CATEGORY: DEVELOPER - PERFORMANCE OPTIMIZATION - D006 CONTACT NAME Eyal Rozenberg: eyal.rozenberg@huawei.com P5300





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Motivation and contribution summary

- An ongoing concern of the IC&T industry is maximizing analytic DBMS performance – with GPUs showing some promise towards this end.
- Previous works have shown speedups through the use of a GPU, but it was still unclear if their solutions are competitive with more performant CPU-based DBMSes.

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Realized plan execution

Our AXE execution environment uses its device abstraction layer to schedule execution on multiple devices.

Possible optimizations include:

- Overlapped I/O & computation
- Simultaneous I/O to multiple devices
- Parallel multi-device execution
- Graph node task parallelism
- Graph node data parallelism



... but it's generally not useful to apply these all together to any single subgraph.

Multiple device support via graph partitions

Multi

The AXE execution environment receives a 'Logical' Execution Graph, from an (arbitrary) application.

2. This graph is then partitioned into subgraphs; each can be assigned to a subset of the available devices (CPUs and GPUs).

3. Subgraphs are replicated for processing on multiple devices, with splitter/joiner nodes effecting partitions of the data.

4. I/O operations are added as necessary to move data between devices' memory spaces.

The Logical Execution Graph is now a **Realized Execution Graph** ready for execution by **AXE's Run-Time Engine**.



Questions to ponder: - Where do splitters/joiner nodes get run? - Why do we choose certain nodes for a subgraph? - Why choose only some devices for subgraph execution?

Towards a real GPU-speedup in SQL query processing with a new heterogeneous execution framework

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