

How I Got Back my Coding Mojo!



Mark West

Safe Harbour



What is Mojo?



A meme featuring two people. On the left, a woman with dark hair and a black halter top with a diamond necklace looks towards the right. On the right, a man with brown hair and glasses, wearing a pink striped shirt, has a shocked expression with wide eyes and an open mouth. There are red, bruise-like marks on his face and neck. The background is a plain wall with a white object on the right.

OH NO!

I'VE LOST MY MOJO!



A large, dark gray 'JS' logo is centered on a bright yellow square background. The letters are bold and sans-serif.

*“Any application that can be
written in JavaScript, will
eventually be written in
JavaScript”*

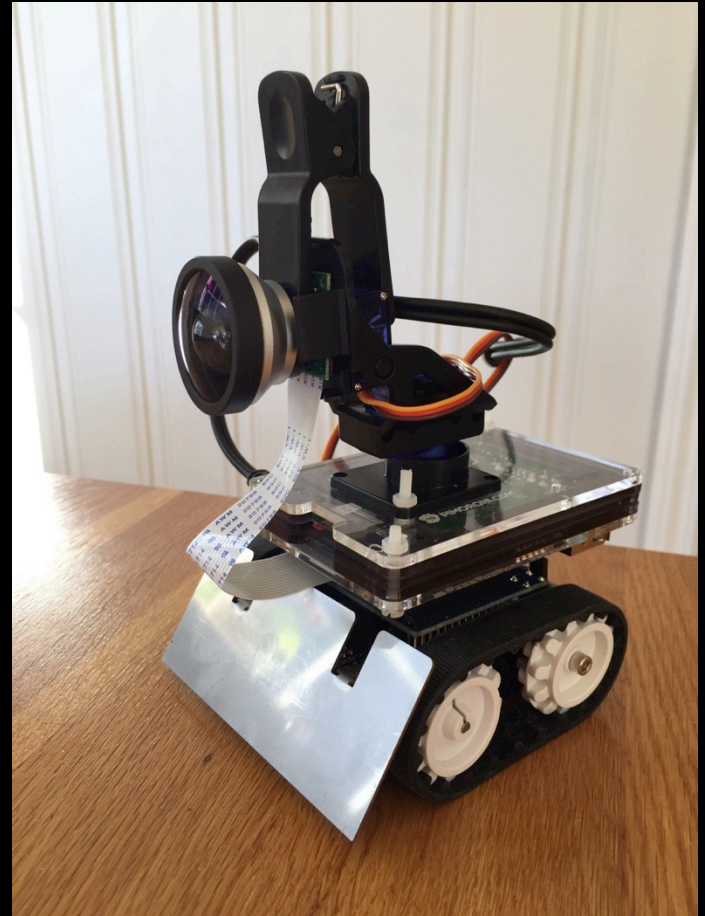
James Atwood (founder, stackoverflow.com)



[illegible]

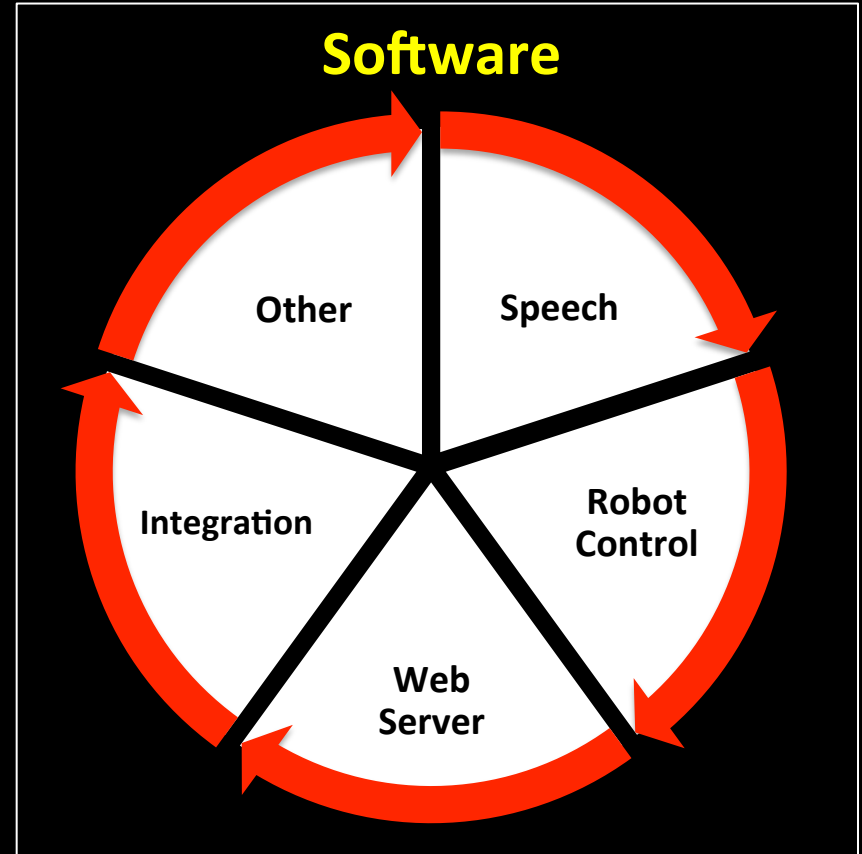
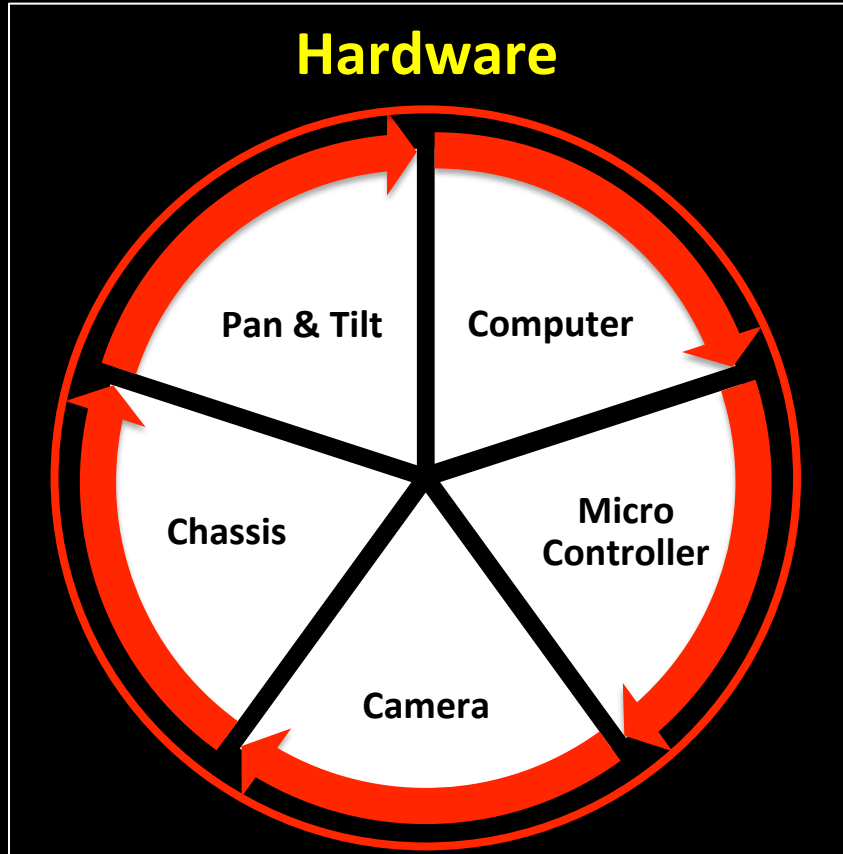
NodeBot Rover

ARDUBERRY
RASPBERRYPI HTML5
SPEECH-RECOGNITION
JAVASCRIPT JOHNNY-FIVE
NODE.JS WEBSOCKETS BROWSERIFY
ARDUINO
MQTT



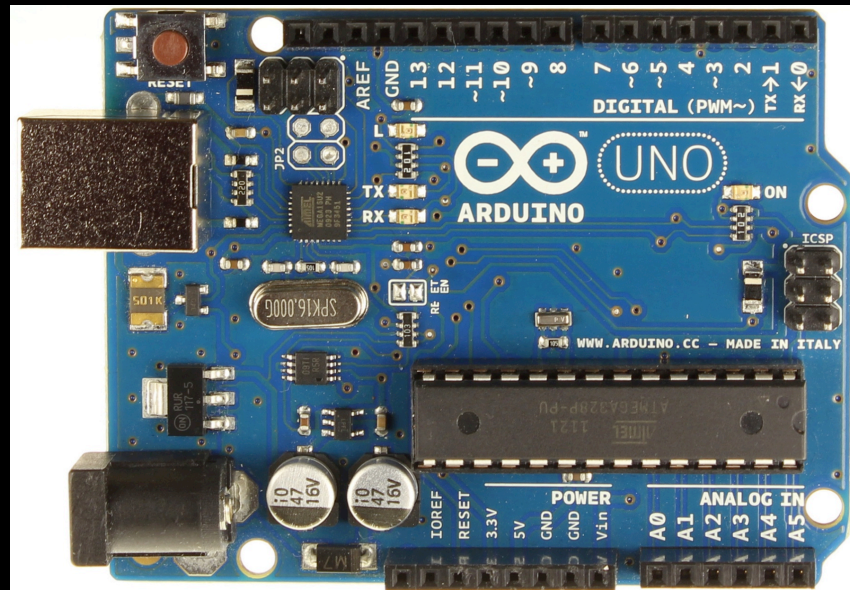
NodeBot Rover Demo

NodeBot Rover Component Overview



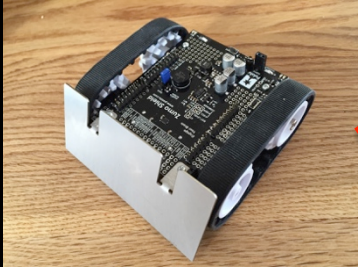
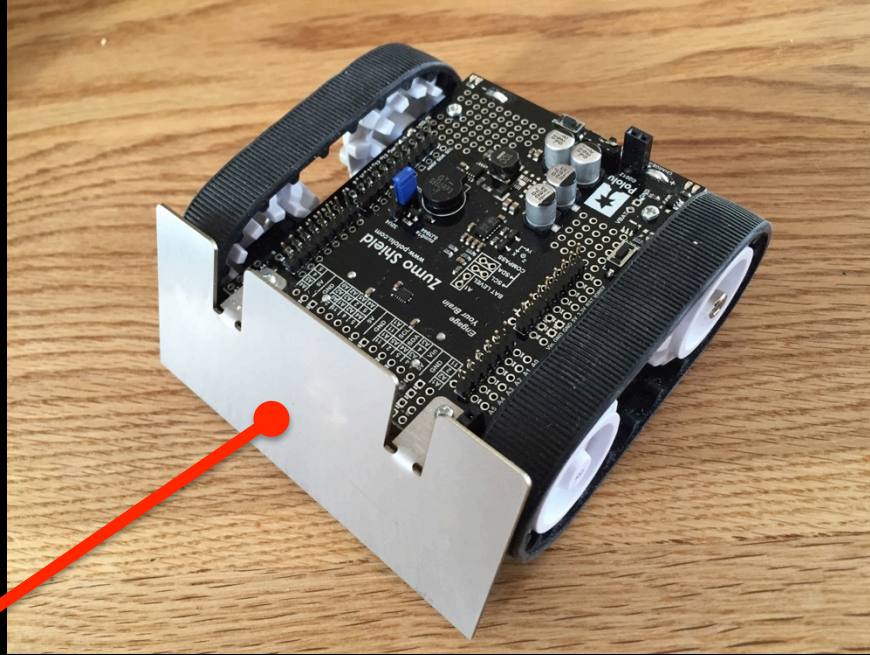
The Arduino Ecosystem

- MicroController platform.
- Many different Arduino models.
- Open Source design.
- MicroControllers extensible via “Shields”.

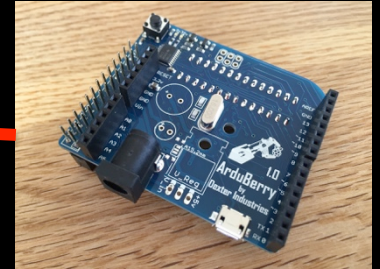
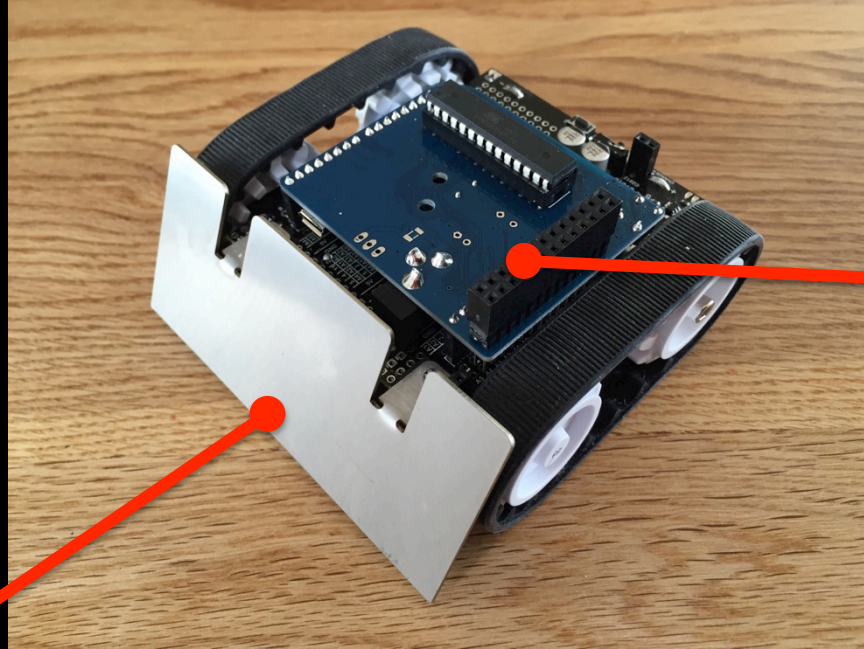
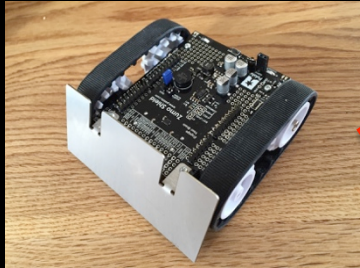


Putting the Hardware Together

Arduino Chassis



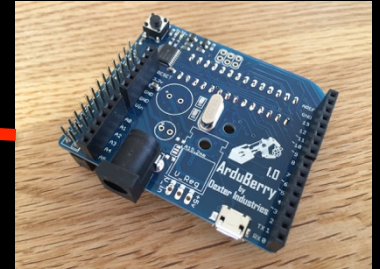
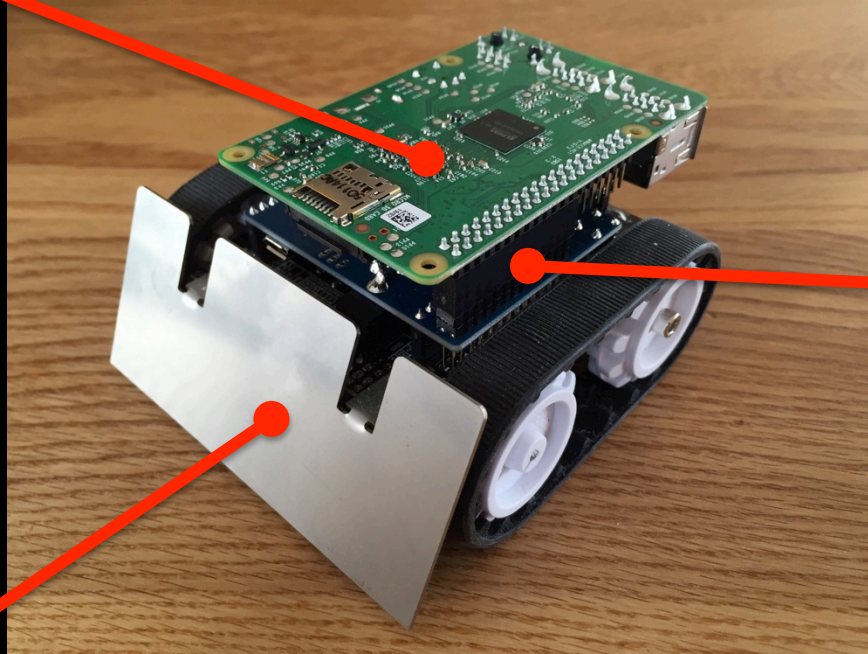
Arduino Chassis



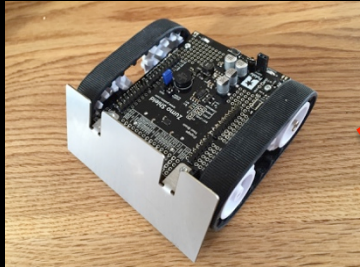
**Arduberry
MicroController**



Raspberry Pi 2



**ArduBerry
MicroController**



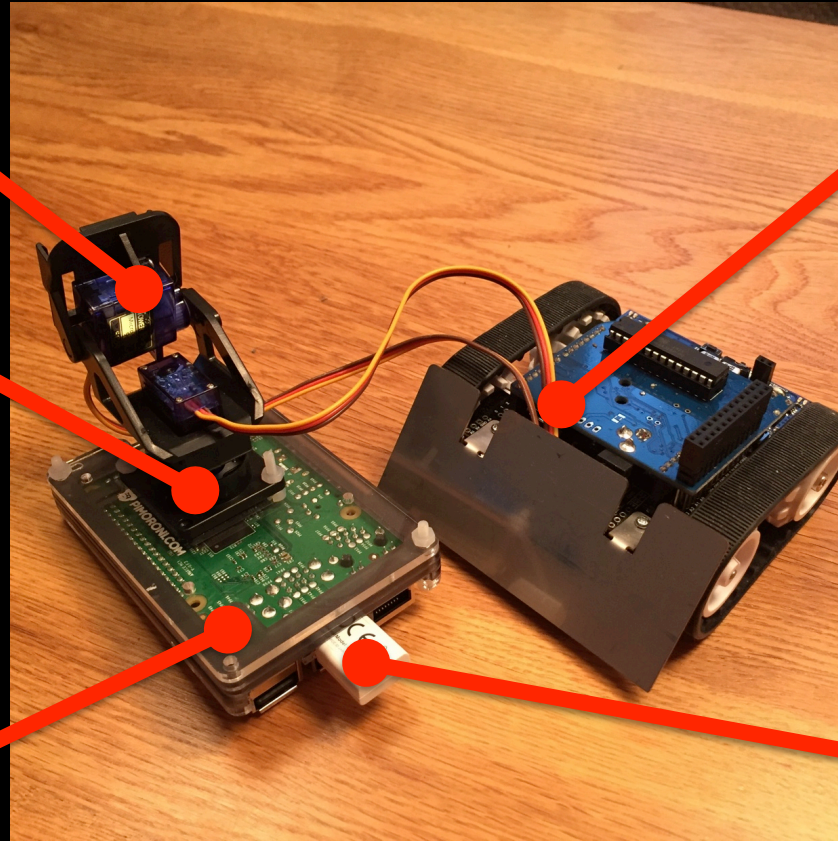
Arduino Chassis

**Two Servos
for Camera
Pan & Tilt**

**Servos wired
to Arduino
Chassis**

**Raspberry Pi
In Plastic Case**

WIFI Dongle

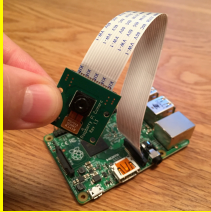


A hand is holding a Raspberry Pi camera module, which is being connected to a Raspberry Pi board via a ribbon cable. Red lines and dots highlight the connection points on the camera module and the Pi board.

A hand is holding a Raspberry Pi camera module, which is being connected to a Raspberry Pi board via a ribbon cable. Red lines and dots highlight the connection points on the camera module and the Pi board.

NodeBot Rover Hardware

Sensors



Raspberry PI Cam

Brain



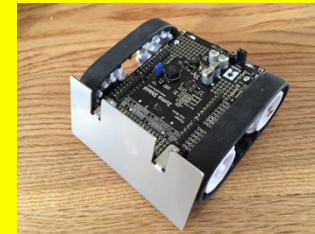
Raspberry PI 2

Nervous System



Arduberry Microcontroller

Actuators



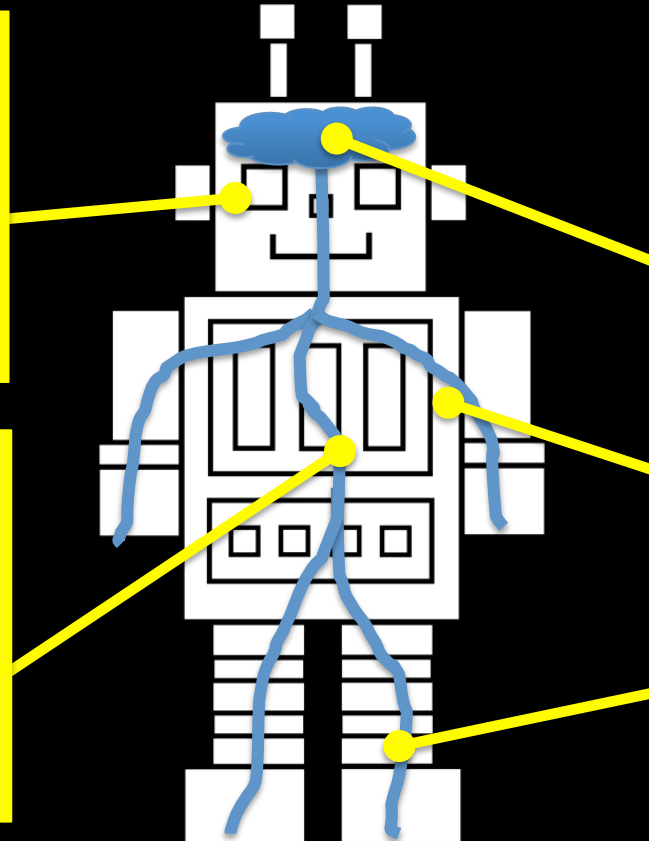
Arduino Chassis



Servo



Servo



Combining the Raspberry PI & Arduino

Raspberry PI

- Linux PC.
- Supports USB peripherals.
- Programming.

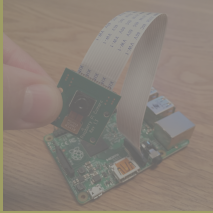
Arduino Platform

- MicroController.
- Robust.
- Flexibility (input/output).

The whole is greater than the sum of parts!

NodeBot Rover Hardware

Sensors



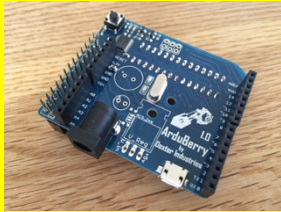
Raspberry Pi Cam

Brain



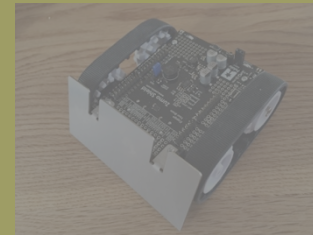
Raspberry Pi 2

Nervous System



Arduberry Microcontroller

Actuators



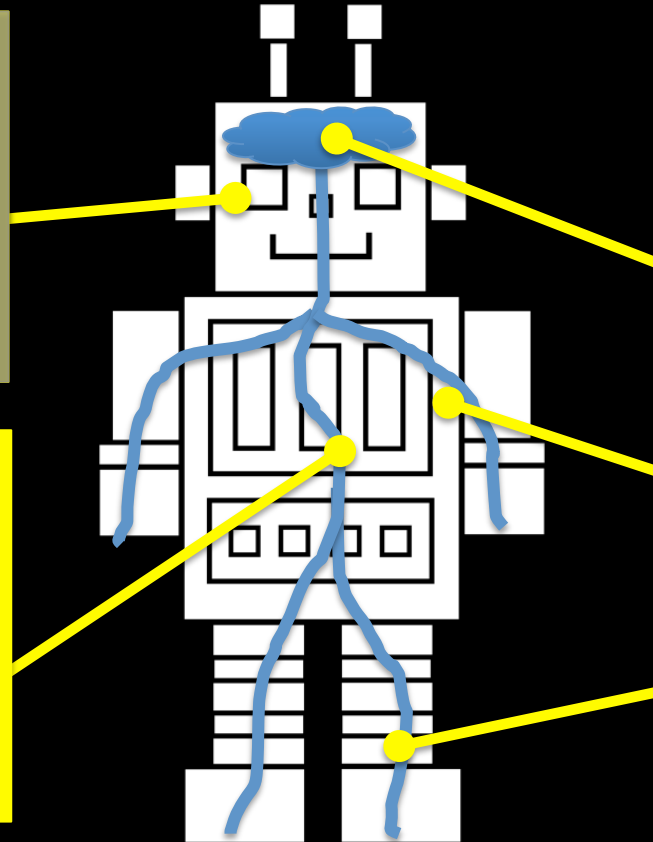
Arduino Chassis



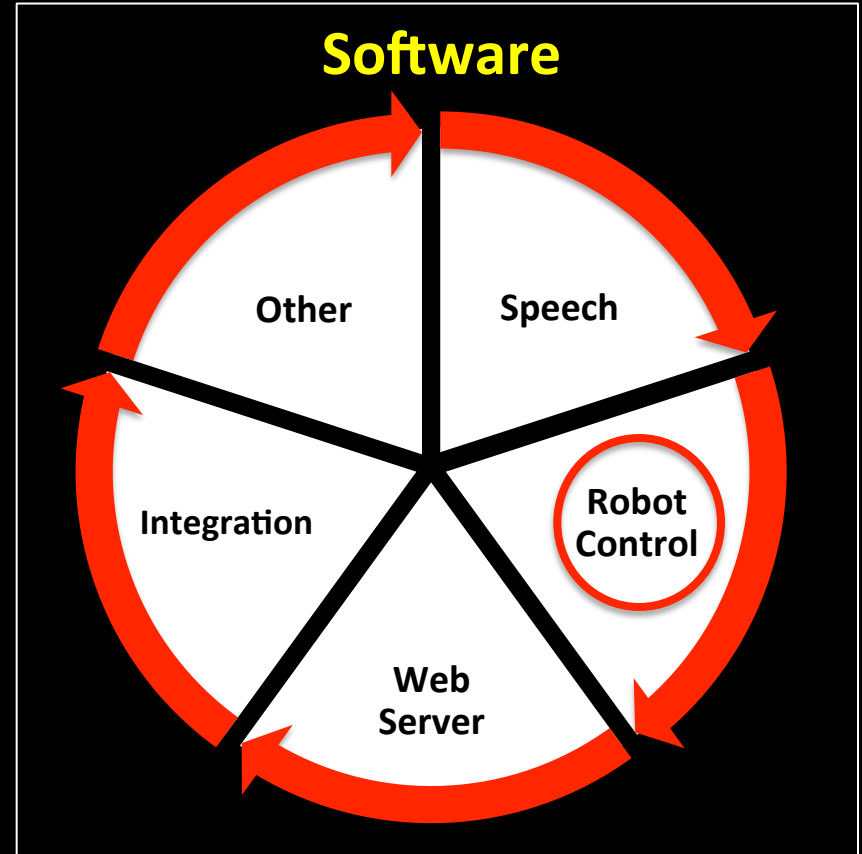
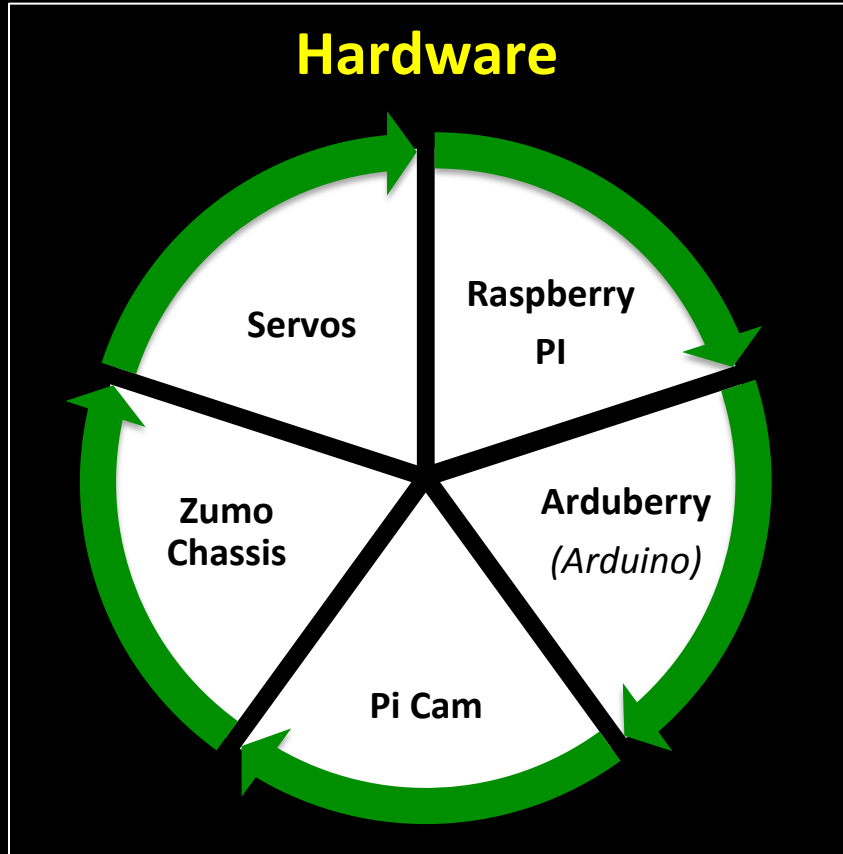
Servo



Servo



NodeBot Rover Component Overview

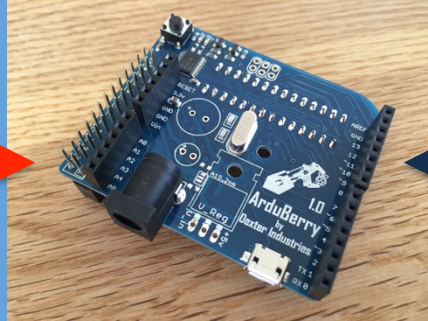


Software Communication across Hardware Layers

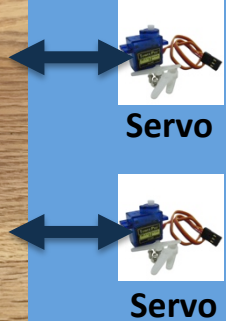
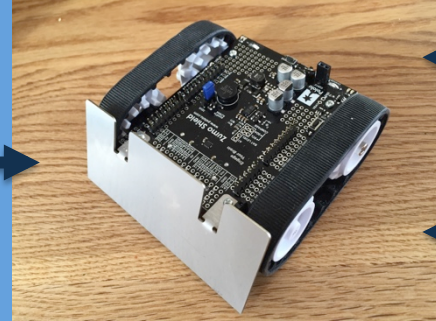
Raspberry PI



Arduberry



Chassis



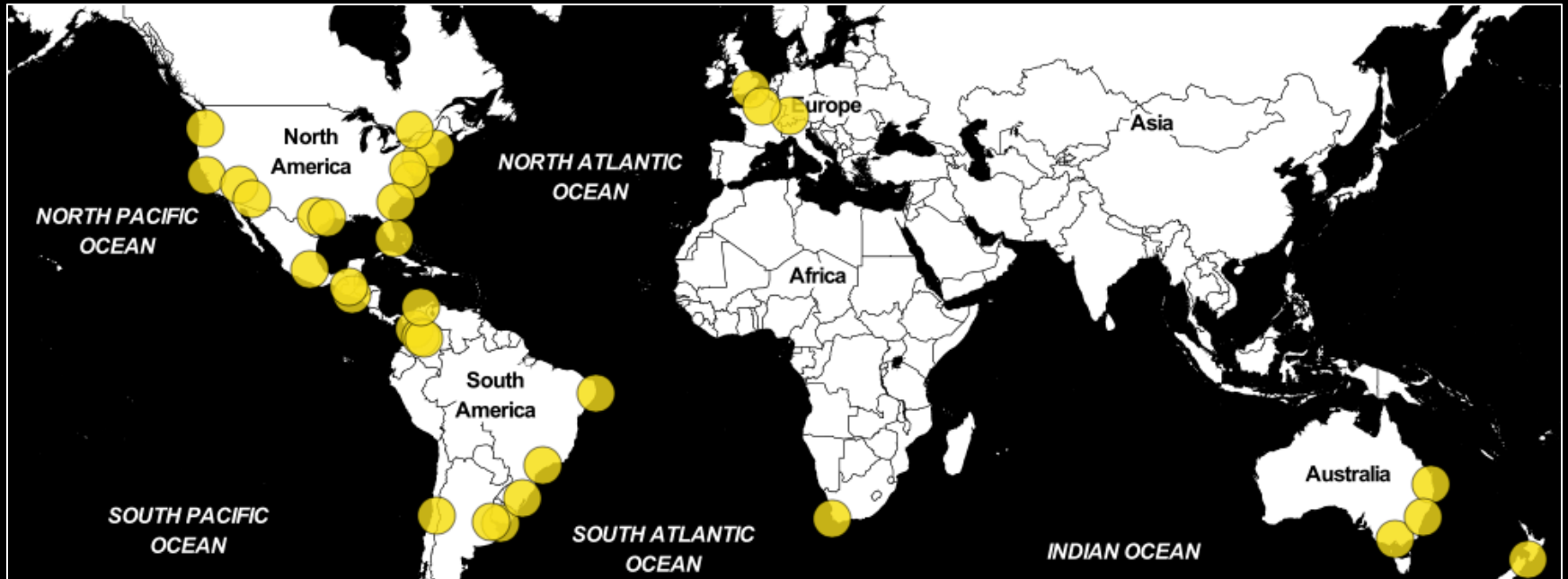
Servo

Servo

{ JavaScript }

{ Binary (Compiled C / C++) }

The NodeBots Movement



Source : nodebots.io

J5

[Home](#)

[News](#)

[API](#)

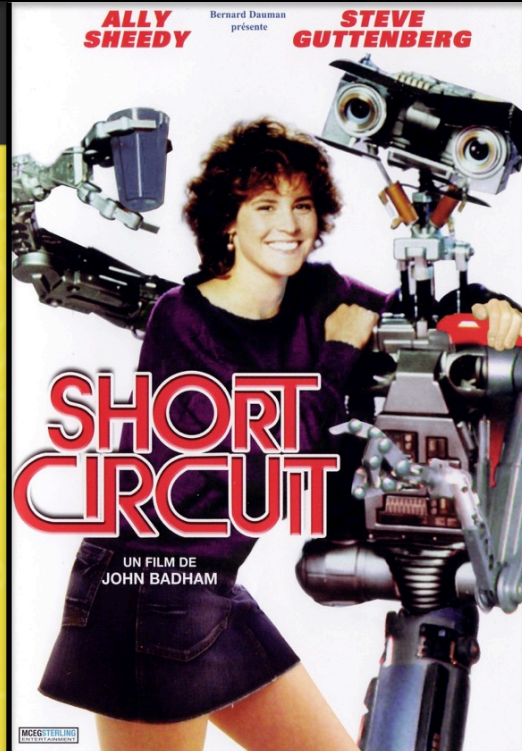
[Examples](#)

[Articles](#)

[Platform Support](#)

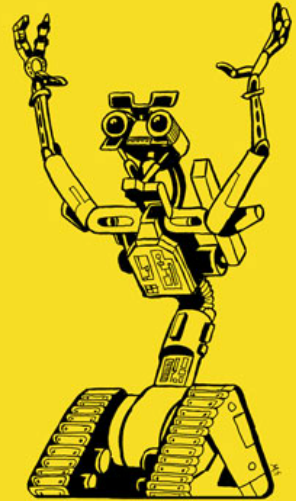
Johnny-Five

The JavaScript Robotics
Programming Framework



Benefits of using Johnny-Five

1. Maturity
2. Community
3. DSL
4. Portability
5. Open Source
6. Node.js ecosystem
7. REPL



Johnny-Five Code Example

```
var five = require("johnny-five");
```

Imports J5 Dependency

```
var myBoard = new five.Board();
```

Initialises UNO

```
myBoard.on("ready", function() {
```

Code block triggered by UNO "Ready" Event

```
    var myLed = new five.Led(13);
```

Declares LED as connected to UNO Pin 13

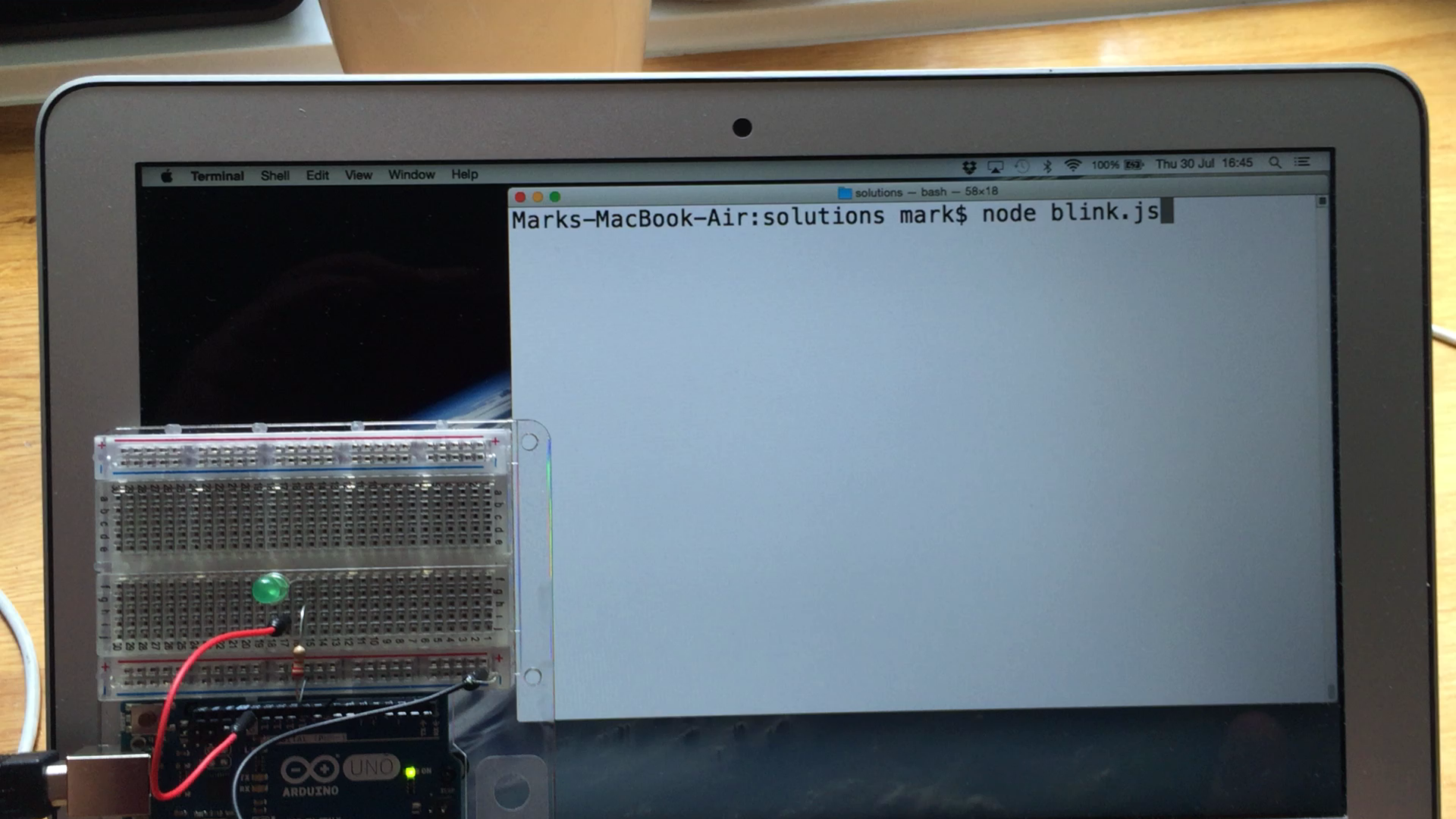
```
    myLed.blink(500);
```

Blinks LED every 500 milliseconds

```
    this.repl.inject({  
        replLed: myLed  
    });
```

Adds LED instance to REPL

```
});
```

Terminal Shell Edit View Window Help

solutions -- bash -- 58x18

Marks-MacBook-Air:solutions mark\$ node blink.js

ARDUINO UNO

Bridging the gap with Firmata

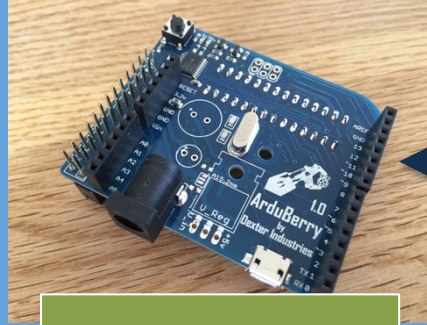
Raspberry PI



Johnny-Five
(Firmata Client)

{ JavaScript }

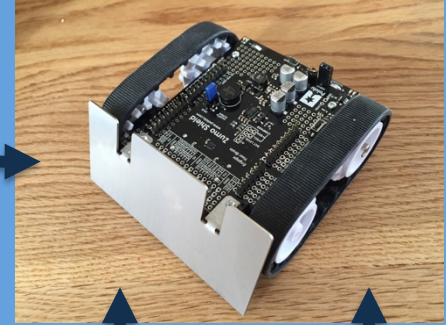
Arduberry



Std. Firmata
(Firmata Server)

{ Binary (Compiled C / C++) }

Chassis



Servo



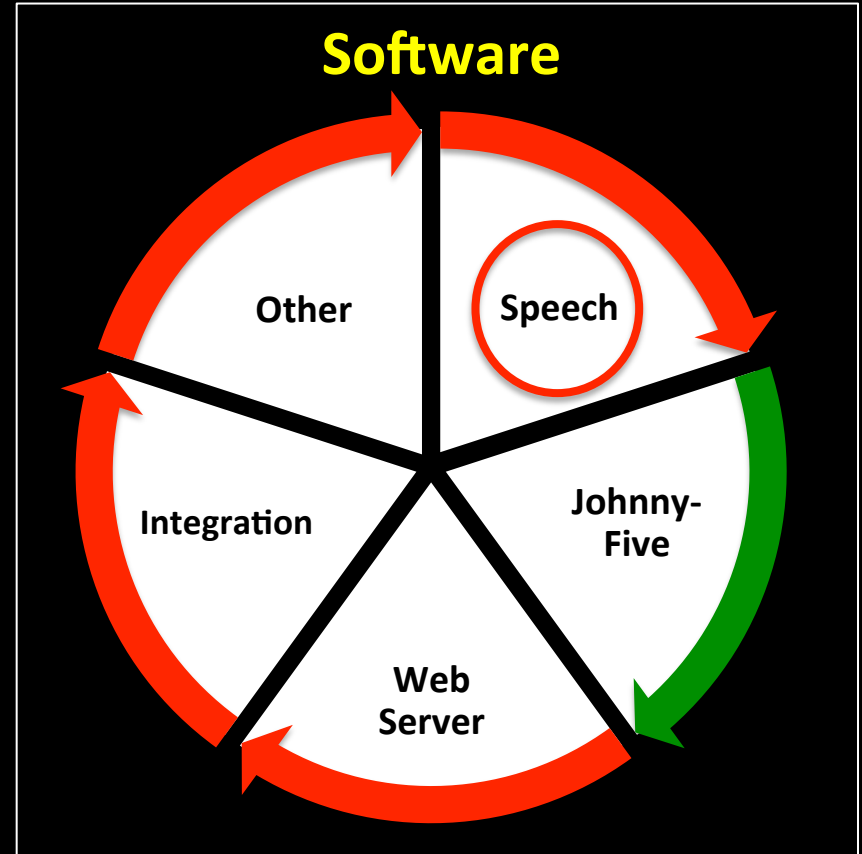
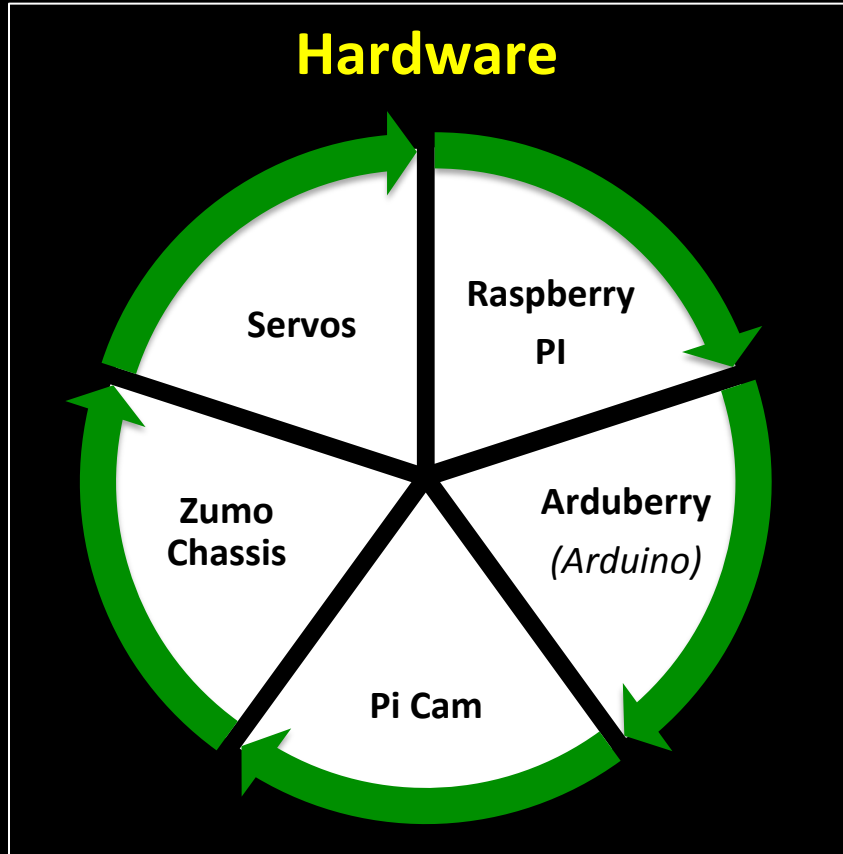
Servo



Getting Started with Johnny-Five

1. Buy an Arduino Experimenters Kit.
2. Follow the tutorials at <http://node-ardx.org>.
3. Visit <http://johnny-five.io> for more information and inspiration.

NodeBot Rover Component Overview



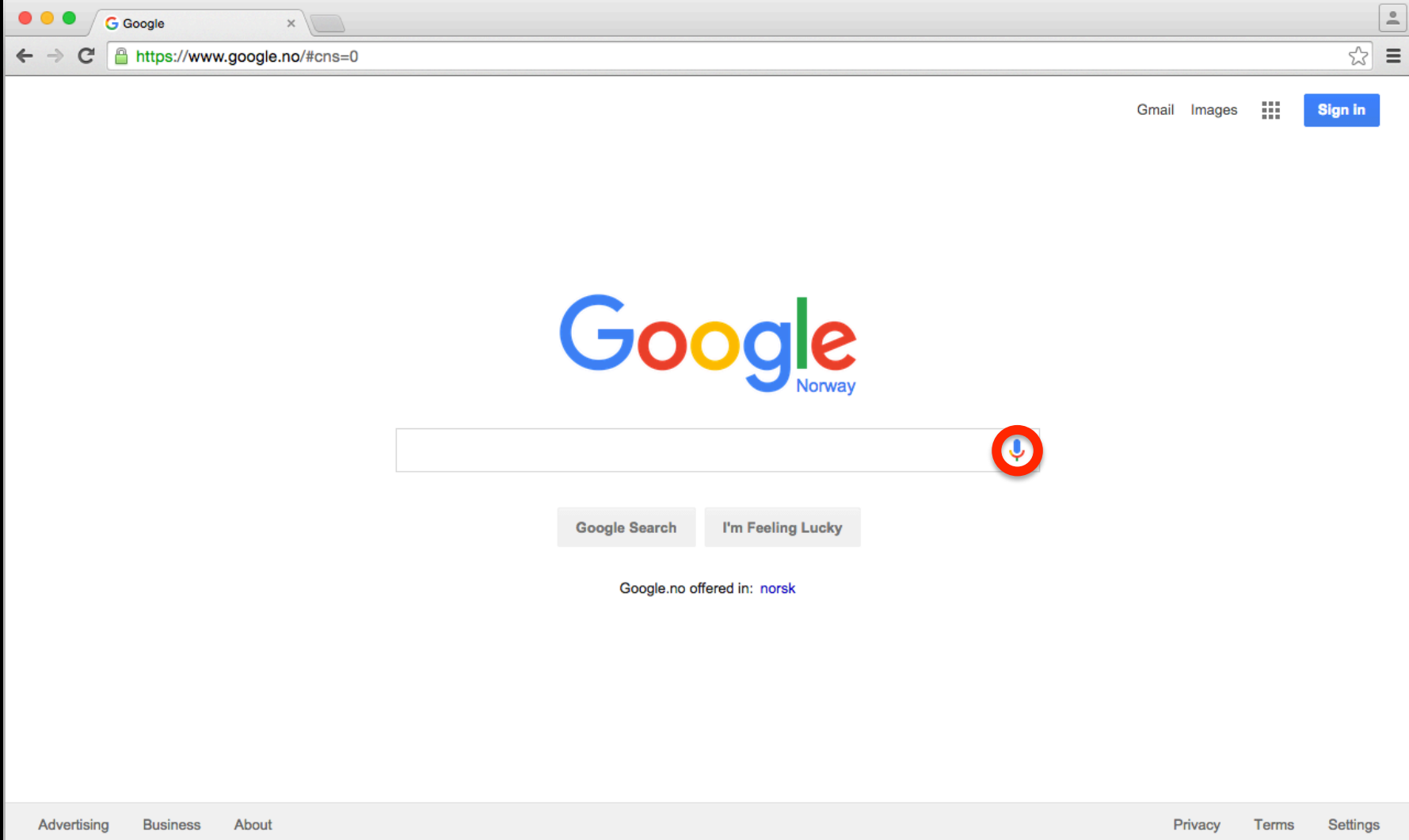
Speech Recognition Requirements

Need to have

- Quality and speed of speech recognition.
- Free, no restrictions.
- Software based.
- JavaScript.

Nice to have

- Speech to text.
- One stop service.
- Battle tested.



Google Search

I'm Feeling Lucky

Google.no offered in: [norsk](#)



Web Speech API Specification

19 October 2012

Editors:

Glen Shires, Google Inc.

Hans Wennborg, Google Inc.

Please refer to the [errata](#) for this document, which may include some normative corrections.

Copyright © 2012 the Contributors to the Web Speech API Specification, published by the [Speech API Community Group](#) under the [W3C Community Final Specification Agreement \(FSA\)](#). A human-readable [summary](#) is available.

Abstract




This specification defines a JavaScript API to enable web developers to incorporate speech recognition and synthesis into their web pages. It enables developers to use scripting to generate text-to-speech output and to use speech recognition as an input for forms, continuous dictation and control. The JavaScript API allows web pages to control activation and timing and to handle results and alternatives.

```
1 var recognition = new webkitSpeechRecognition();
2
3 // Are we performing continuous recognition or not?
4 recognition.continuous = true;
5
6 // Do we want interim results or not (true means yes)
7 recognition.interimResults = true;
8
9 // ENGLISH english, none of that colonial nonsense my good man!
10 recognition.lang = "en-GB";
11
12 // Kick off the Speech Recognition process
13 recognition.start();
14
15 // Triggered by start of Speech Recognition process
16 recognition.onstart = function() { ... }
17
18 // Triggered when results returned from Speech Recognition
19 recognition.onresult = function(event) { ... }
20
21 // Triggered by errors in the Speech Recognition process
22 recognition.onerror = function(event) { ... }
23
24 // Triggered by end of Speech Recognition process
25 recognition.onend = function() { ... }
26
27 // Force stop of the Speech Recognition process
28 recognition.stop();
```

Web Speech API

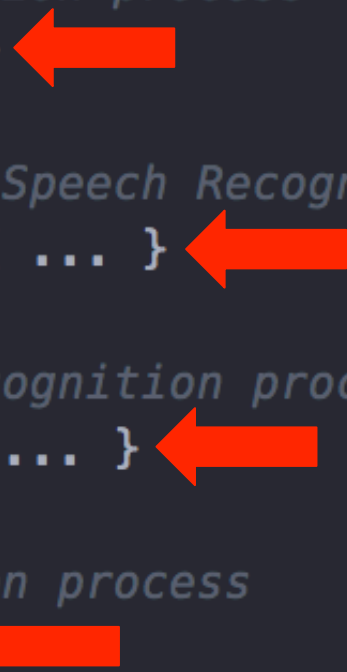
(limited to Google Chrome)

Web Speech API : Configuration

```
1  var recognition = new webkitSpeechRecognition();  
2  
3  // Are we performing continuous recognition or not?  
4  recognition.continuous = true;   
5  
6  // Do we want interim results or not (true means yes)  
7  recognition.interimResults = true;   
8  
9  // ENGLISH english, none of that colonial nonsense my good man!  
10 recognition.lang = "en-GB"; 
```


Web Speech API : Events

```
15 // Triggered by start of Speech Recognition process
16 recognition.onstart = function() { ... }
17
18 // Triggered when results returned from Speech Recognition
19 recognition.onresult = function(event) { ... }
20
21 // Triggered by errors in the Speech Recognition process
22 recognition.onerror = function(event) { ... }
23
24 // Triggered by end of Speech Recognition process
25 recognition.onend = function() { ... }
```


Four red arrows are positioned to the right of the code, each pointing left towards the assignment of an event listener. The first arrow points to line 16, the second to line 19, the third to line 22, and the fourth to line 25.

Web Speech API : Control

```
12 // Kick off the Speech Recognition process  
13 recognition.start();
```



```
27 // Force stop of the Speech Recognition process  
28 recognition.stop();
```



Speech Demo

SPEECH RECOGNITION



MARY HAD A LITTLE LAMB IS FLEECE WAS
WHITE AS SNOW AND EVERYWHERE THAT
MARY WENT THE LAMB WAS SURE TO GO
SENDING 'MARY HAD A LITTLE LAMB IS
FLEECE WAS WHITE AS SNOW AND
EVERYWHERE THAT MARY WENT THE LAMB
WAS SURE TO GO' TO ROBOT, LAST COMMAND
SENT WAS 'SURE TO GO'.

SURE TO GO

SENDING 'SURE TO GO' TO ROBOT, LAST
COMMAND SENT WAS 'MARY HAD A LITTLE
LAMB IS FLEECE WAS WHITE AS SNOW AND
EVERYWHERE THAT MARY WENT THE LAMB
WAS'.

MARY HAD A LITTLE LAMB IS FLEECE WAS
WHITE AS SNOW AND EVERYWHERE THAT
MARY WENT THE LAMB WAS

SENDING 'MARY HAD A LITTLE LAMB IS
FLEECE WAS WHITE AS SNOW AND
EVERYWHERE THAT MARY WENT THE LAMB
WAS' TO ROBOT, LAST COMMAND SENT WAS '
WAS SURE TO GO'.

WAS SURE TO GO

SENDING 'WAS SURE TO GO' TO ROBOT, LAST
COMMAND SENT WAS 'MARY HAD A LITTLE
LAMB IS FLEECE WAS WHITE AS SNOW AND
EVERYWHERE THAT MARY WENT THE LAMB'.

MARY HAD A LITTLE LAMB IS FLEECE WAS
WHITE AS SNOW AND EVERYWHERE THAT

Web Speech API : Robot

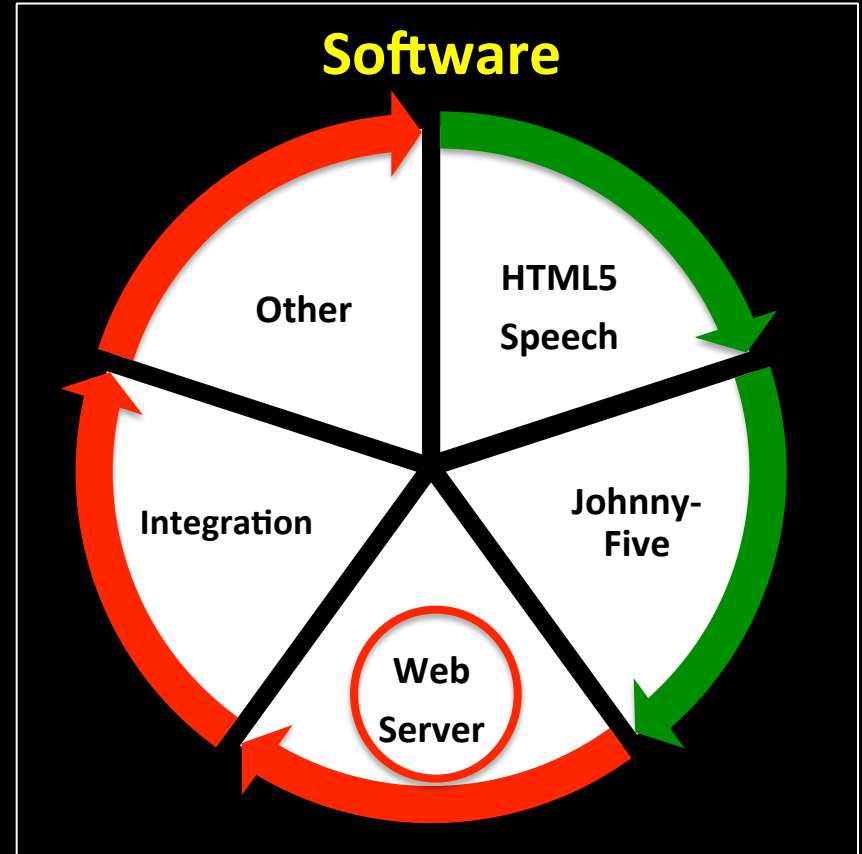
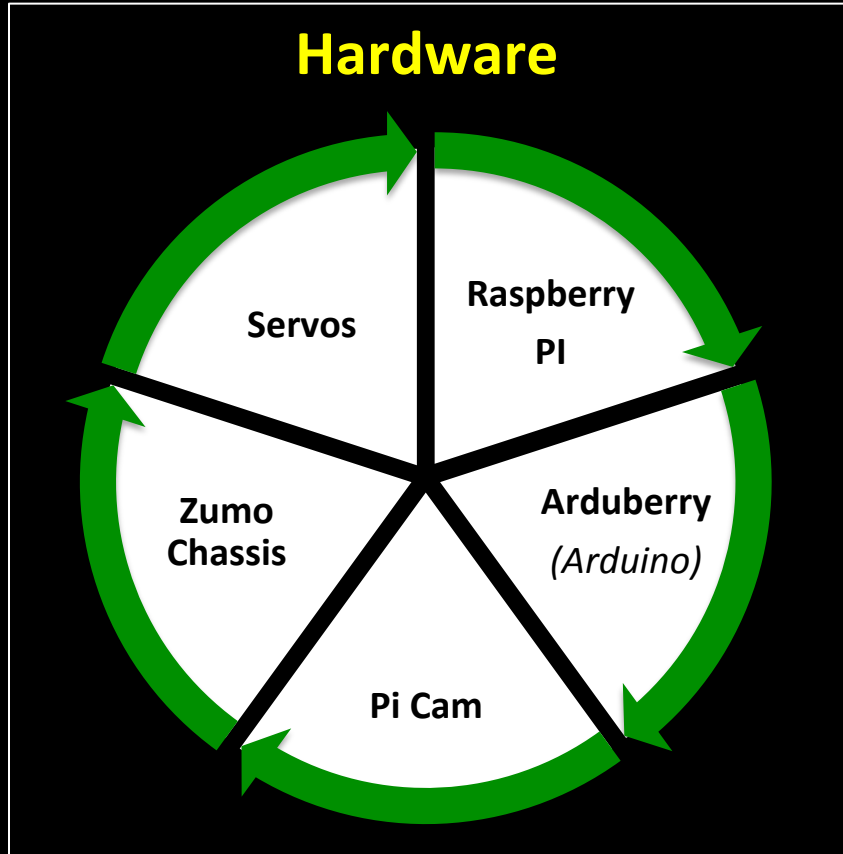
Button press and release connected to
Web Speech API *start* and *stop* Control
methods.

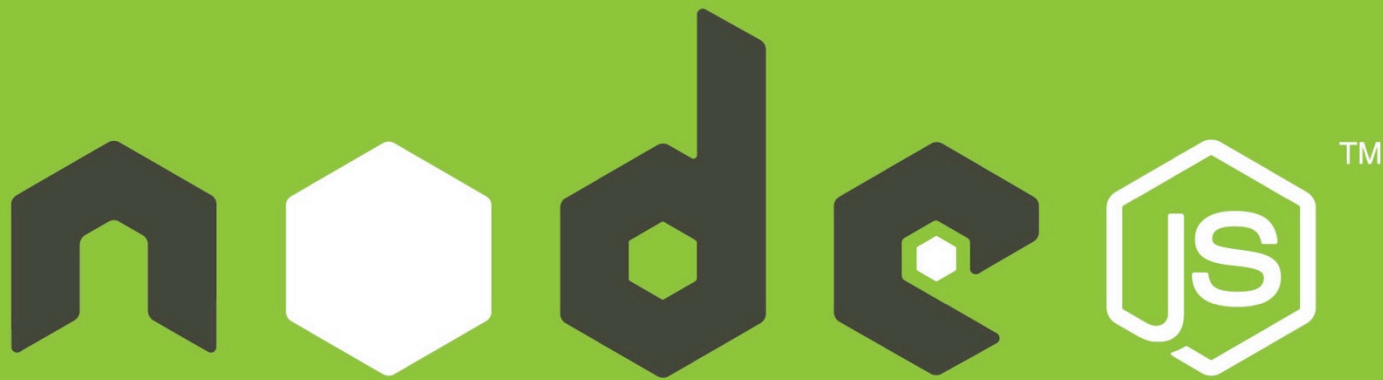
Continuous dictation switched on, to avoid
cutting commands short.

Interim results switched on – shown in
green text (final results in white).

Each set of results checked for uniqueness
to avoid sending duplicate commands to
the Robot.

NodeBot Rover Component Overview





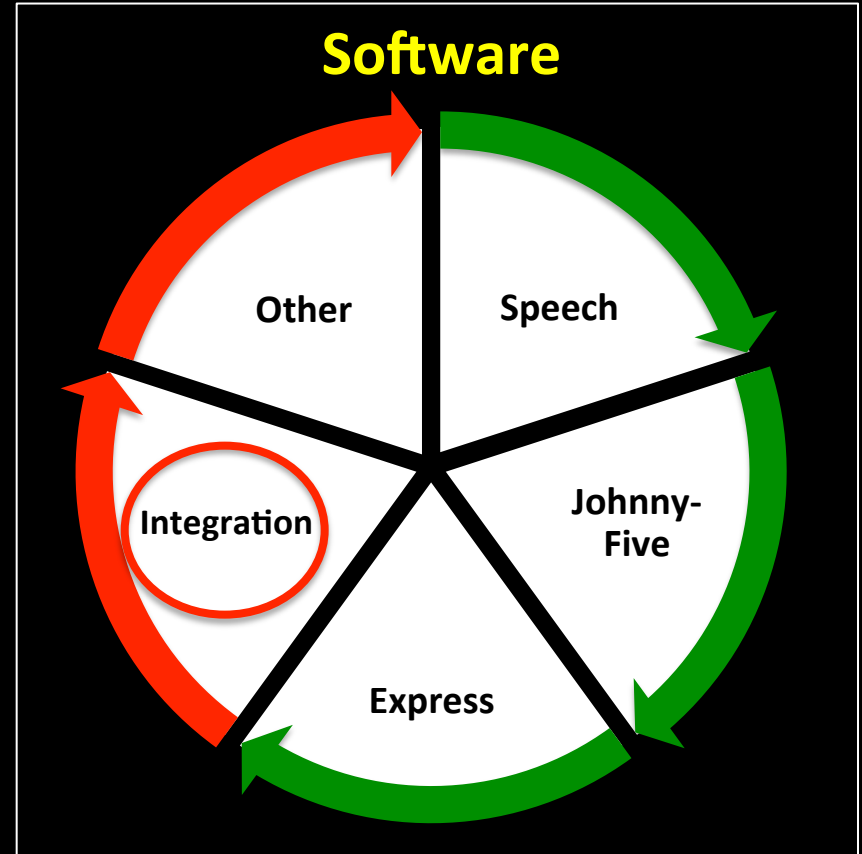
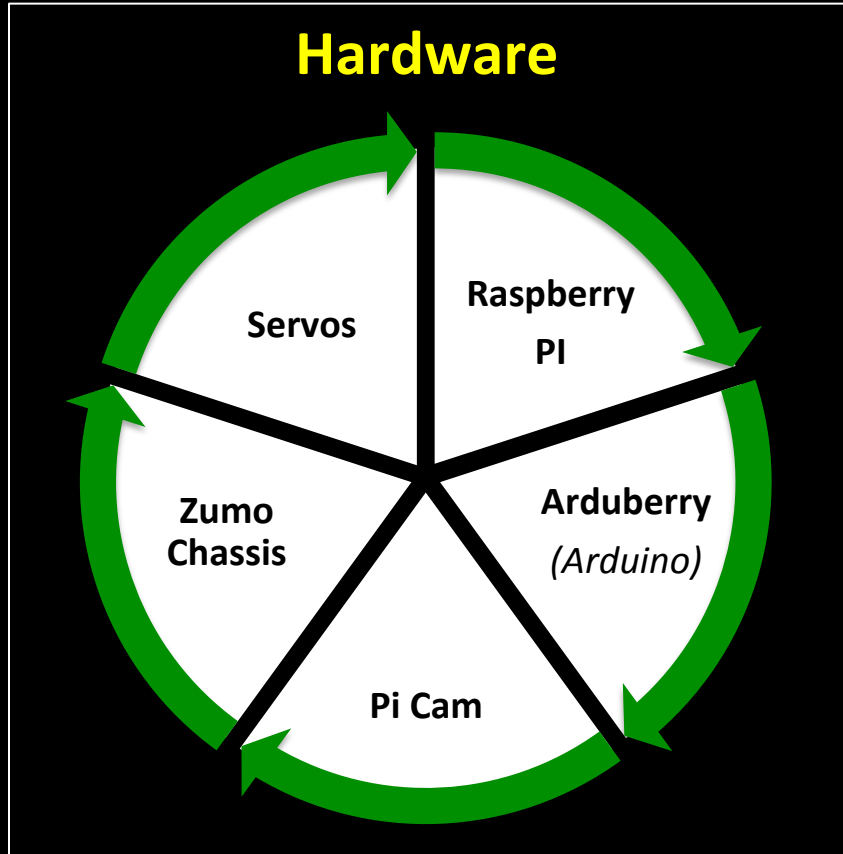
express

```
22 var express = require("express");
23 var app = express();
24 var fs = require("fs");
25 var options = {
26   key: fs.readFileSync("certificates/key.pem"),
27   cert: fs.readFileSync("certificates/cert.pem"),
28   requestCert: true
29 };
30 var server = require("https").createServer(options, app);
31
32 // Required to serve the static files (i.e. images)
33 app.use(express.static(__dirname));
34
35 // Serves up HTML page
36 app.get("/", function(req, res){
37   res.sendFile(__dirname+'/arduino_speech.html');
38 });
39
40 //HTTPS Server
41 server.listen(8080, function(){
42   console.log("HTTPS listening on *:8080");
43 });
```

Node.js Express Web Server

(17 lines of code)

NodeBot Rover Component Overview



Raspberry PI 2

HTTPS

Browser

*Express
Process*

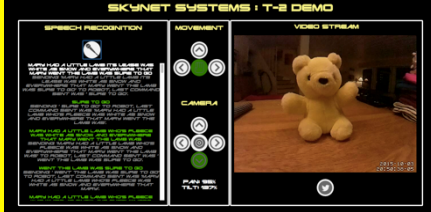


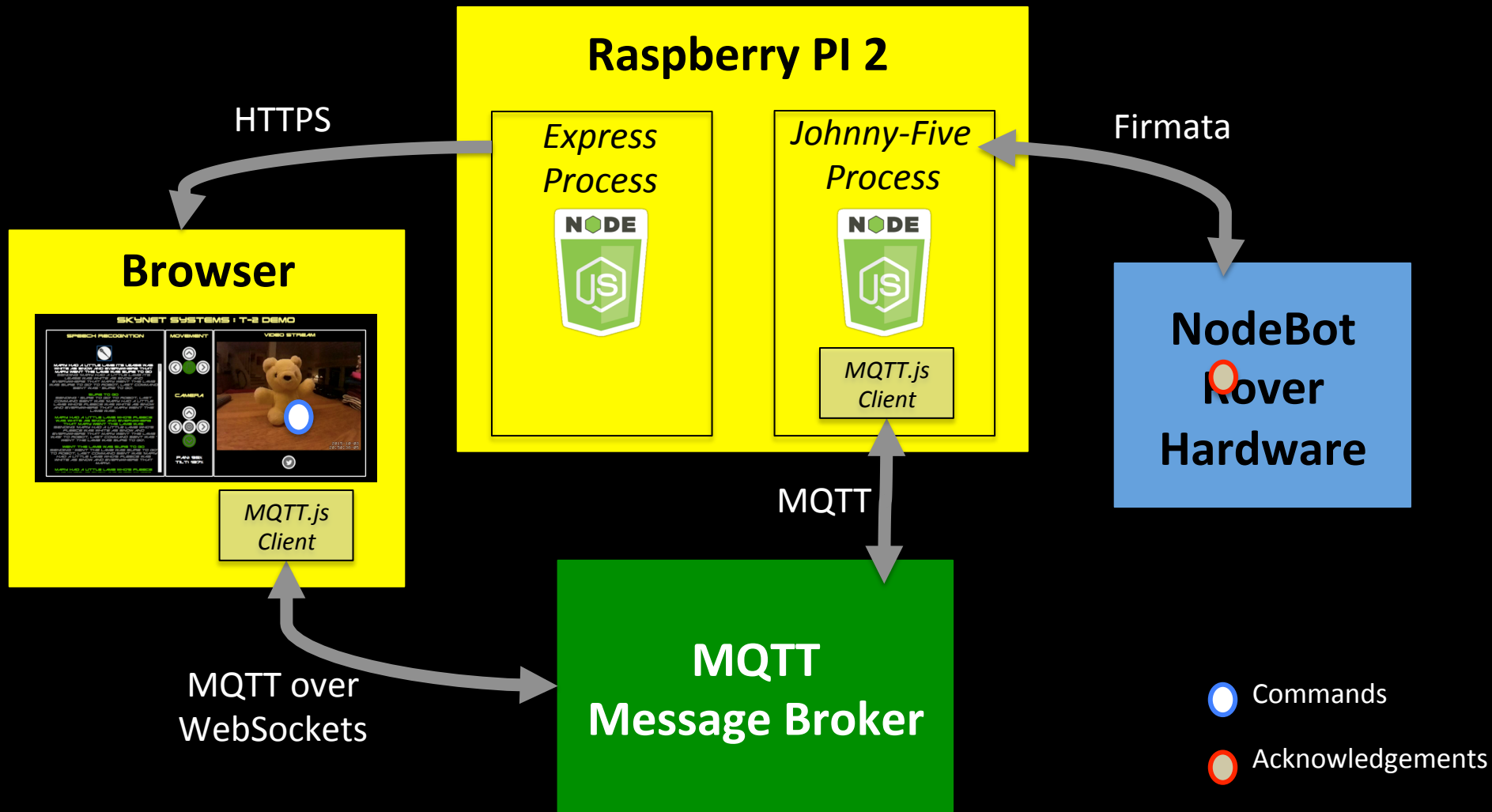
*Johnny-Five
Process*



Firmata

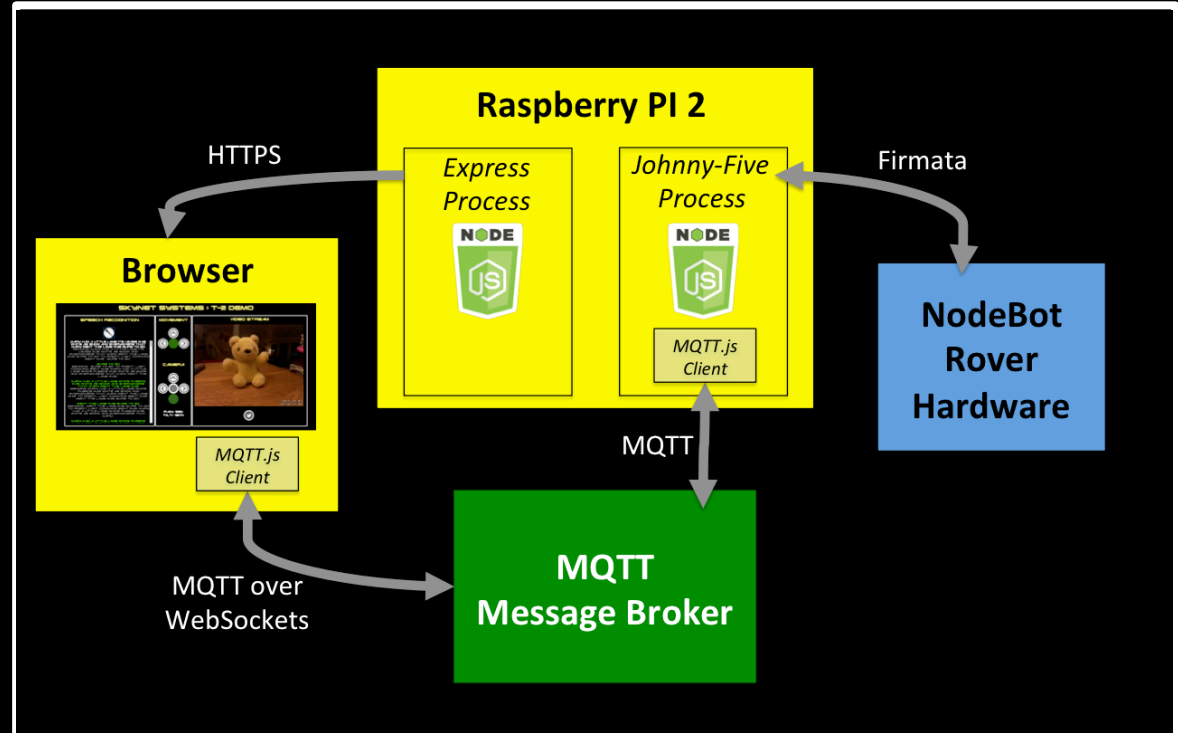
NodeBot
Rover
Hardware





Why Add a Message Broker?

- Separation of concerns.
- Isolate main components for easier testing.



MQTT – MQ Telemetry Transport

- Internet of Things connectivity protocol.
- Designed to be lightweight with a small footprint and little overhead.
- Is a protocol **and** a Pub-Sub Message Broker.
- Used by Facebook for pushing updates to mobile clients.

Adding MQTT to the NodeBot Rover

Broker

- Public MQTT Broker
 - Many Public Brokers exist.
 - One less process to run on Raspberry PI.

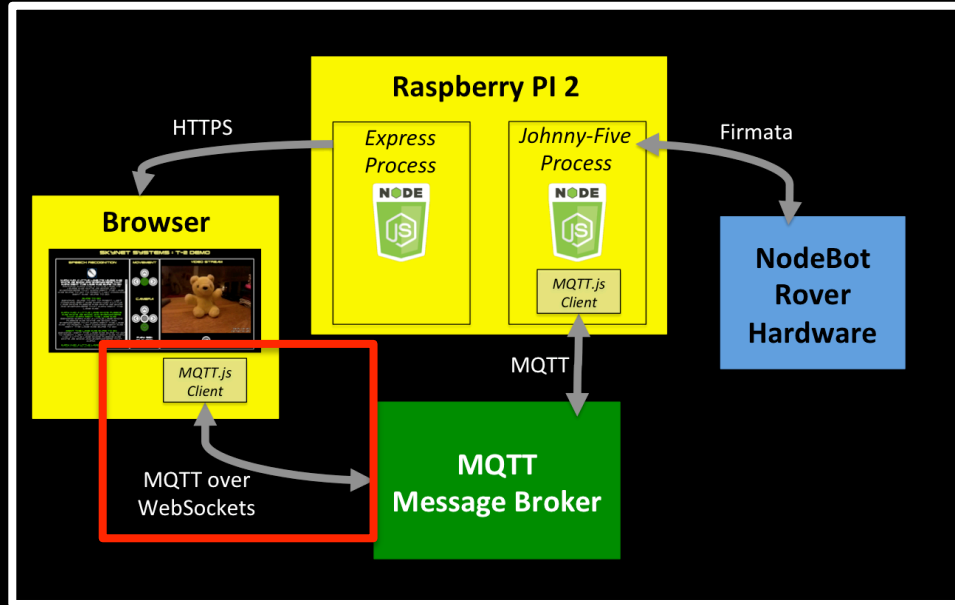
Client

- MQTT.js
 - Provides an MQTT client library for Node.js.
 - Extremely simple to use.
 - Integrates seamlessly with Johnny-Five.

MQTT.js (Node.js) Client Example

```
1 var mqtt = require('mqtt');
2 var client = mqtt.connect('mqtt://test.mosquitto.org');
3
4 client.on('connect', function () {
5   client.subscribe('presence');
6   client.publish('presence', 'Hello mqtt');
7 });
8
9 client.on('message', function (topic, message) {
10   // message is Buffer
11   console.log(message.toString());
12   client.end();
13 });
```


MQTT Over WebSockets with MQTT.js

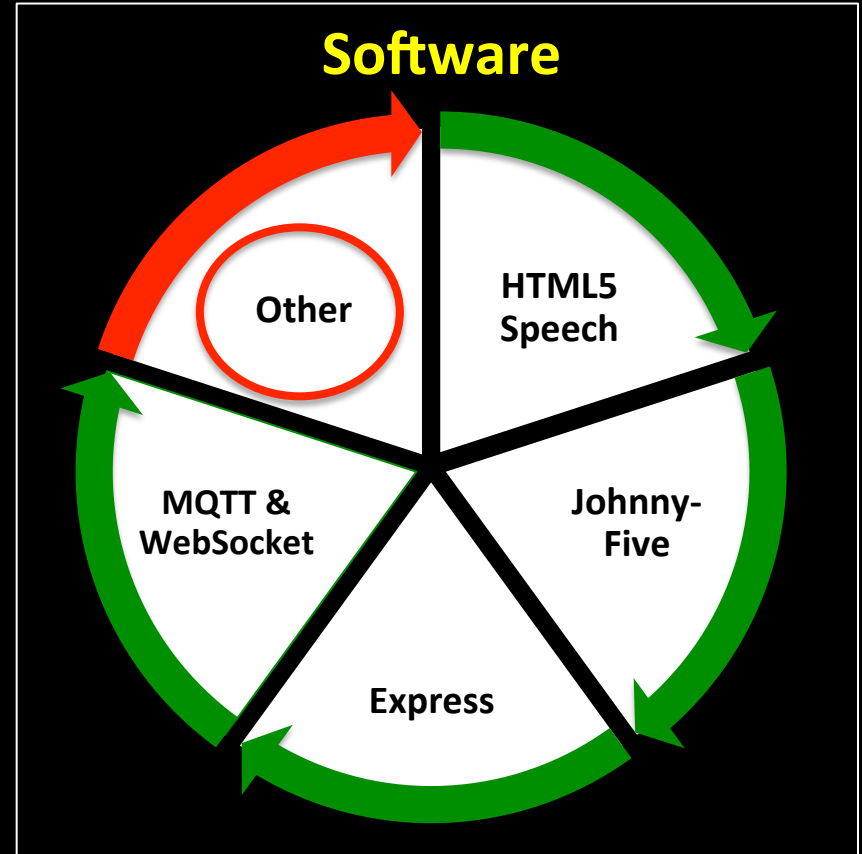
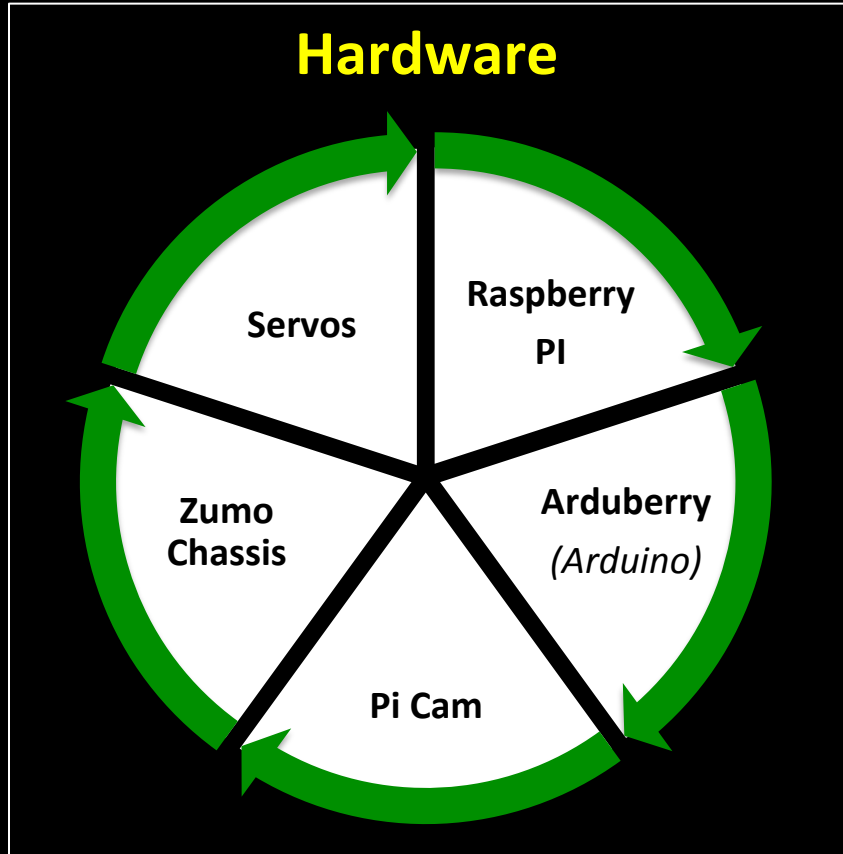


- MQTT.js is a Node.js package and is meant for use on the Server Side.
- To allow MQTT.js to run from the Browser, we first needed to "Browserify" the MQTT library.
- We could then access the "Browserified" MQTT client library from the Browser.
- This solution requires that your MQTT Broker has a WebSocket endpoint.



MQTT Over WebSockets Demo

NodeBot Rover Component Overview



Node.js Twitter Client

- Fully fledged Twitter Client:
 - Asynchronous.
 - Supports *REST API* (write and write)
 - Supports *Streaming API* (events and tweets).
- Requires developer credentials from Twitter:
 - Trivial to get hold of.

Node.js Twitter Client REST Example

```
1 var Twitter = require('twitter');
2
3 var client = new Twitter({
4   consumer_key: process.env.TWITTER_CONSUMER_KEY,
5   consumer_secret: process.env.TWITTER_CONSUMER_SECRET,
6   access_token_key: process.env.TWITTER_ACCESS_TOKEN_KEY,
7   access_token_secret: process.env.TWITTER_ACCESS_TOKEN_SECRET
8 });
9
10 client.post('statuses/update', {status: 'This is a tweet'},
11 function(error, tweet, response){
12   if (!error) {
13     console.log(tweet);
14   }
15 });
```

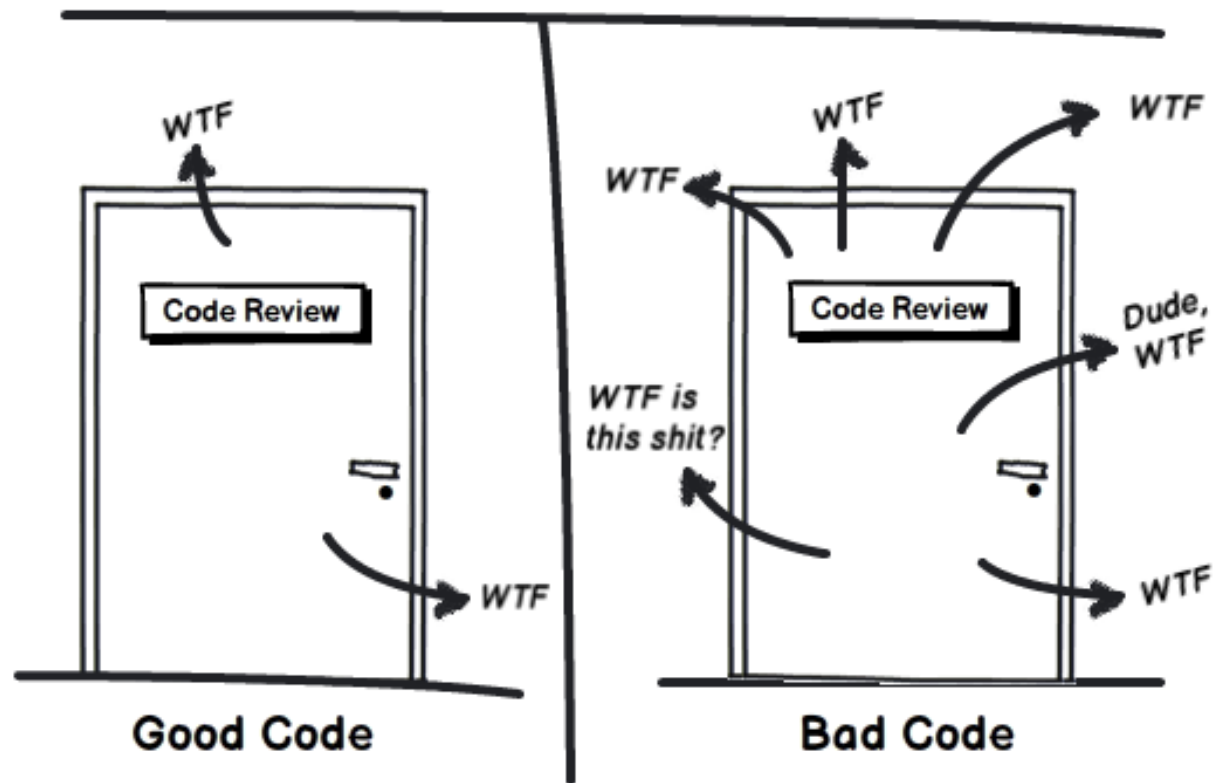
Video Streaming via Motion

- **Motion**: Software Motion Detector.
- Provides streaming video with possibility to create snapshots.
- Good performance on the Raspberry PI.
- **Potential side project**: get Robot to follow moving objects?

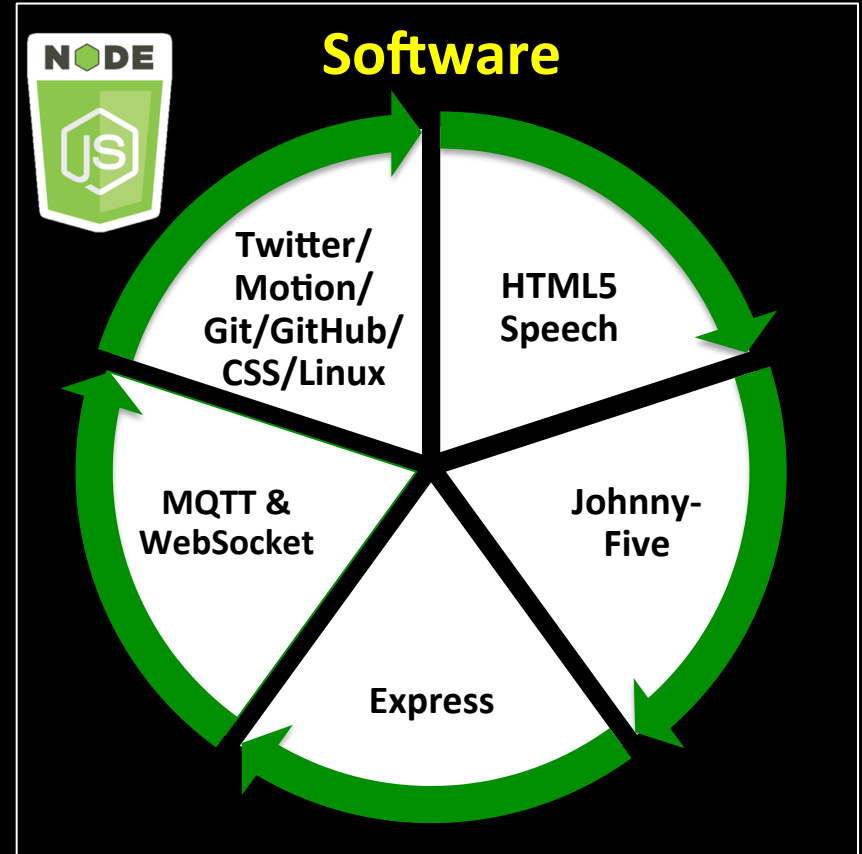
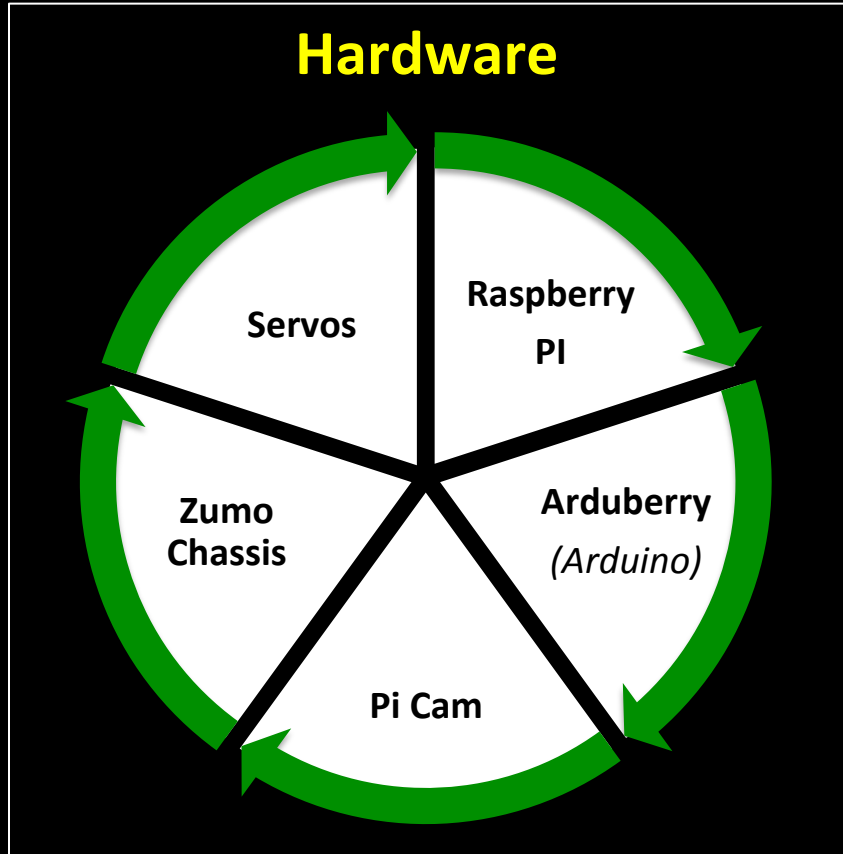
Other things I picked up

- Git / GitHub
- HTML5
- CSS
- Linux

Code Quality Measurement: WTFs/Minute



NodeBot Rover Component Overview



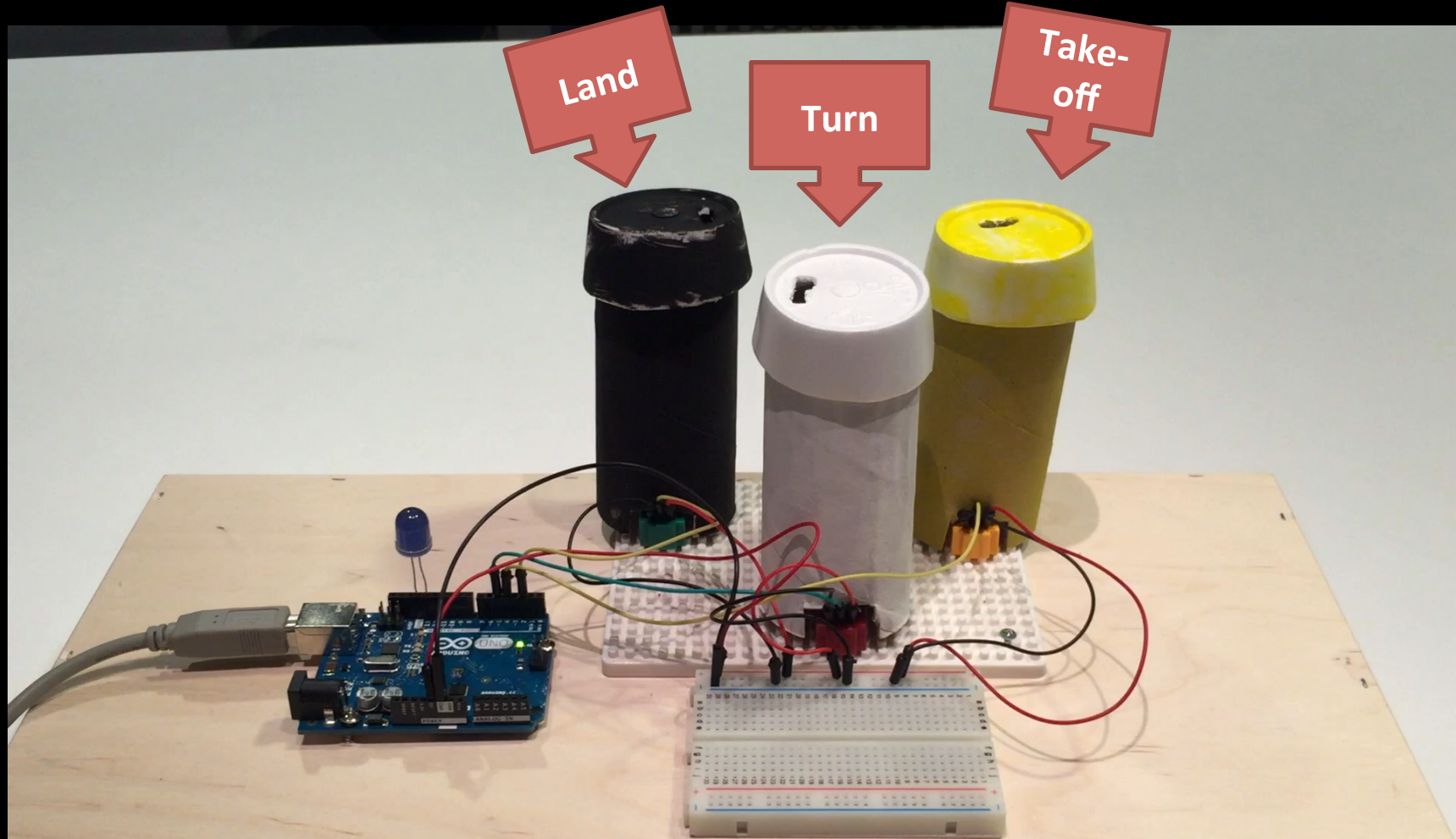
So Did I Get My
Coding Mojo
Back?



Land

Turn

Take-off







 @markawest