Energy-efficient Distributed GPU Communication

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GPU-centric Communication

Cluster systems increasingly deploy accelerators like GPUs to stay within a given power budget, limited by the end of Dennard Scaling. Since then, various applications have been ported to CUDA to make use of the computational power of GPUs. However, communication is still crucial, both in terms of performance but also energy efficiency. Communication between GPUs is done by traditional CPU-tailored communication methods, such as the Message Passing Interface (MPI). This is shown here:



In order to move data, the GPU has to copy the data to the CPU first (1). Next, the data is sent to the target CPU (2,3,4) and copied to the target GPU memory (5).

We already introduced a direct communication method, avoiding any interference with the CPU. The CPU is entirely bypassed and control flow can stay on the GPU for the whole application. Context switches are no longer necessary, resulting in savings regarding energy and time. The approach is shown here:



The GPU is able to trigger communication by controlling directly the Network Interface Controller (NIC) (1). On the target side, the NIC writes the data into the GPU memory without any staging copies (2). Currently, we have implemented two approaches of direct GPU-GPU communication:

- GGAS: inline with the execution model of GPUs, the data is sent collaboratively by all threads. The NIC forwards memory operations like loads and stores and completes them on the target side. [1]
- GPU RMA: a Put/Get model, whereby one thread creates a Work Request (WR) and the NIC handles the communication. The GPU is released from sourcing the data and can continue with computations. [2]



faster.

following figure.



found in [3].





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