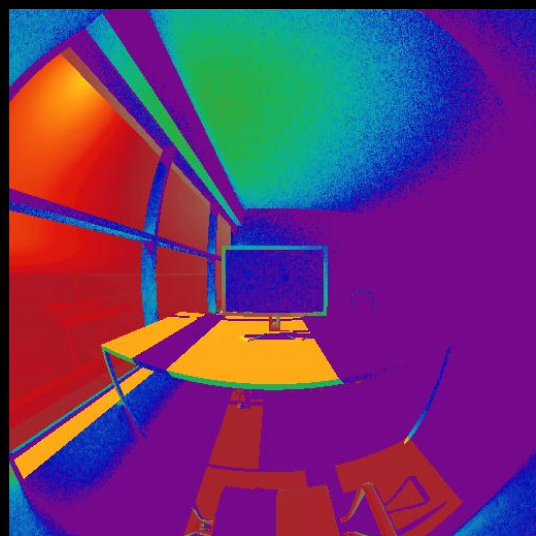
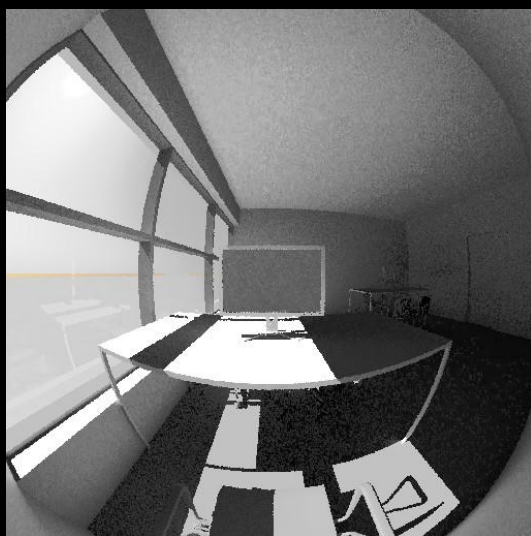


Lawrence Berkeley National Laboratory. *Daylighting The New York Times Building*. http://windows.lbl.gov/comm_perf/nyt_visualizing.html

Radiance Tradeoff

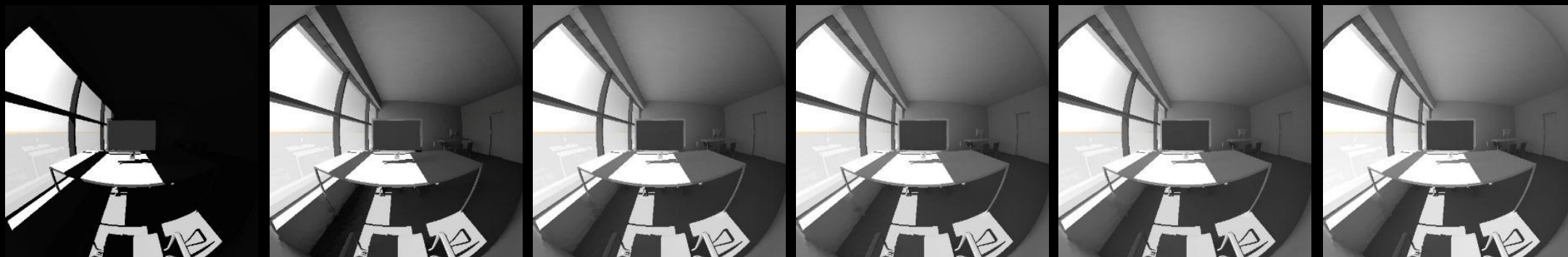


138,844,405 rays 49 minutes

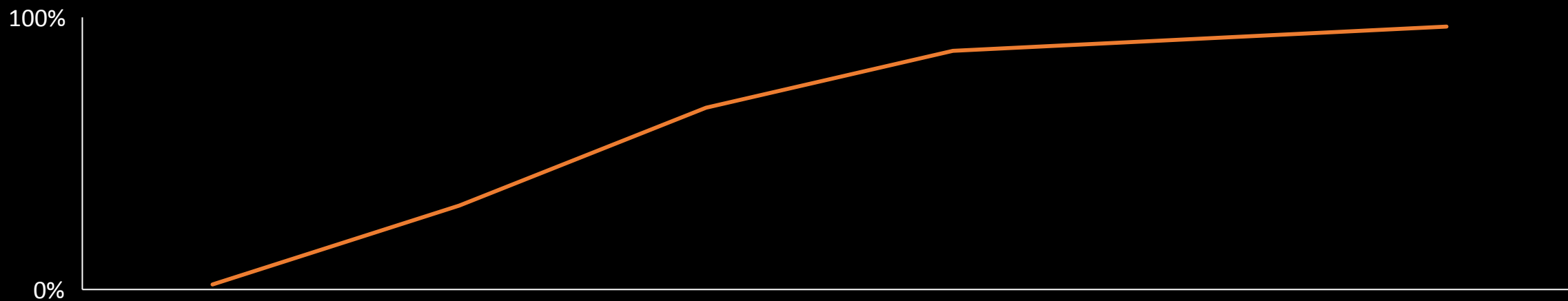


41,010,721 rays 1.5 minutes

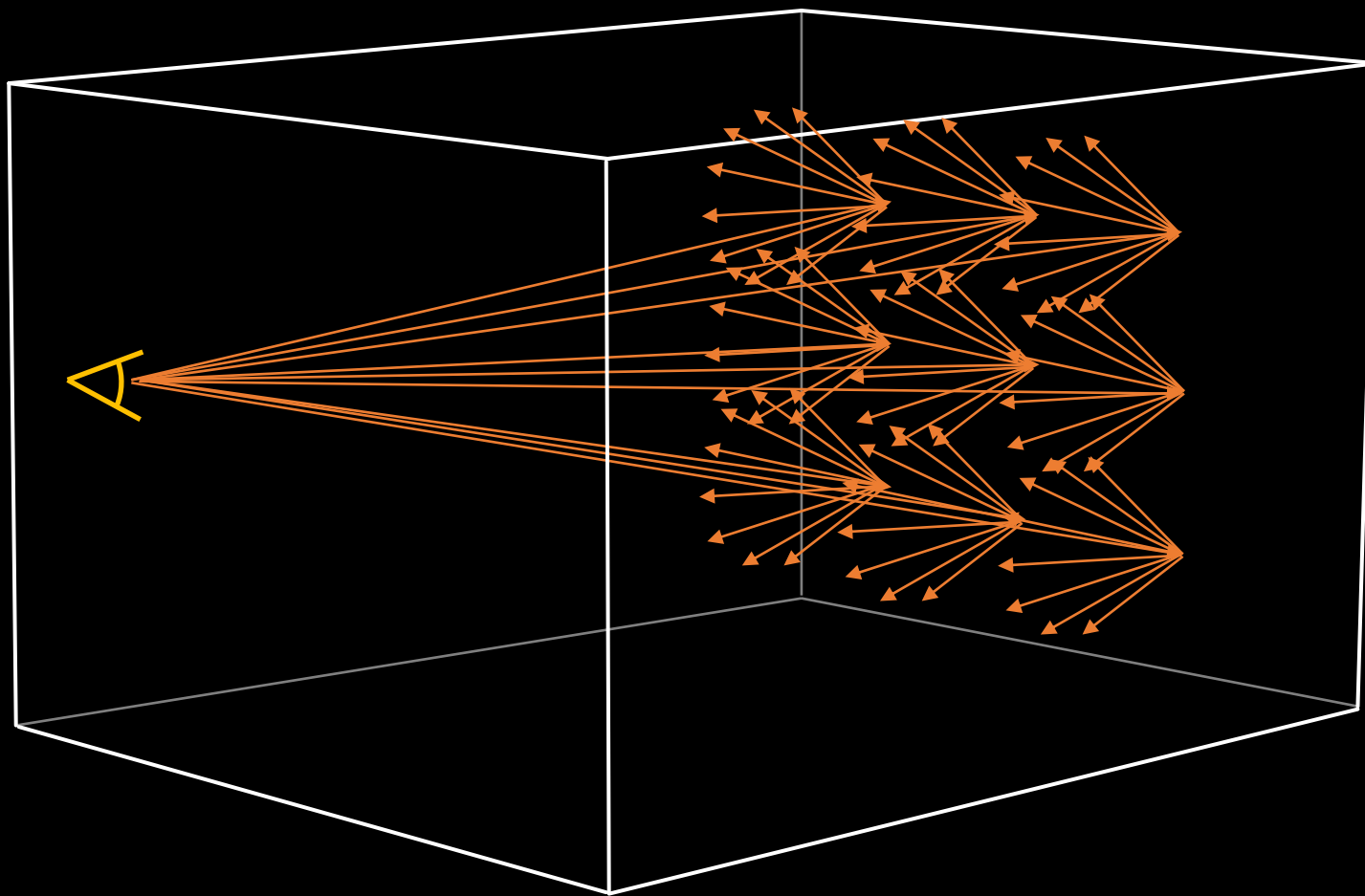
Ambient Bounces



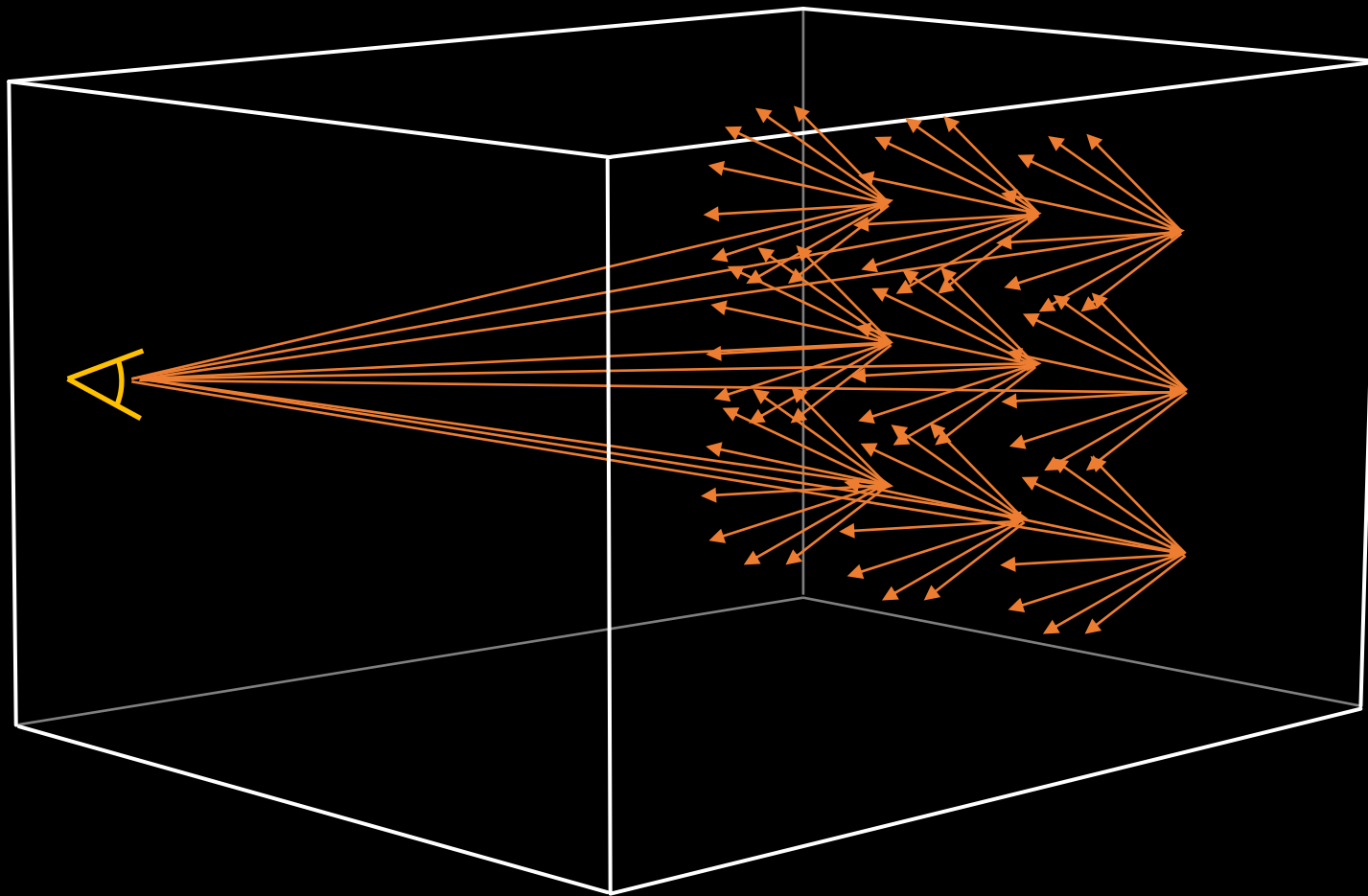
Diffuse Bounces	0	1	2	3	4	5	
Mean Luminance	1.18	66.3	147	194	204	214	cd/m^2



Whitted-Style Ray Tracing: CPU



Whitted-Style Ray Tracing: GPU



OptiX™

- Built-in **ray traversal** using BVH or KD trees
- User-defined **shader programs**

- Ray generation
- Intersection testing
- Closest hit
- Any hit
- Miss

*Implement to
match Radiance*

Radiance (C/C++)

```
if (rayorigin(&p, REFLECTED, r, refl) == 0)
{
    VSUM(p.rdir, r->rdir, pnorm, 2.*pdot);
    checknorm(p.rdir);
    rayvalue(&p);
    multicolor(p.rcol, p.rcoef);
    addcolor(r->rcol, p.rcol);
}
```

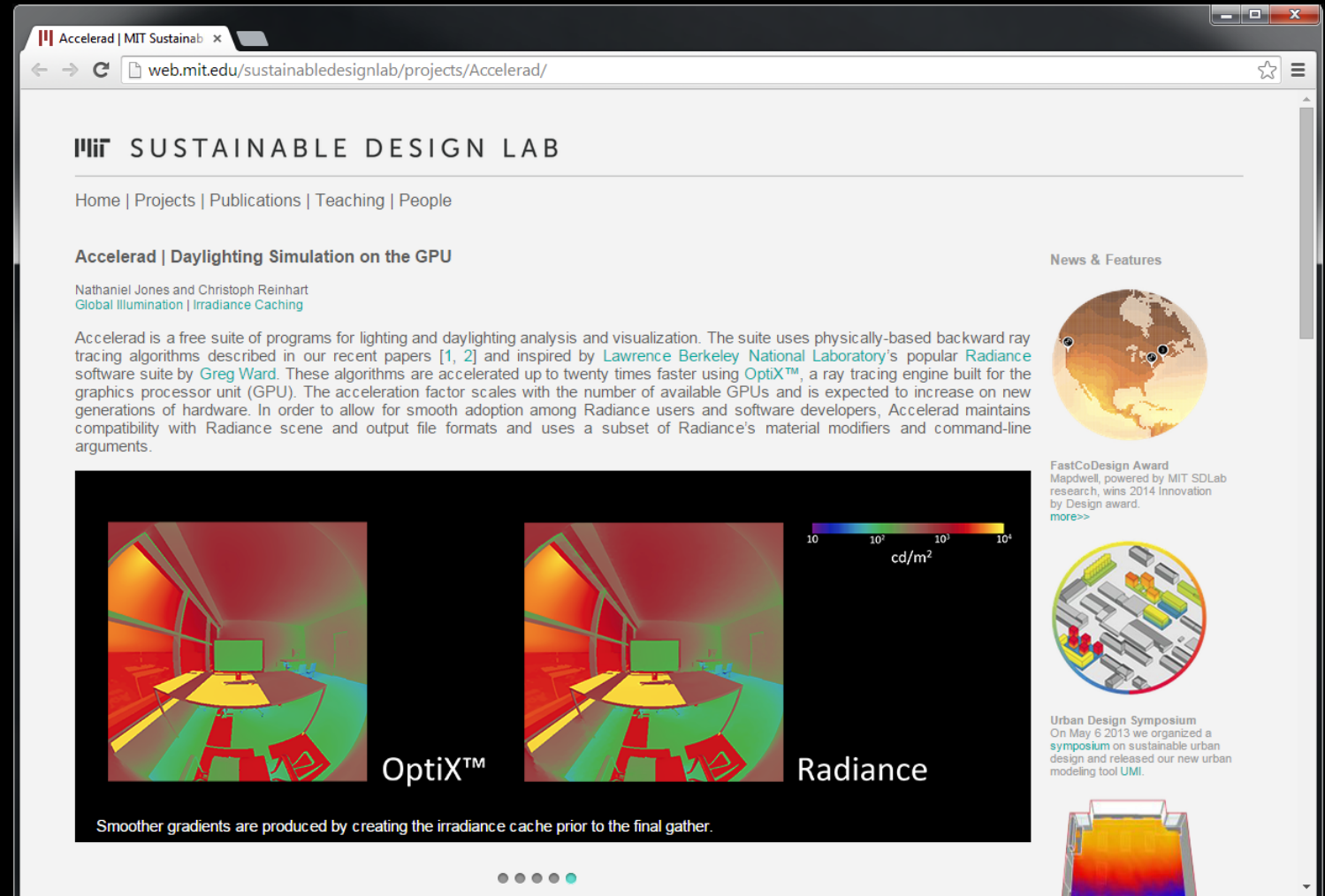


Accelerad (CUDA/OptiX)

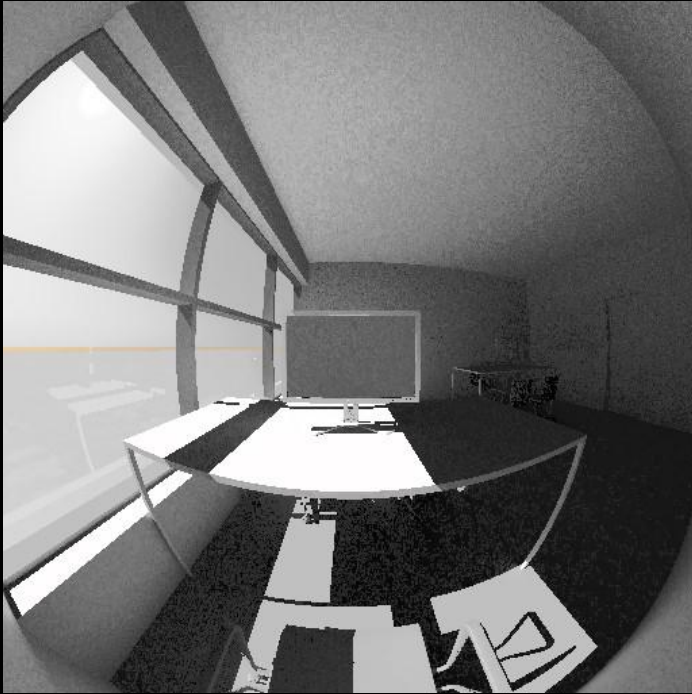
```
if (prd.weight >= minweight &&
    prd.depth <= abs(maxdepth))
{
    float3 rdir = reflect(ray.dir, pnorm);
    Ray ray = make_Ray(hit_point, rdir,
                      ray_type, RAY_START, RAY_END);
    rtTrace(top_object, ray, prd);
    result += prd.result * rcoef;
}
```

Accelerad

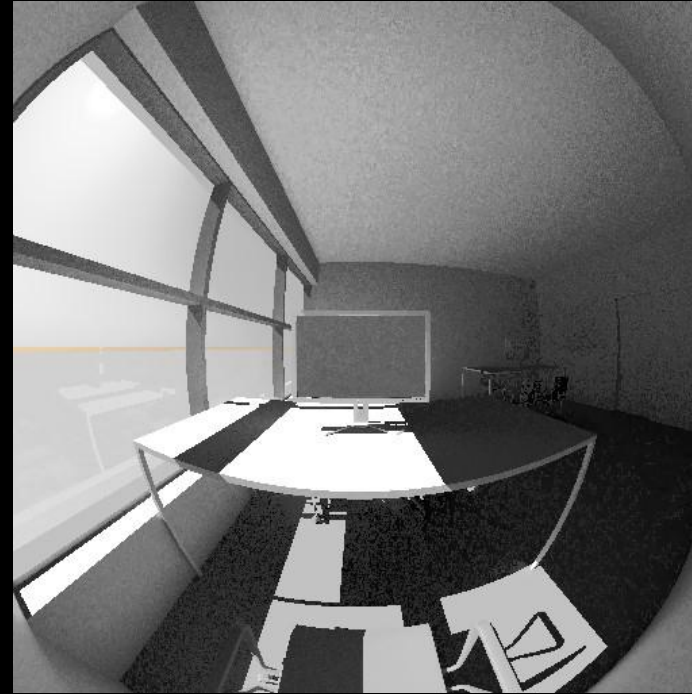
- Fork of **Radiance** source code
- Uses **OptiX™** for all ray tracing
- Free in beta



Results: Single Image

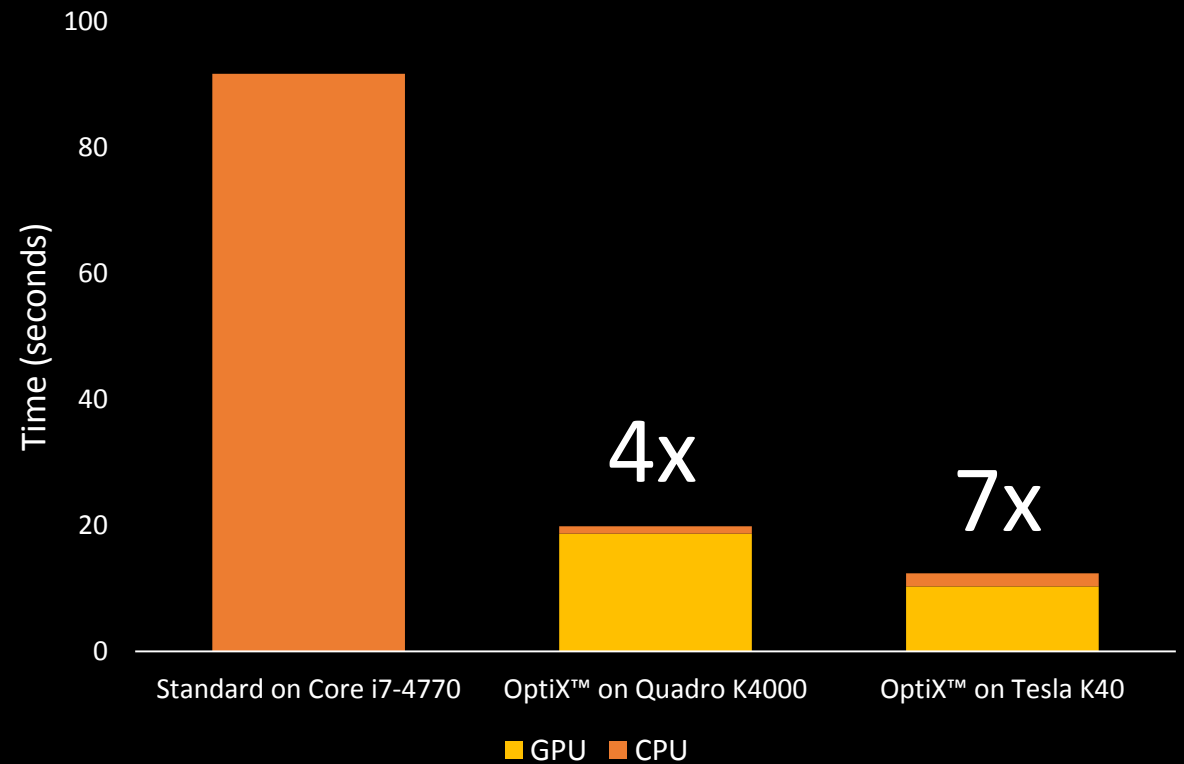
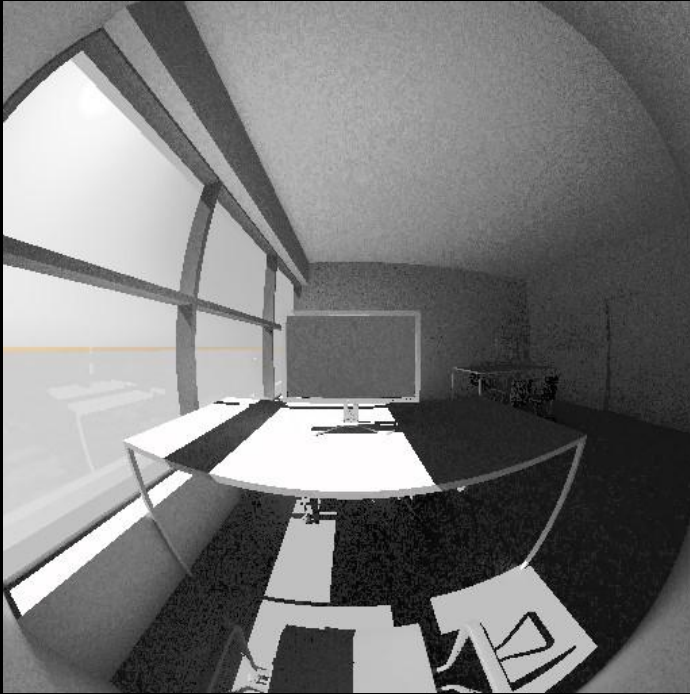


Accelerad
12 seconds

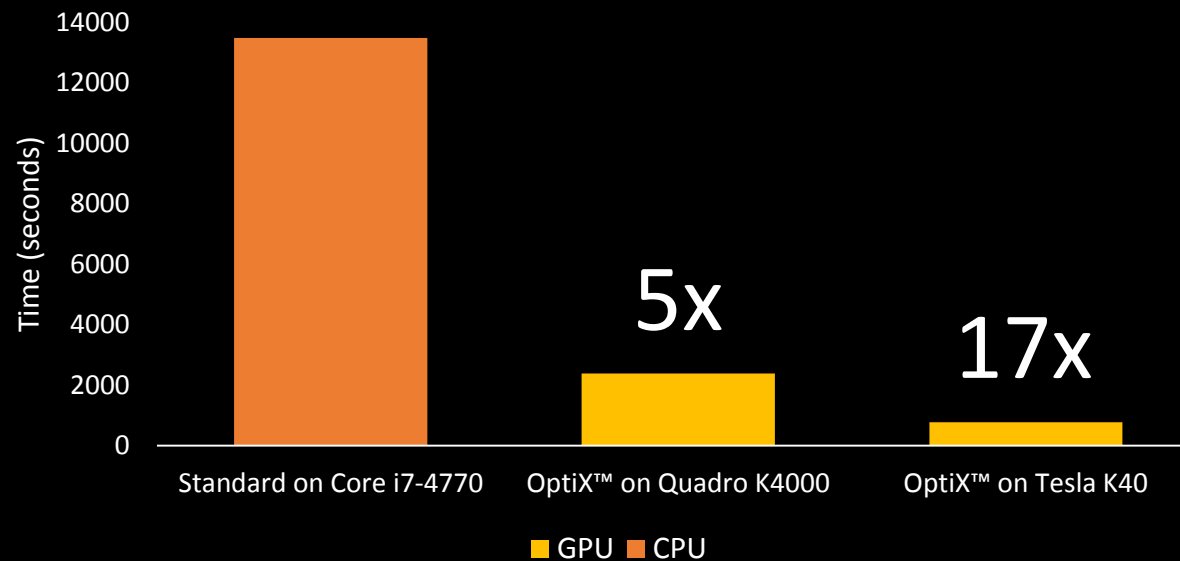
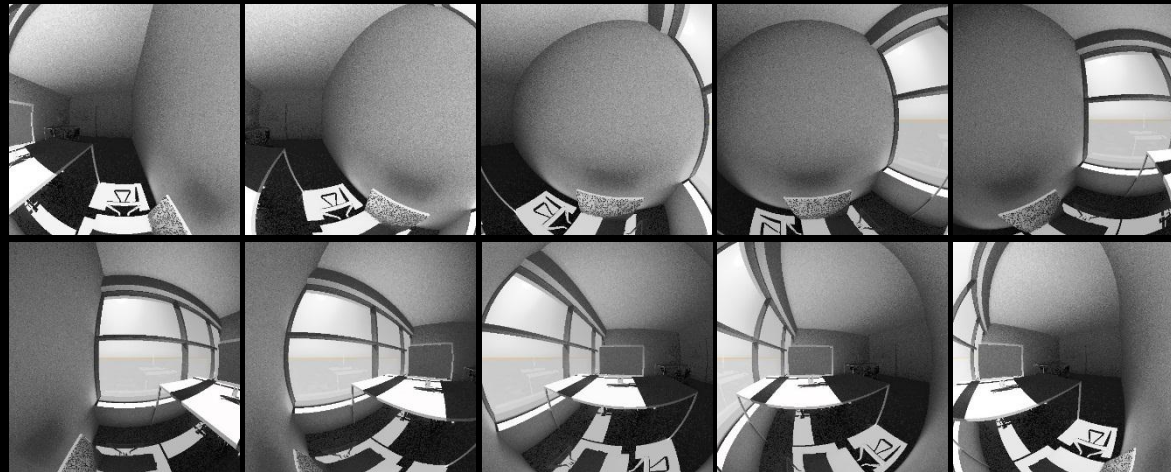


Radiance
92 seconds

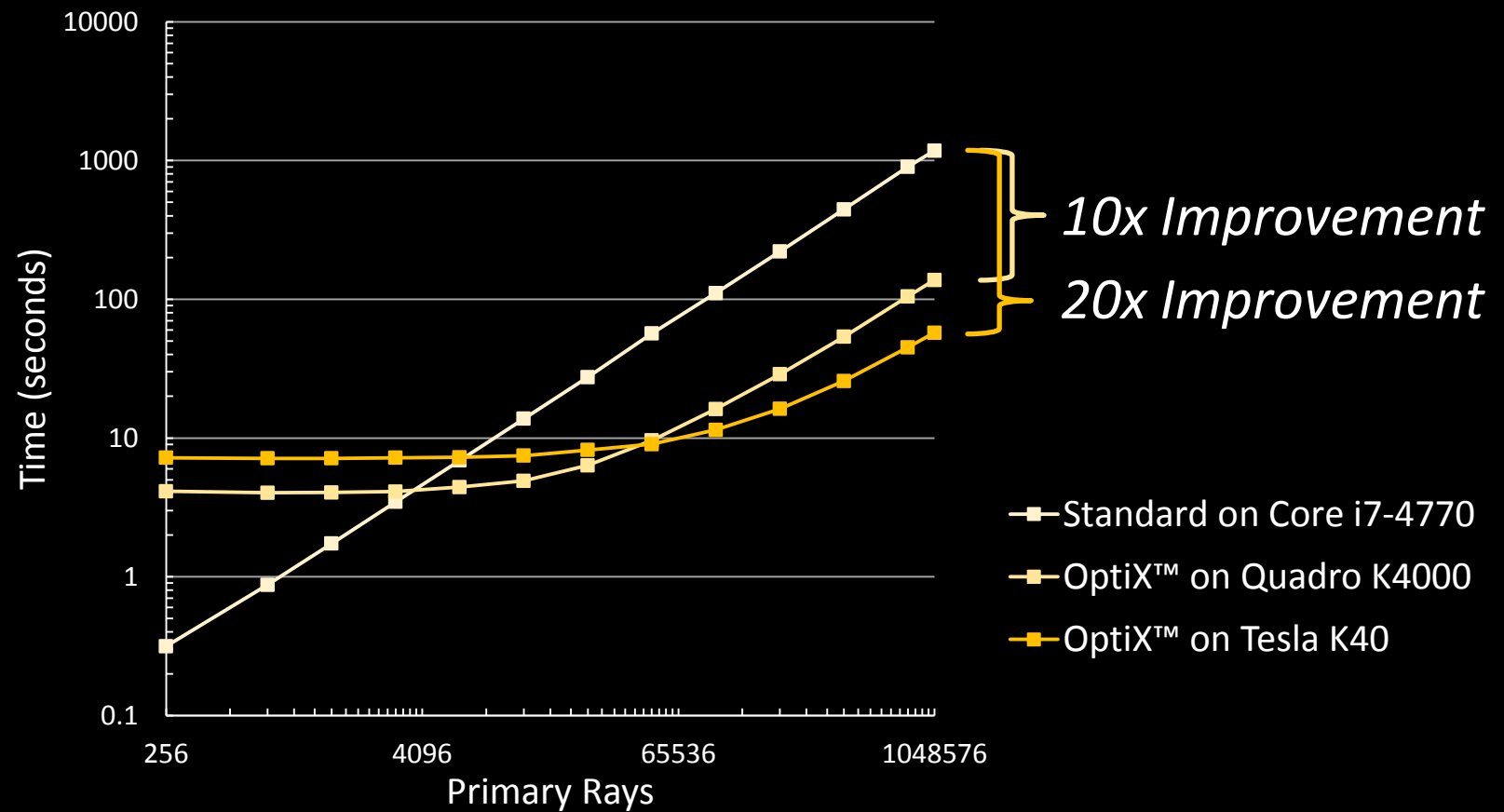
Results: Single Image

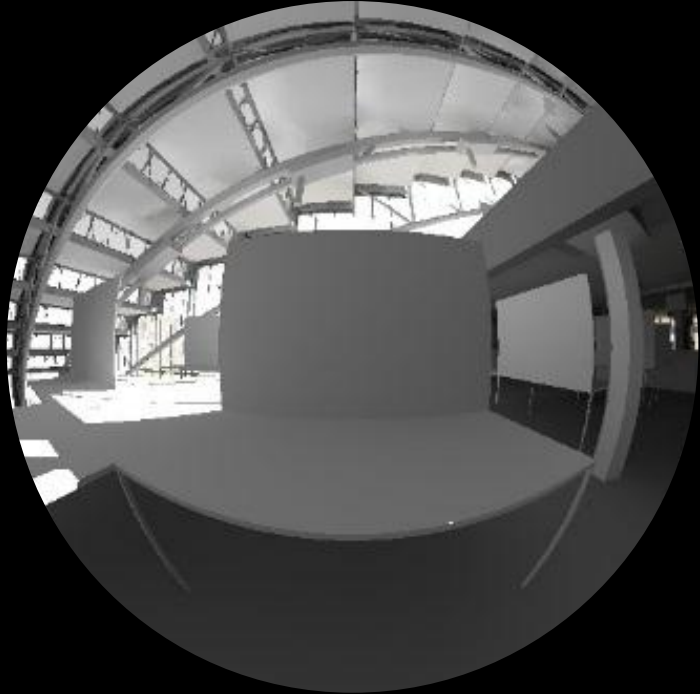


Results: 120 Images



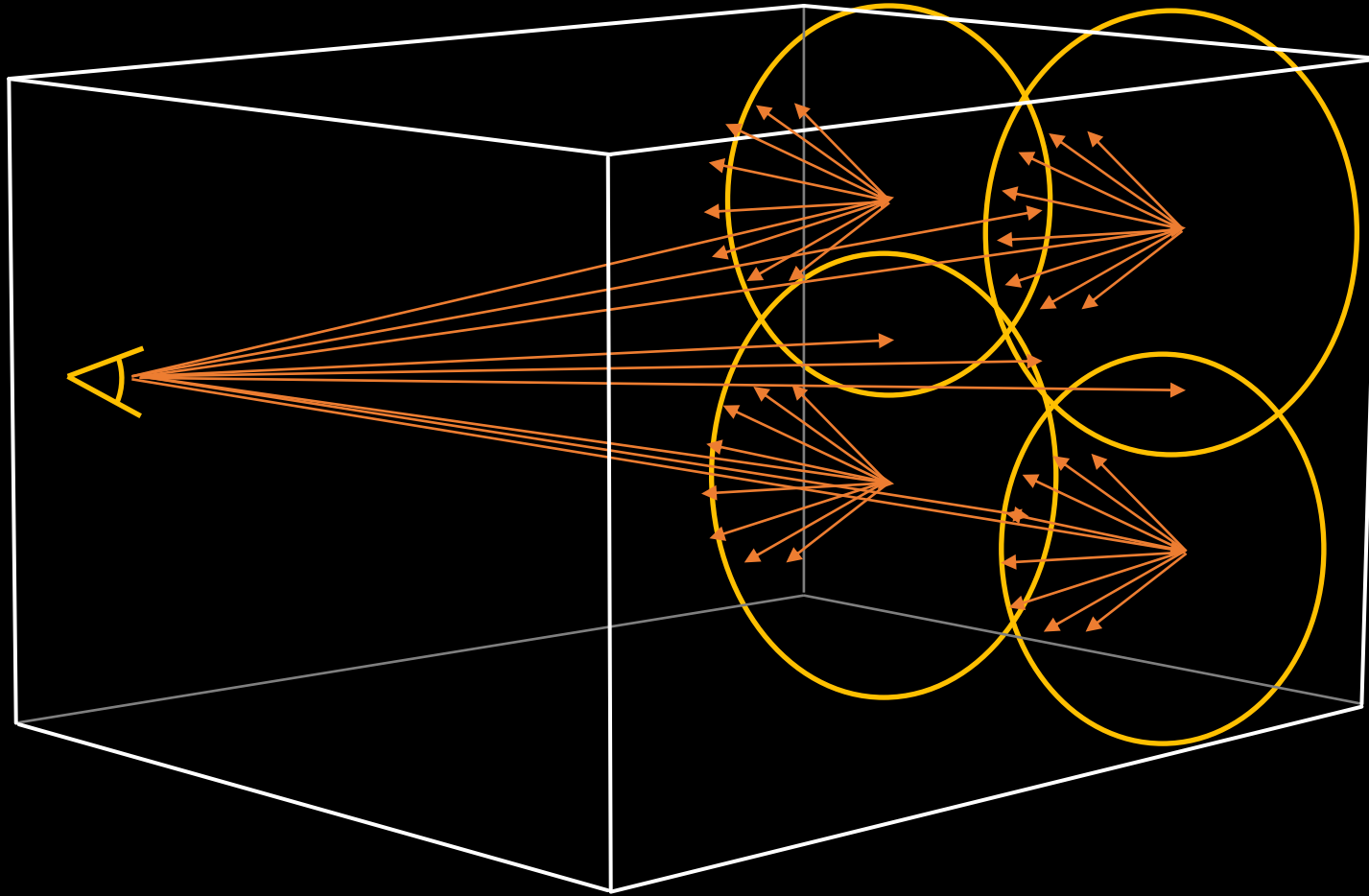
Speedup



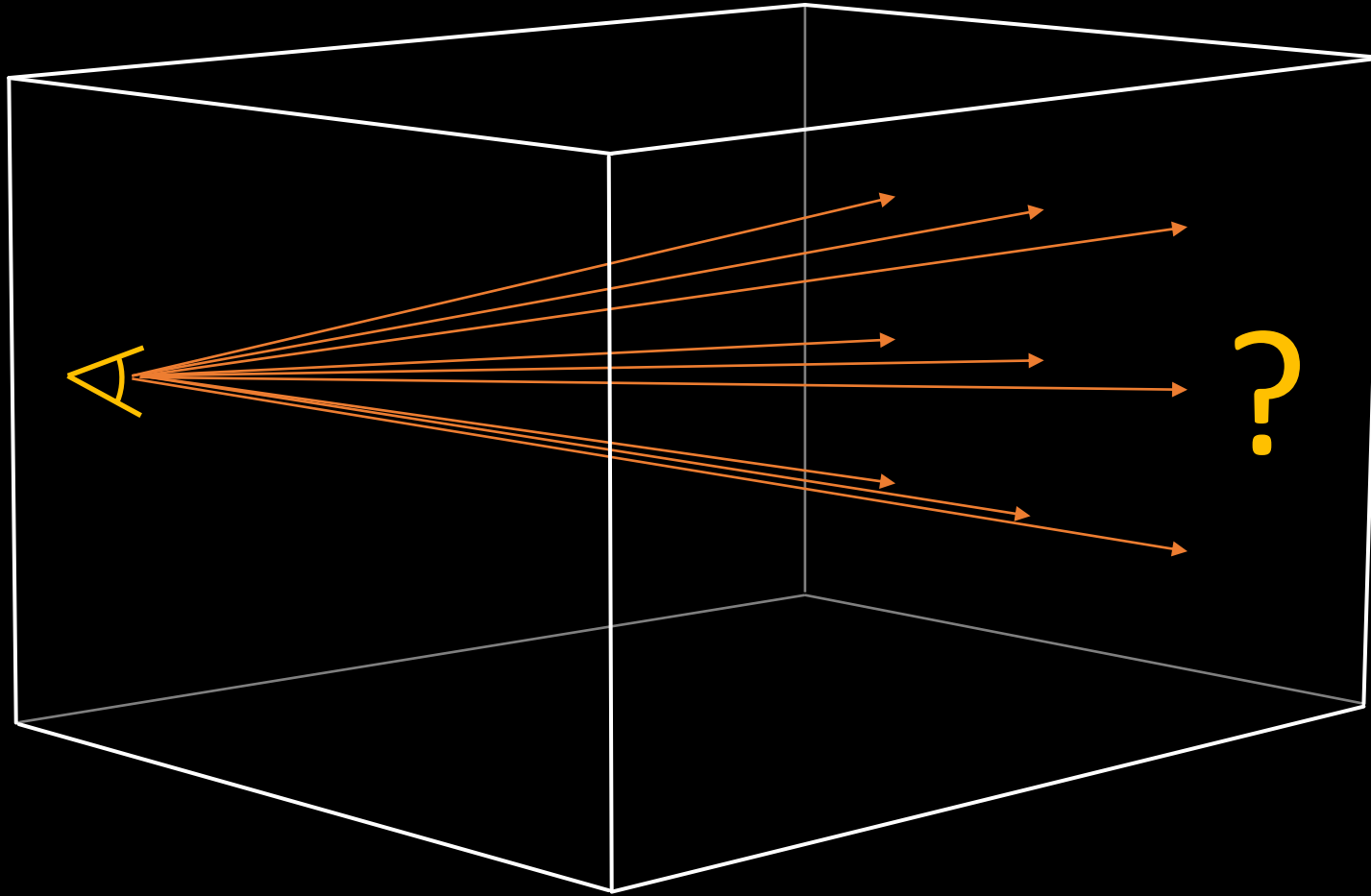


Global Illumination Irradiance Caching Validation Testing

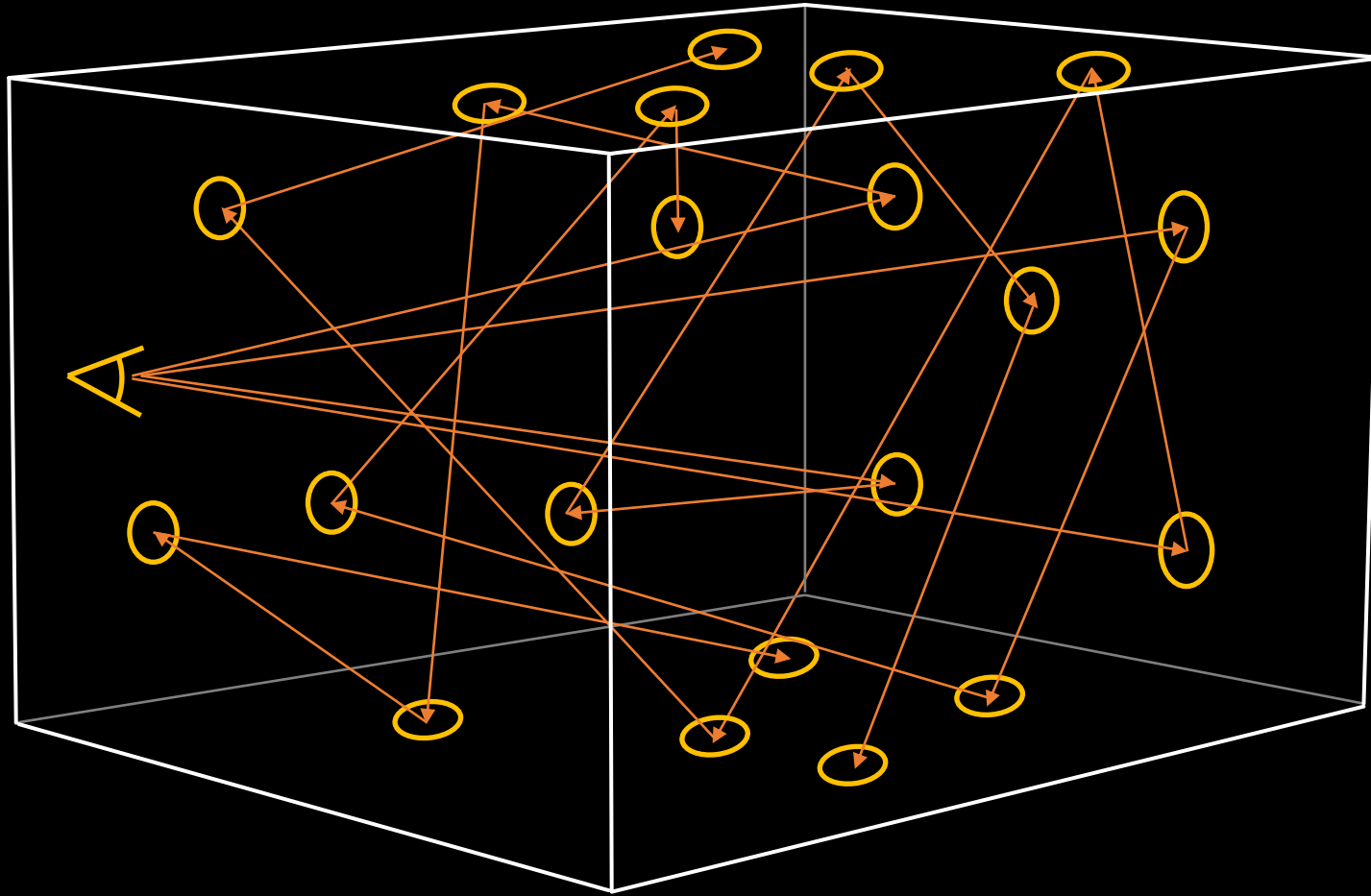
Irradiance Caching: CPU



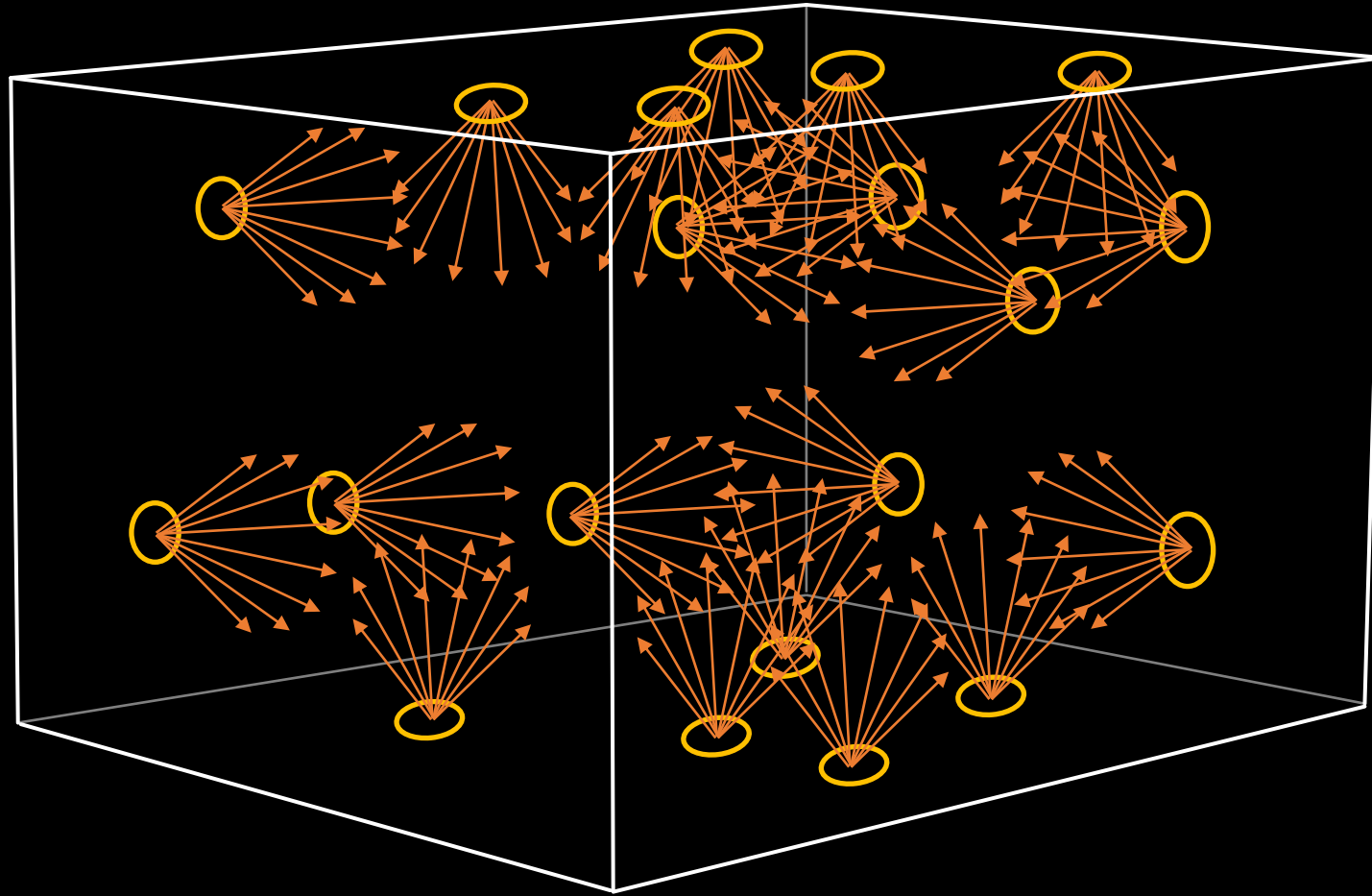
Irradiance Caching: GPU



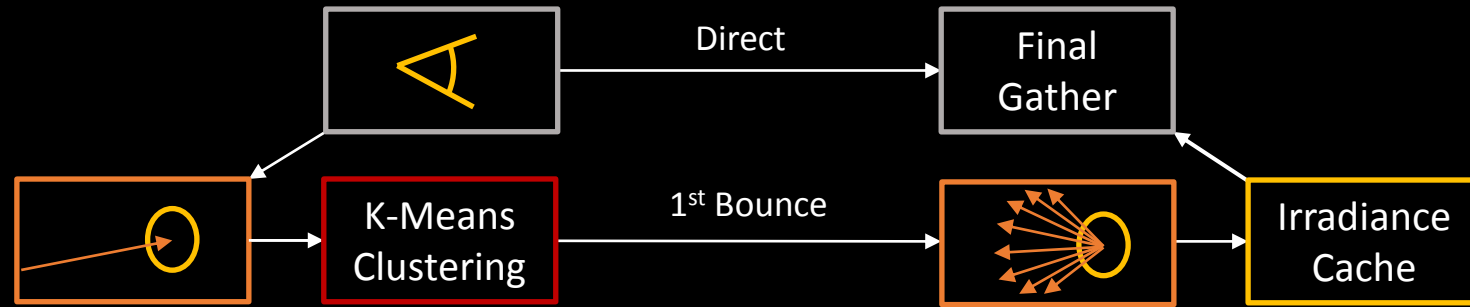
First Pass: Geometry Sampling



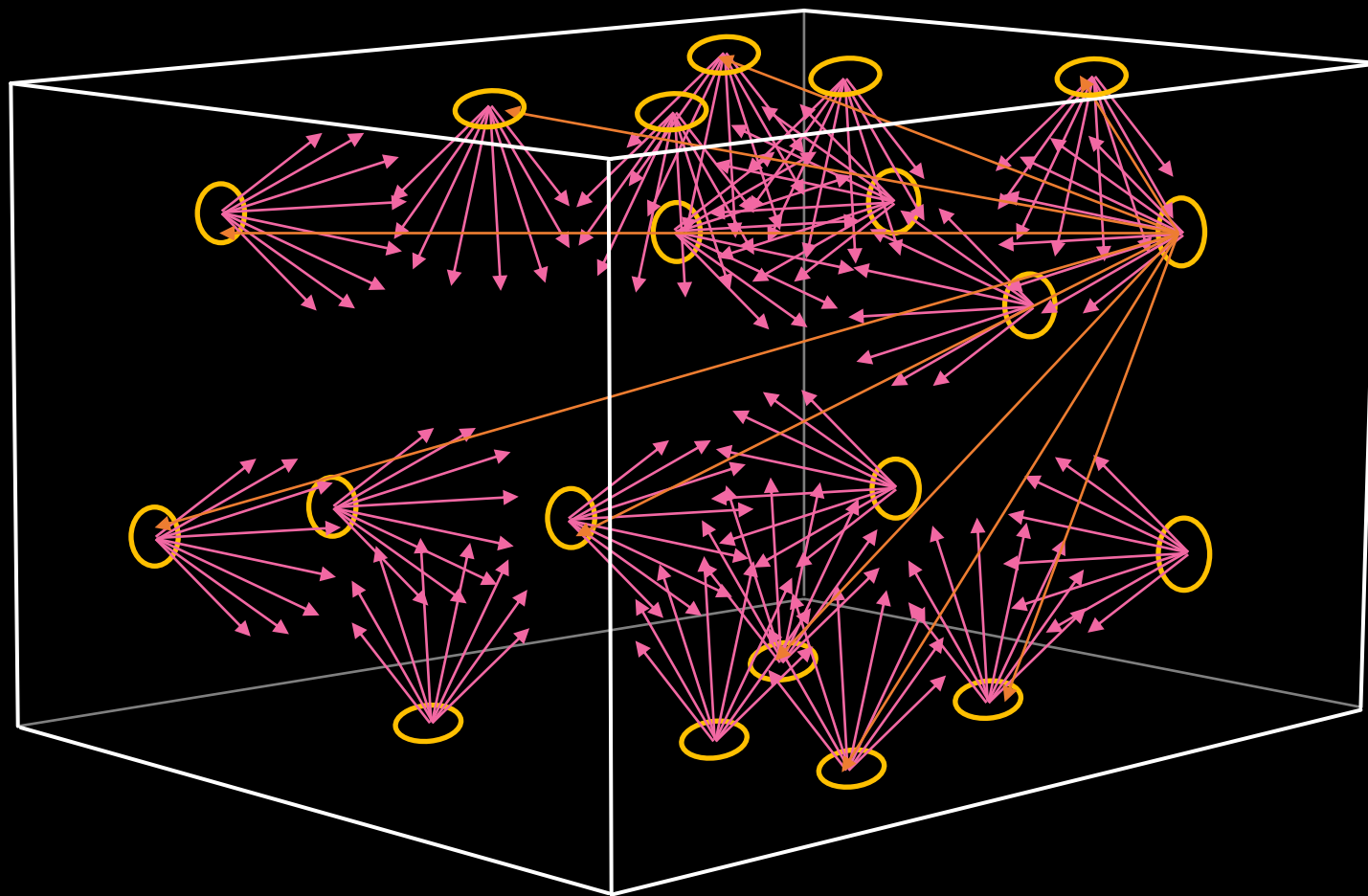
Second Pass: Ambient Sampling



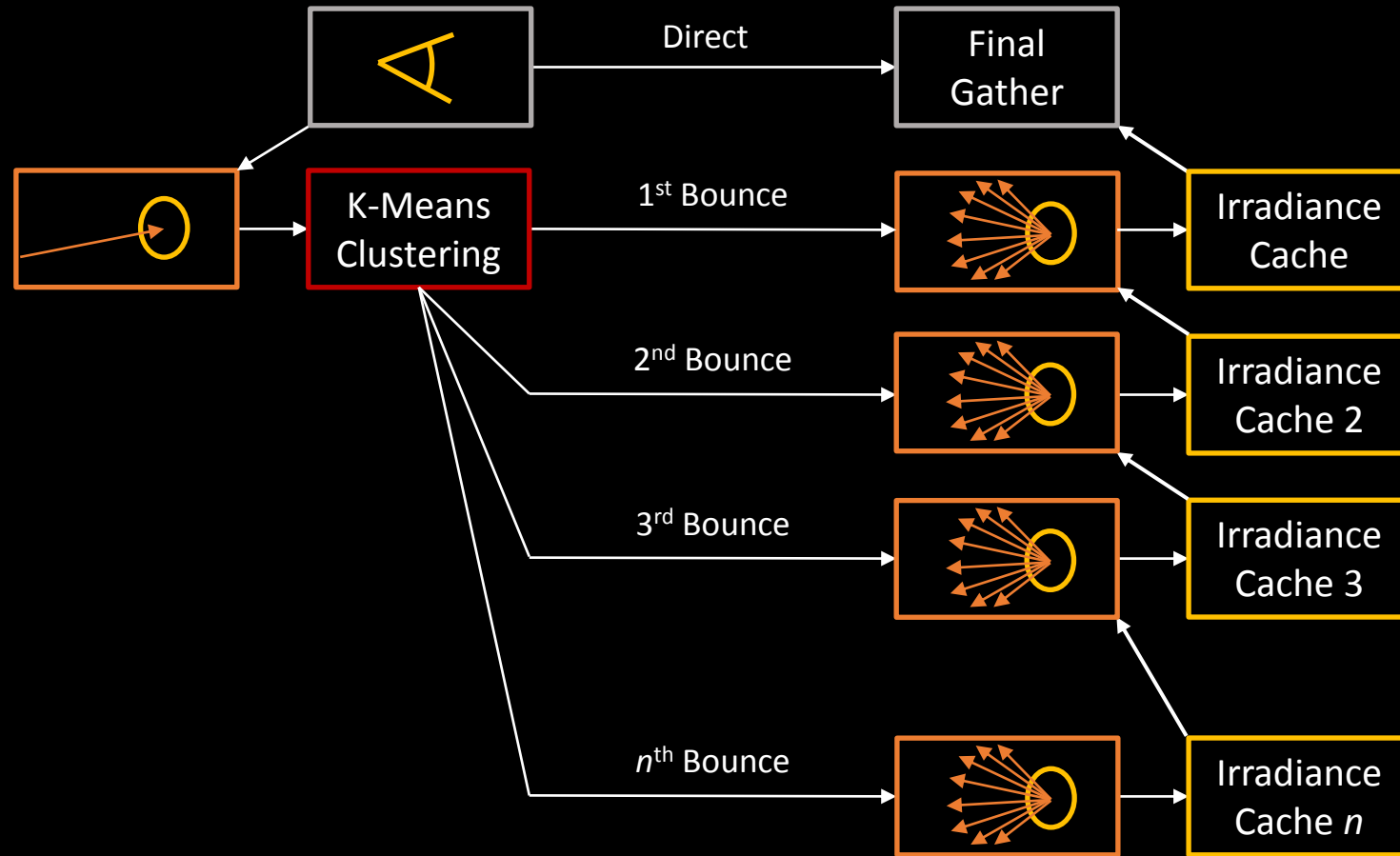
Parallel Irradiance Cache



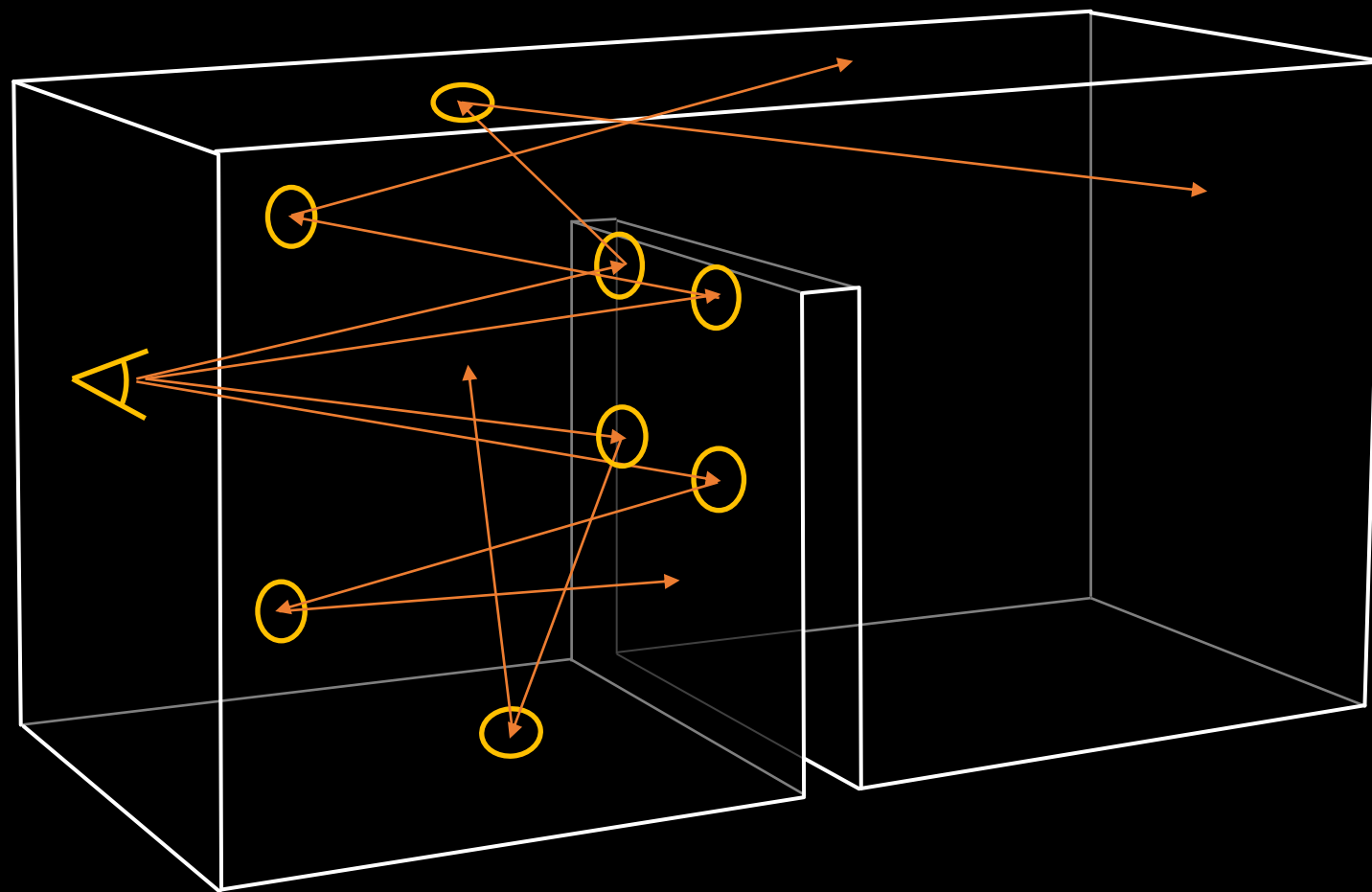
Ambient Sampling: Second Bounce



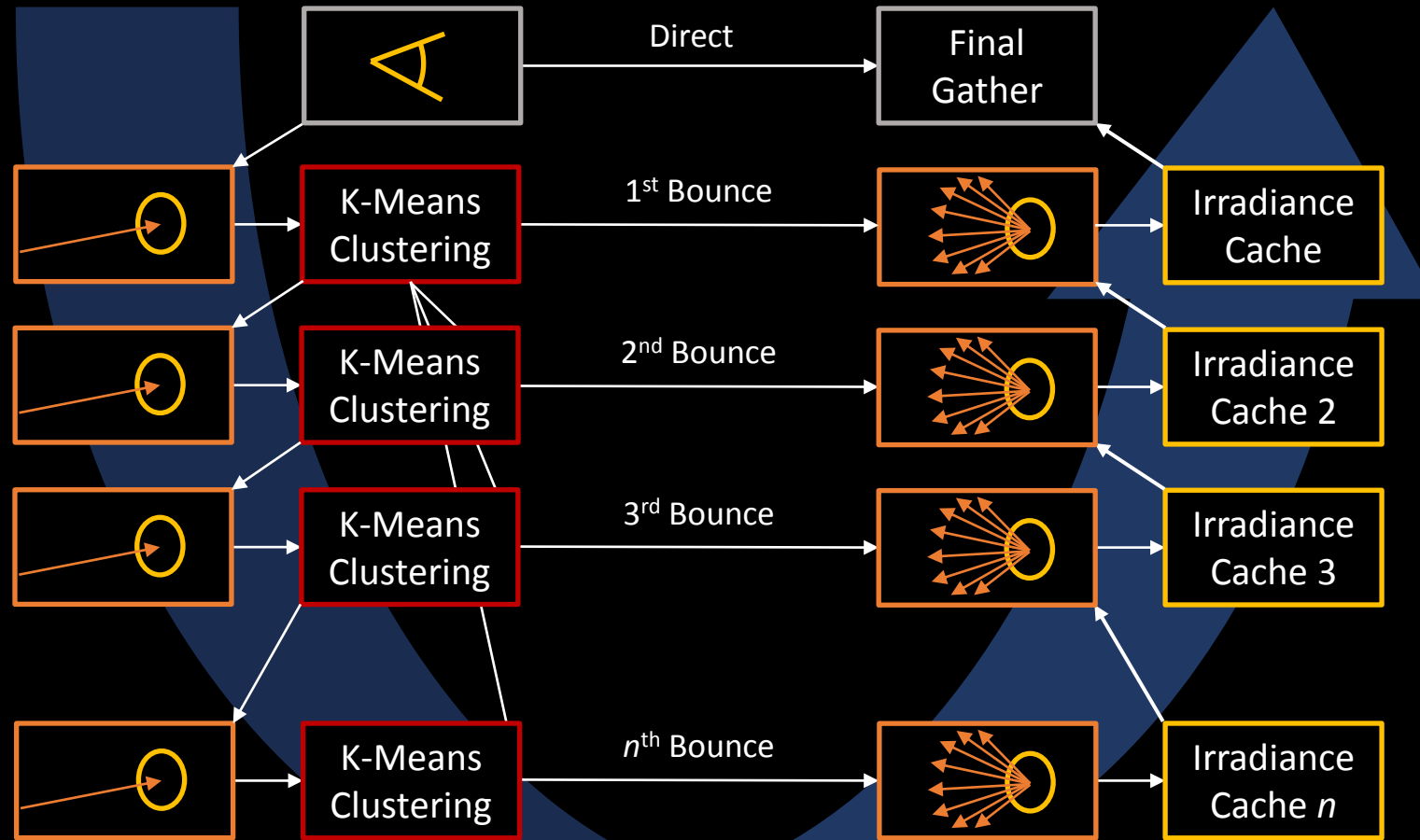
Parallel Multiple-Bounce Irradiance Cache



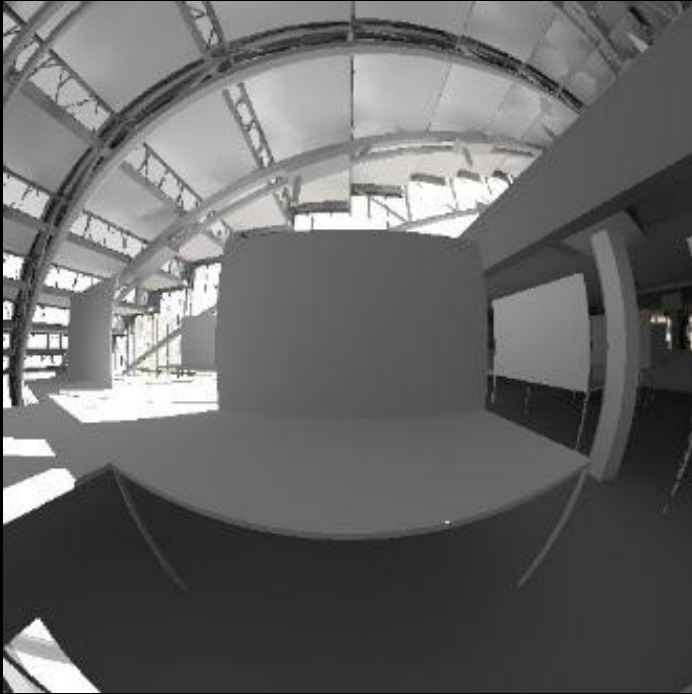
Shortcoming



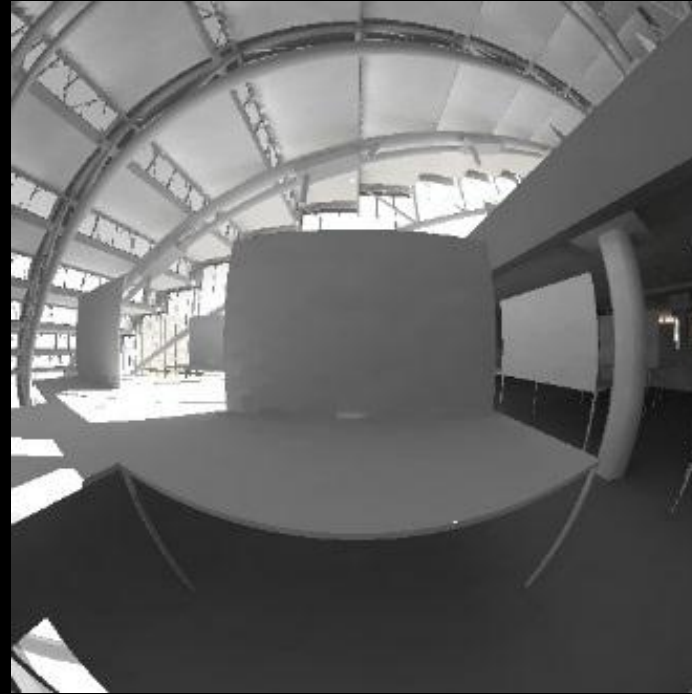
Parallel Multiple-Bounce Irradiance Cache



Results: 5 Ambient Bounces

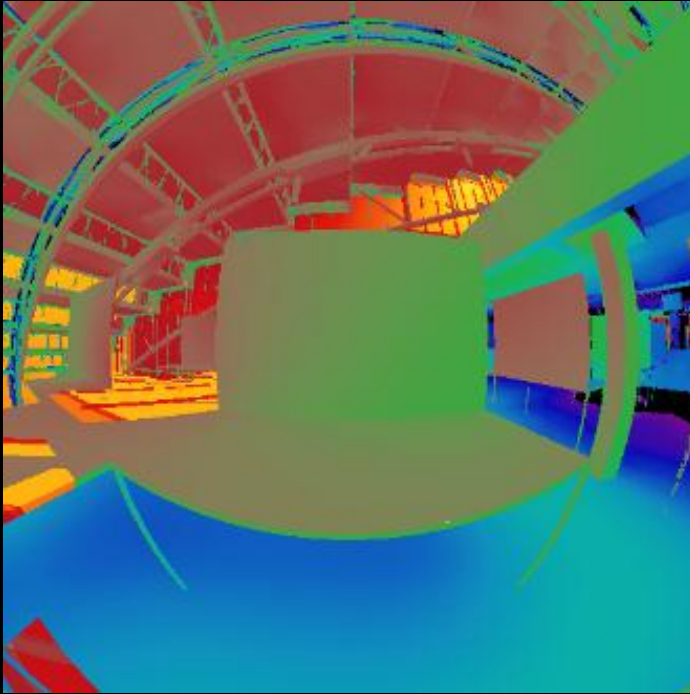


Accelerad
10 minutes

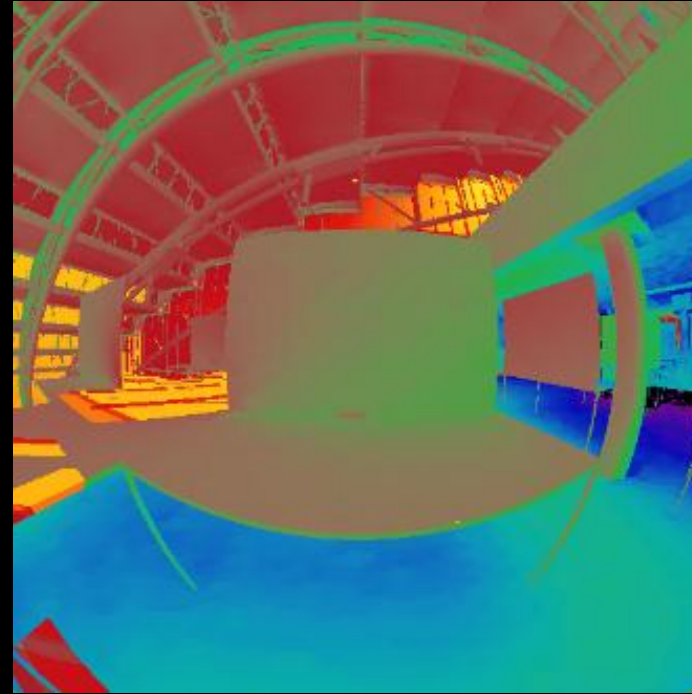


Radiance
198 minutes

Results: 5 Ambient Bounces



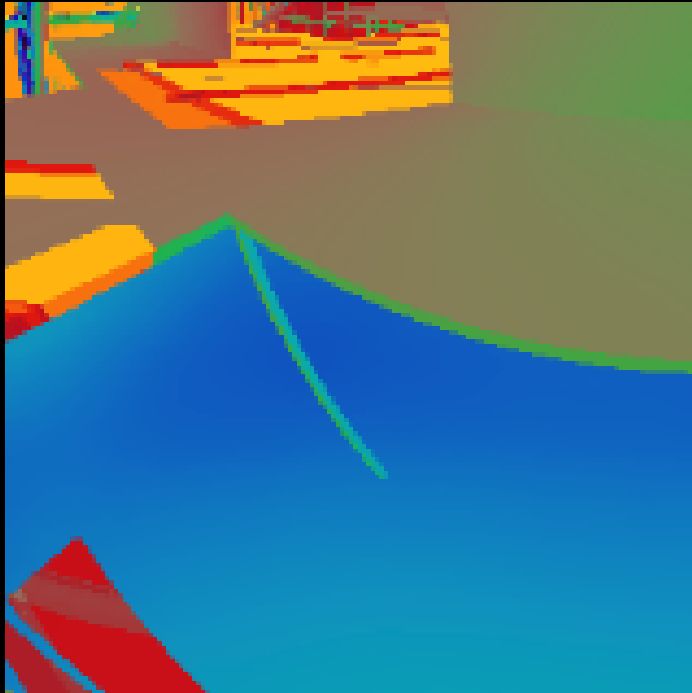
Accelerad



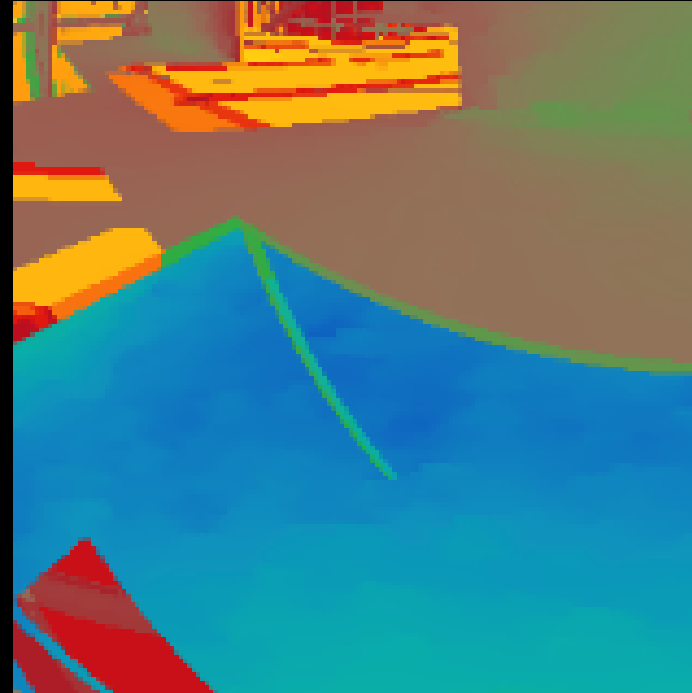
Radiance



Results: 5 Ambient Bounces



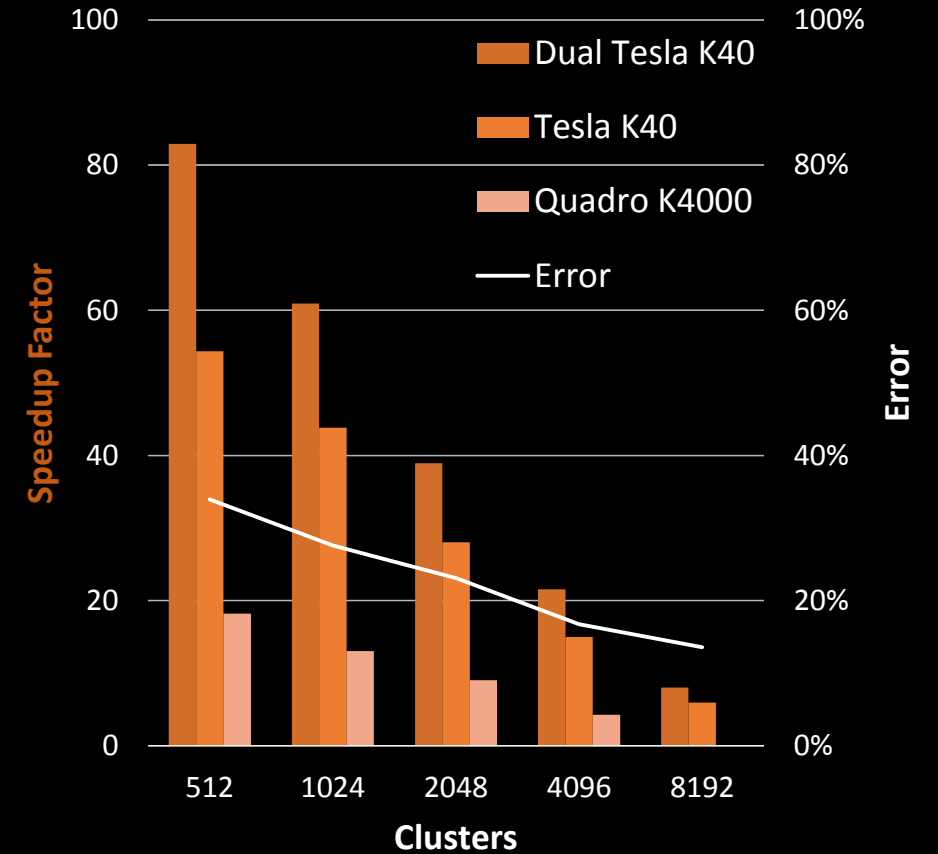
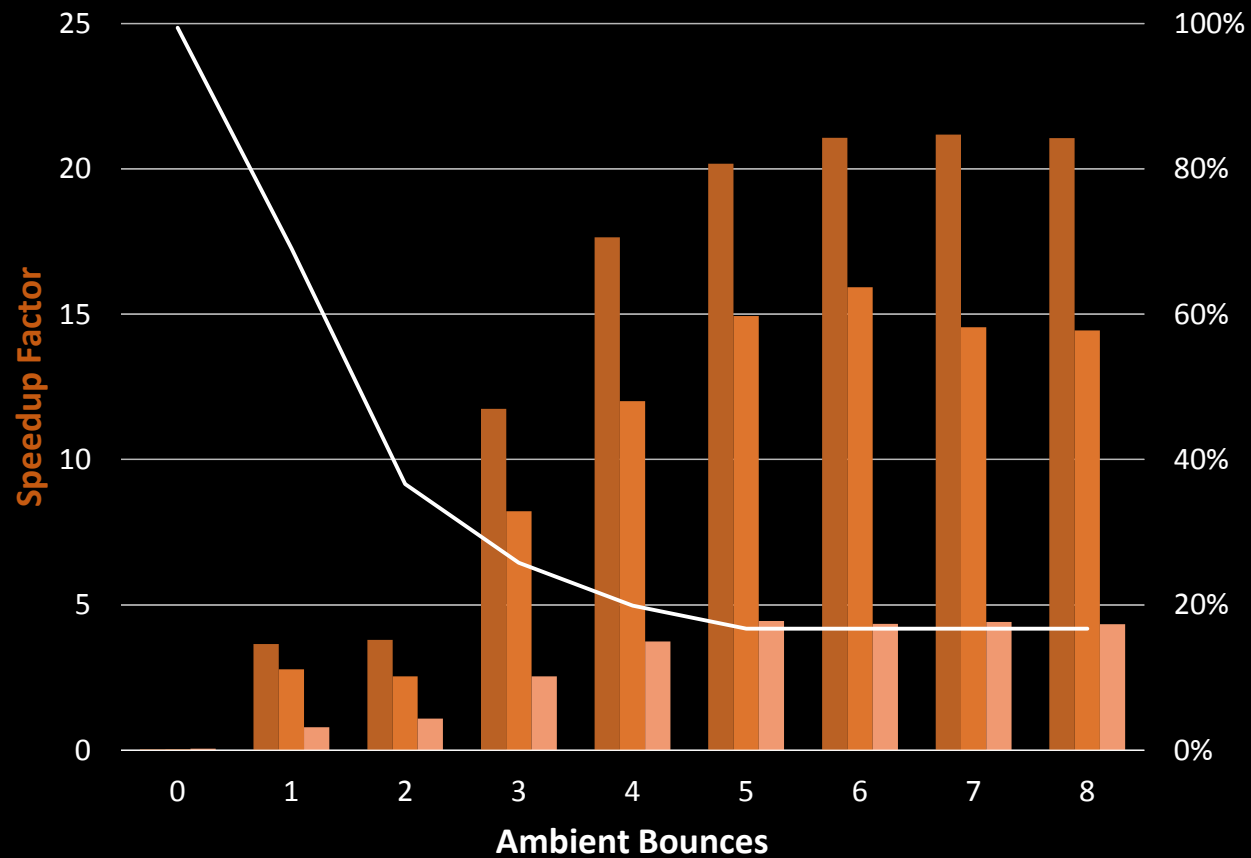
Accelerand



Radiance



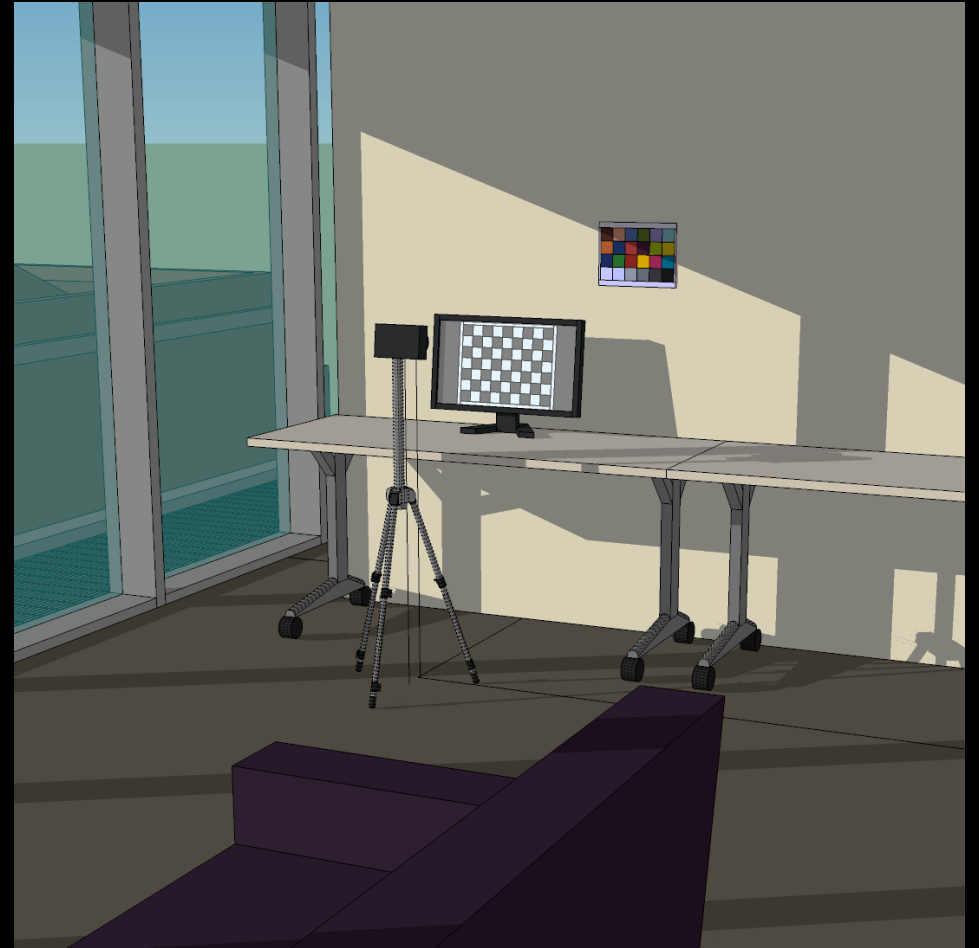
Speedup and Error



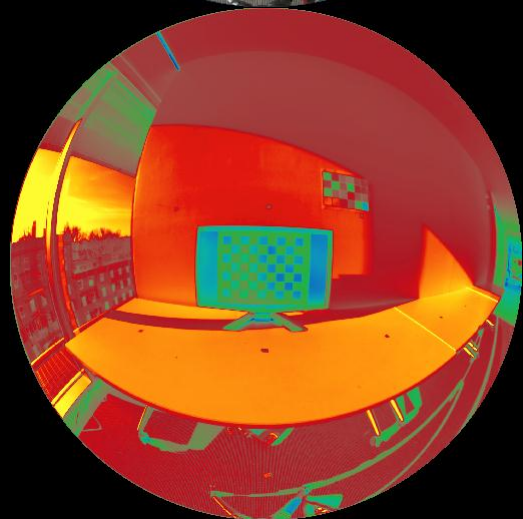
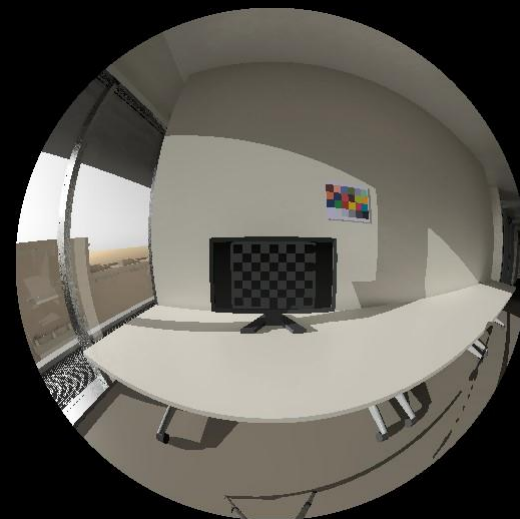
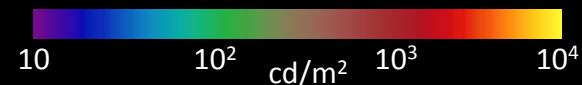


Global Illumination
Irradiance Caching
Validation Testing

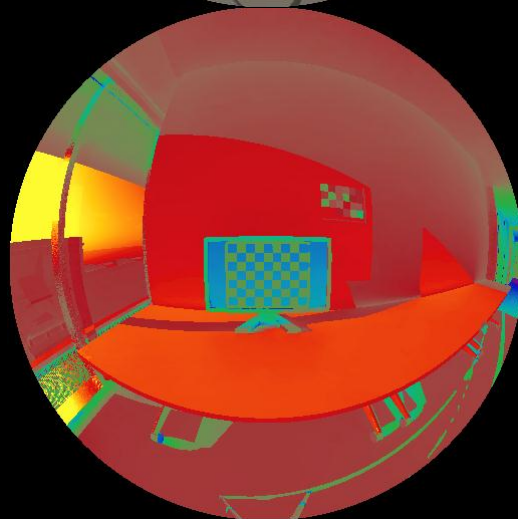
Validation Study



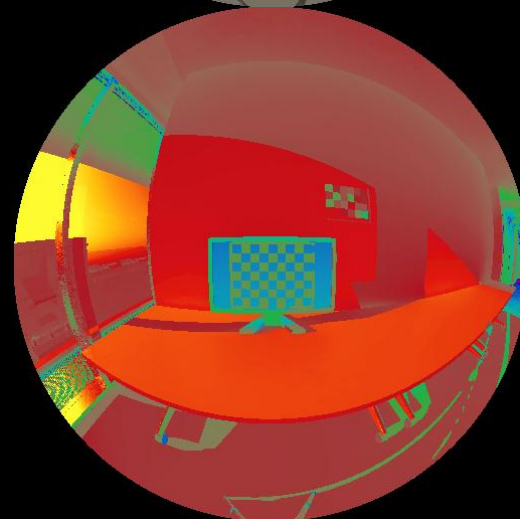
Clear Sky, 9:30 AM



HDR Photograph

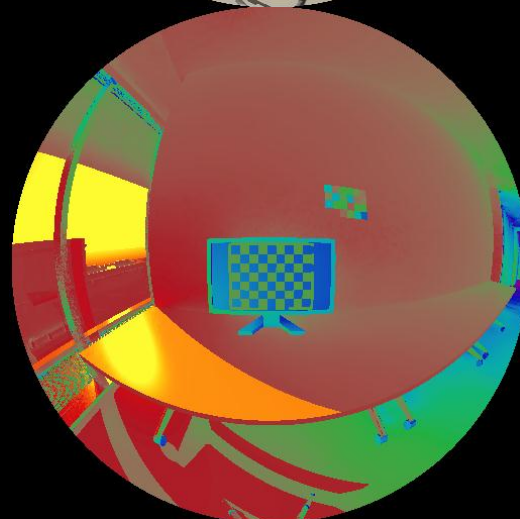
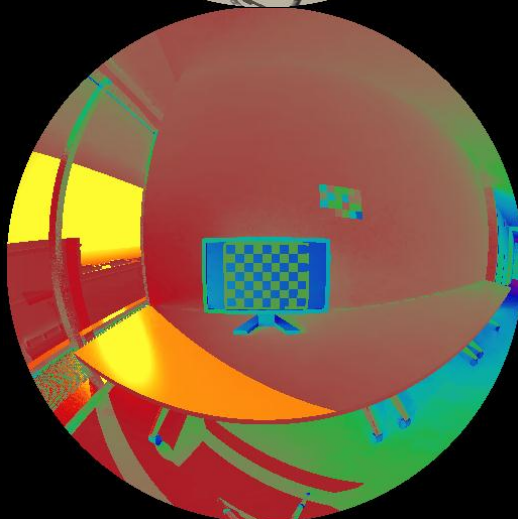
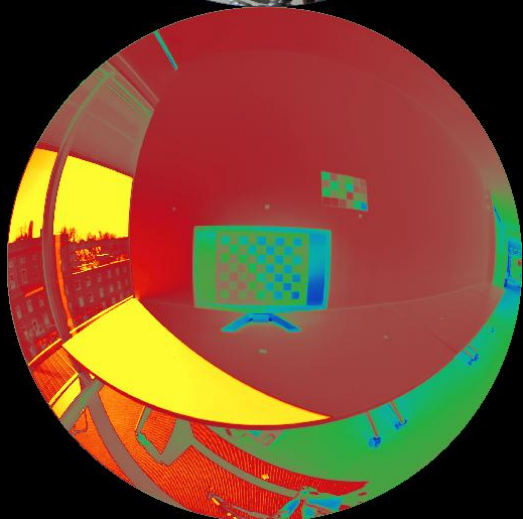
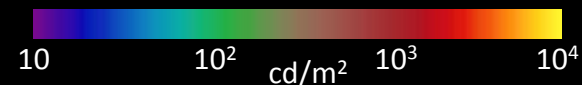


Radiance
303 Minutes



Accelerad
11 Minutes

Clear Sky, 12:30 PM

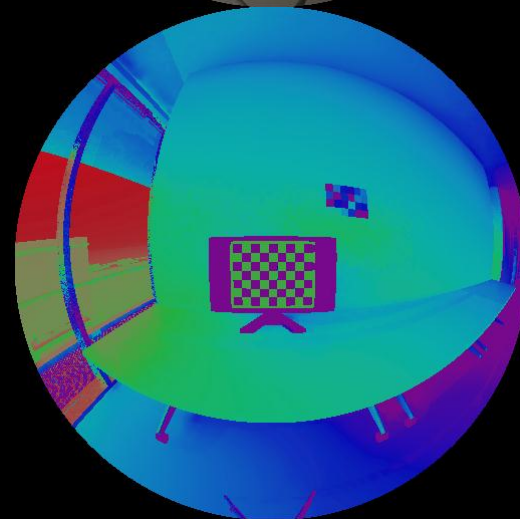
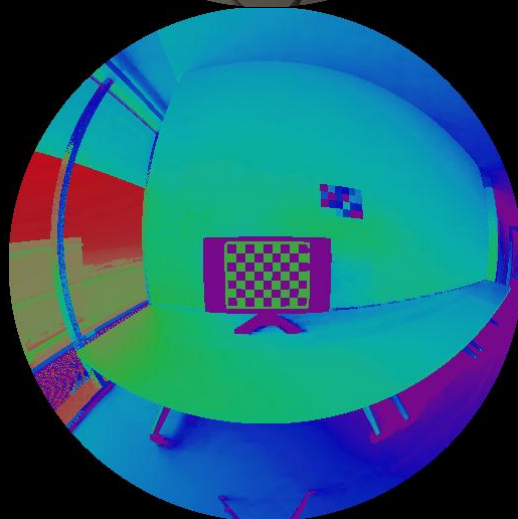
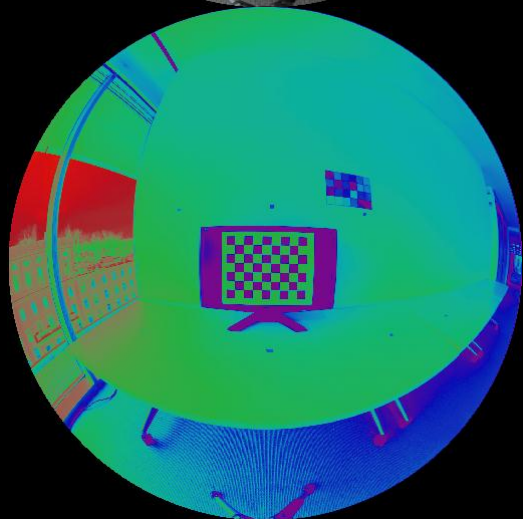
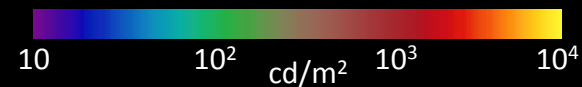


HDR Photograph

Radiance
321 Minutes

Accelerad
11 Minutes

Overcast Sky



HDR Photograph

Radiance
294 Minutes

Accelerad
12 Minutes

Visual Comfort Metrics



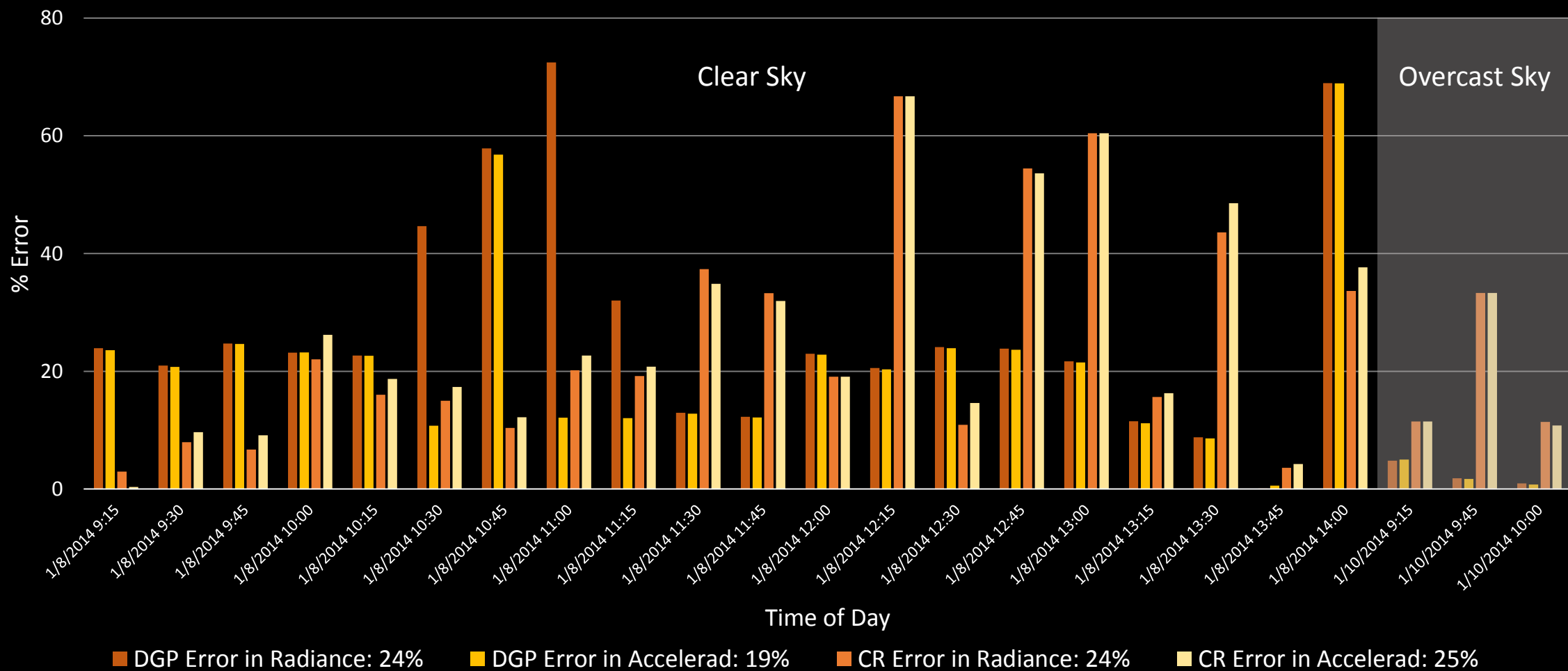
Daylight Glare Probability (DGP)

$$DGP = 5.87 \times 10^{-5} E_v + 0.0918 \times \log_{10} \left(1 + \sum_{i=1}^n \frac{L_{s,i}^2 \omega_{s,i}}{E_v^{1.87} P_i^2} \right) + 0.16$$

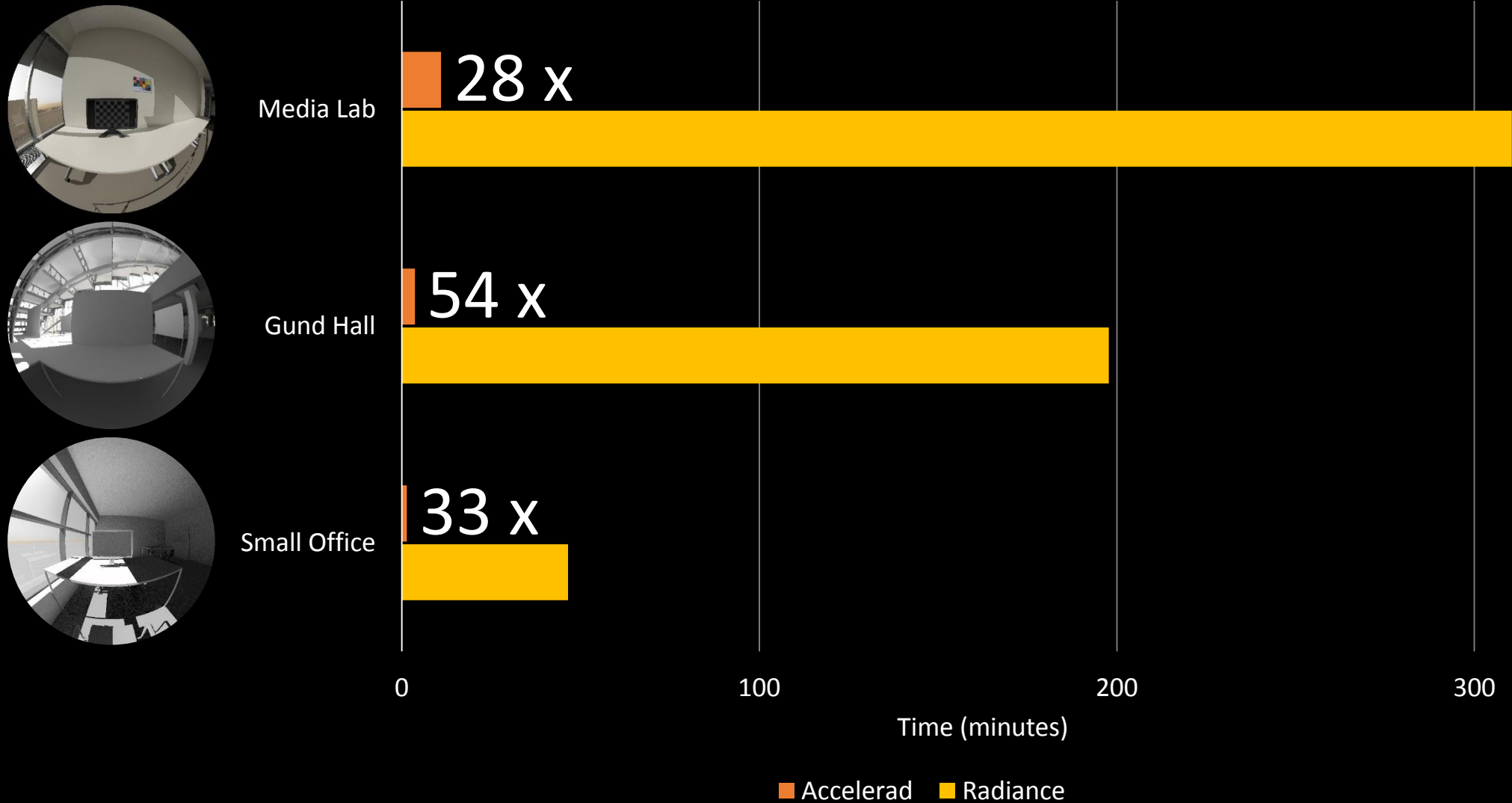
Monitor Contrast Ratio (CR)

$$CR = \frac{L_H + L_r}{L_L + L_r}$$

Accuracy



Speedup



Where Are We Going?

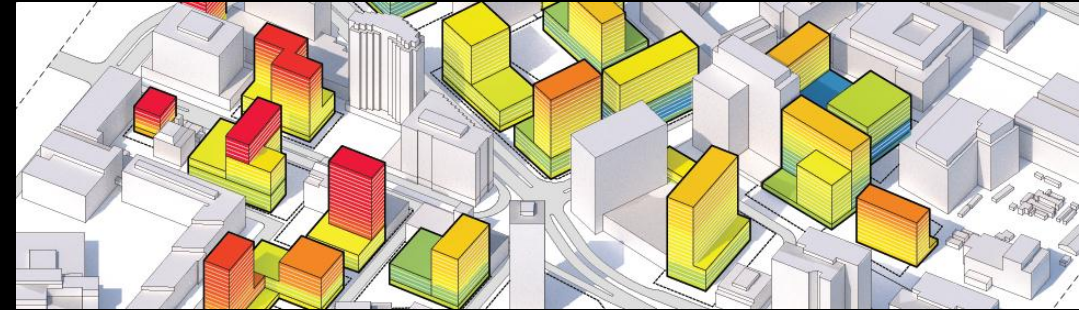
Annual simulation using **daylight coefficients**

Spatial mapping for **adaptive glare analysis**

Detailed spectral analysis for **alertness** and **health**

Optimized number and location of **ambient records**

Performance optimization



Thanks



Information

<http://mit.edu/sustainabledesignlab/projects/Accelerad/>

Questions?

Nathaniel Jones <nljones@mit.edu>